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# Searching for the Orthogonal States of a Neural Network 

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ABSTRACT

Two approaches to find orthogonal states of neural network are presented in the paper. The first approach is a recursive one, it builds $N$ orthogonal vectors based on $N / 2$ orthogonal vectors. The second approach is a formula approach, in which orthogonal vectors can be obtained using a formula. Using these approaches, orthogonal states of neural network are found. Some properties of the neural network built on these orthogonal vectors are presented in Appendix A and some examples are given in Appendix B.

## SEARCHING FOR ORTHOGONAL STATES OF NEURAL NETWORKS

by:

## Heng Wang

## A Thesis

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## Chapter 1

## Introduction

A neural network is a distributed information processing structure consisting of neurons interconnected by synaptic connections. The neurons can possess local memory and can carry out localized information processing operation. The function of neural networks is primarily determined by the connection topology between the neurons, the connection strengths and the type of processing formed at the computing elements. The complete system can conduct functions such as classification, optimization and associative memory.

Consider a interconnected network of $n$ neurons, the state of the system is $u$, which is a set of binary states of each neuron. In the $M-P$ model, the new state of neuron $i$ is

$$
u_{t}=\operatorname{sgn}\left(\sum_{j} w_{i j} u_{\jmath}-L\right)=\left\{\begin{array}{l}
1, \text { if } \sum w_{i j} u_{j} \geq L \\
0, \text { if } \sum w_{i j} u_{\jmath}<L
\end{array}\right.
$$

where $L$ is a threshold level, $u$ is a n-tuple vector which stands for the state of the associative memory of the network, $u_{t}$ is the state of neuron $i$ and $w_{i j}$ is the weight of the synaptic connection between neurons $i$ and $j$.

In the Hopfield-Little model [9] of associative memory, the neurons have binary states with threshold value assumed to be zero. The weight matrix of the memory can
be made of the sum of the outer product of each desired vector. That is $W_{\imath j}=\sum s_{i}^{(k)} S_{j}^{(k)}$. The network is fully connected and symmetric, on which the Hebb rule applys. Once the weights are determined, the neural network can produce the desired output. When the input vector is corrupted, partially incorrect or incomplete, it still has the ability to converge the desired one. The neural states at these minima represent the memories of the system.

Therefore, it is crucial to determine what kind of prototypes to be selected and how to construct the associative memory.

The Hebb's law and the projection rule serve as the classical solutions to provide prototype vectors or fixed points of a neural network with synaptic matrix $W$. The former solution differs from the latter in that the prototype vectors ( $V^{\prime} s$ ) in the Hebb's law must be orthogonal to each other and the synaptic matrix can be constructed as the sum of outer products of these orthogonal vectors, 1.e., the prototypes. The construction rule for the synaptic matrix is:

$$
W=\frac{1}{n}\left(V_{1} * V_{1}+\quad+V_{n} * V_{n}\right)=\frac{1}{n} \sum_{k=1}^{n} V_{k} * V_{k}=\frac{1}{n} X X^{T}
$$

where the superscript $T$ stands for transpose, $n$ is the total number of prototype vectors and '*' indicates the outer product. When they are not orthogonal to each other, the Hebb's law cannot guarantee the perfect retrieval of the prototypes.

It was mentioned in [10] that for orthogonal feature vectors, the capacity is $100 \%$ in comparison with the tradeoff between the memory capacity and the degree of faulttolerance which has been estimated to be about $15 \%$ of $B$ bits in Hopfield-Little Model [9].

In order to achieve good error recovery, it is desirable that these orthogonal prototype vectors are equally spaced apart in terms of the Hamming Distance. Further, this Hamming Distance should be as large as possible. For a $N$-neuron network, the largest Hamming Distance between any two orthogonal vectors is $N / 2$, if they are equally spaced apart. A neural network constructed from such a set of prototype vectors should demonstrate a better retrieval capability which in turn results in a network with higher memory capacity. The Hamming Distance between any two of orthogonal vectors constructed by the proposed technique is $N / 2$.

This paper presents two techniques to search for $N$ orthogonal vectors of a $N$ neuron network. Some properties of the neural network built upon these orthogonal vectors are presented in the appendix. Due to the generality of these rules, some properties exhibited by low order neural networks can be extended to the networks with large number of neurons.

## Chapter 2

## Methods to Find

## Orthogonal States of A $\mathbf{N}$-neuron Network

### 2.1 Introduction

There are various approaches to find out orthogonal vectors. One is to use those sinusoidal function and the other is to use those non-sinusoidal series. In the latter, there are some well-known functions: Walsh function, Harr function and Ramemacher function. Both Walsh function and Harr function can form a complete orthogonal set while Ramemacher function provided another set of two-level orthogonal functions which are incomplete but true subset of the Walsh function. In this paper, we present a unique recursive approach and a formula approach to find orthogonal vectors.

In the recursive approach, the $2 N$ orthogonal vectors for a $2 N$-neuron network can be constructed based on the $N$ orthogonal vectors of a $N$ neural network with $N$ neurons. The above $N$ orthogonal vectors can be constructed in a similar fashion based on the $N / 2$ orthogonal vectors of a neural network with $N / 2$ neuron, ... and this alternative has the disadvantage of the necessity of constructing for all neural networks with $\frac{N}{2^{k}}$ neurons, $\mathrm{k}=0,1,2, \ldots \log N-1$. The formula approach circumvents this drawback by calculating the $N$ components of each of the $N$ orthogonal vectors based on a formula. The resulting orthogonal vectors are identical to those constructed using
the recursive alternative.

### 2.2. Recursive Procedure

Consider a N -neuron network with $N=2^{k}$ where k is a positive integer. The following lemma is obvious.

Lemma 1: The distance between any two orthogonal neuron vectors is $N / 2$.
Proof: Let $V_{1}$ and $V_{2}$ be the two orthogonal vectors. Then $\sum_{\jmath=1,, N} v_{1 \jmath} v_{2 \jmath}=0$, which indicates that half of the components in $V_{1}$ and $V_{2}$ have different signs. Hence the distance between them is $N / 2$.

Let $V_{1}=\left[\begin{array}{llll}1 & 1 & . . & 1\end{array}\right]^{T}$. In order for $V_{2}$ to be orthogonal to $V_{1}, V_{2}$ must have equal number $\left(\frac{N}{2}\right)$ of 1 's and -1 's. Choose those $V_{2}$ 's as

$$
V_{2}=\left[\begin{array}{llllllllll}
-1 & -1 & -1 & \ldots & -1 & 1 & 1 & 1 & \ldots & 1
\end{array}\right]^{T}
$$

or

$$
V_{2}=-\left[\begin{array}{llllllllll}
-1 & -1 & -1 & \ldots & -1 & 1 & 1 & 1 & \ldots & 1
\end{array}\right]^{T}
$$

It is easy to see that $V_{1} V_{2}=0$. Notice that the two $V_{2}$ 's are not orthogonal to each other and there are two blocks in $V_{2}$ : one with all 1's (denoted by the + block) and the other with all -1 's (denoted by the - block).

To find $V_{3}$, we divide each block of $V_{2}$ into one + block and one - block. Since there are two blocks in $V_{2}$, there are four possible $V_{3}$ 's,

$$
V_{3}=\left[\begin{array}{llllllllllllll}
1 & 1 & \ldots & 1 & -1 & -1 & . . & -1 & 1 & 1 & \ldots & 1 & -1 & -1
\end{array},-1\right] T=[+-+-] T,
$$

or
or

$$
V_{3}=-\left[\begin{array}{llllllllllllll}
1 & 1 & \ldots & 1 & -1 & -1 & \ldots & -1 & 1 & 1 & \ldots & 1 & -1 & -1
\end{array} \ldots-1\right]^{T}=[-+-+]^{T},
$$

or

$$
\left.V_{3}=-\left[\begin{array}{lllllllllllllll}
1 & 1 & \ldots & 1 & -1 & -1 & . . & -1 & -1 & -1 & \ldots & -1 & 1 & 1 & \ldots
\end{array}\right) .1\right]^{T}=[-++-] T
$$

We call the above vectors with ' $+/$ ' components $+/$ equivalent vectors. To evaluate the inner product between two +/- equivalent vectors, we substitute ' 1 ' for ' + ' and ' -1 ' for ' '-'. The following theorem states that one can test whether two vectors are orthogonal to each other using the $+/$ equivalent vectors.

Theorem 2.1: If $V_{t}$ and $V_{J}$ have identical number of blocks, each block has identical number of components, and $V_{l} V_{J}=0$, then $V_{l}^{e} V_{J}^{e}=0$, where $V_{t}^{e}$ and $V_{J}^{e}$ are the $+/$ equivalent vectors of $V_{i}$ and $V_{1}$.

Proof: This theorem follows from that fact that the inner product between any two blocks has the same magnitude.

It is easy to see that all these four possible $V_{3}$ 's are orthogonal to both $V_{1}$ and $V_{2}$. Notice that these four $V_{3}$ 's are not orthogonal to each other. Pick as many as possible so that they are orthogonal to each other. Theorem 2.1 helps because it is easier to test the orthogonality between $+/$ equivalent vectors whose dimensions are reduced by a factor of k . Thus, we search the four $+/$ - vectors of $V_{3}$ for the largest set of orthogonal vectors. A further transformation is possible on these +/- vectors by
replacing each block of " + -" with ' 1 ' and " -+ " with ' -1 '. The resulting vectors are: $[11]^{T},[1-1]^{T},[-11]^{T},[-1-1]^{T}$, which is complete in the sense that $1 t$ includes all vectors of dimension 2 whose components are 1 or -1 . Thus there are two orthogonal vectors out of these four vectors.

Select $V_{3}^{e}=[+-+-]^{T}$ and $V_{4}^{e}=[+--+]^{T}$ which are orthogonal to each other. Correspondingly $V_{3}=\left[\begin{array}{llllllllllllll}1 & 1 & . & 1 & -1 & -1 & \ldots & -1 & 1 & 1 & . & 1 & -1 & -1\end{array}-1\right]^{T}$ and $\left.V_{4}=\left[\begin{array}{lllllllllllll}1 & 1 & \ldots & 1 & -1 & -1 & \ldots & -1 & -1 & -1 & \ldots & -1 & 1\end{array} 1 \ldots .1\right]\right]^{T}$.

So far, we have generated four orthogonal vectors: one at each of the first two steps and two at the third step. In the next step, divide, as before, each of the four blocks of $V_{4}$ or $V_{3}$ into two subblocks which can be "+-" or "-+". Since each block has two possible divisions, there are $2^{4}$ combinations. Although these vectors are orthogonal to the four vectors previously found, they are not orthogonal to each other. Again select as many orthogonal vectors as possible. These $2^{4}$ vectors form a complete set of vectors of dimension 4. Hence there are 4 orthogonal vectors in this step. We can recursively perform this division to acquire new orthogonal vectors until the block consists of only one component. By induction, we have the following lemma.

Lemma: For all i, $V_{\imath+1}$ has equal number of " + "s and "-"s,

Lemma: There are $2^{n}$ subblocks after the $n-t h$ step and there are $2^{2^{n-1}}$ possible vectors.
and we have $1+\sum_{k=0}^{n-1} 2^{k}=2^{n}$.

For each block, there are two possible divisions: $\left[\begin{array}{c}+ \\ -\end{array}\right]$ or $\left[\begin{array}{c}- \\ +\end{array}\right]$. Denote $\left[\begin{array}{c}+ \\ -\end{array}\right]$ as 1 and $\left[\begin{array}{c}- \\ +\end{array}\right]$ as -1 . For $n$ blocks, there are thus $2^{n}$ possible combinations of divisions.

For instance,

$$
V_{a}=\left[\begin{array}{c}
1 \\
-1 \\
1 \\
-1
\end{array}\right] \rightarrow V_{a}^{\prime}=\left[\begin{array}{l}
1 \\
1
\end{array}\right]
$$

and

$$
V_{b}=\left[\begin{array}{c}
1 \\
-1 \\
-1 \\
1
\end{array}\right] \rightarrow V_{b}^{\prime}=\left[\begin{array}{c}
1 \\
-1
\end{array}\right]
$$

It is easy to see that $V_{a} \cdot V_{b}=V_{a} \cdot V_{b}^{\prime}=0$. This is true for the general case as stated in the following lemma:

Lemma: Let $V_{a}, V_{b}$ be two generated vectors and $V_{a}^{\prime}, V_{b}^{\prime}$ the corresponding vectors by the substitution of $\left[\begin{array}{c}+ \\ -\end{array}\right] \rightarrow(1)$, and $\left[\begin{array}{c}- \\ +\end{array}\right] \rightarrow(-1]$, then $V_{a} V_{b}=0$, iff $V_{a}^{\prime} \cdot V_{b}^{\prime}=0$.

Theorem 2.2: Let $V_{l}$ be any one orthogonal vector generated earlier, $V_{j}$ a vector among all the $2^{2^{k-1}}$ at the $k$-th step, then $V_{l} V_{\jmath}=0$.
Proof: Let $V_{l}=\left[\begin{array}{llll}v_{l 1} & v_{l 2} & \ldots & v_{t k}\end{array}\right]^{T}$ where $v_{l 1}$ is the first block where components are all " 1 "s or all " -1 "s, $v_{12}$ is the second such component, and so on. Let $V_{j}=\left[v_{j 1} v_{j 2} \ldots v_{j k}\right]^{T}$ where $v_{j 1}$ corresponds to $v_{l 1}, v_{j 2}$ to $v_{l 2}$, and so on.

By the nature of the procedure, there are equal number of " 1 "s and " -1 "s in each $v_{j e}, e=1, \ldots, k$. Thus, for all $e \in[1,2, \ldots, k], v_{t e} v_{j e}=0$, which in turn leads to $V_{l} V_{J}=0$.

Theorem 2.3: The number of division steps to obtan $N$ orthogonal vectors is $P=\log N$.

Note that after the $k-t h$ step, the total number of vectors generated from step 0 to step $k$ is $2^{k}$ and the corresponding total number of orthogonal vectors is $k$. At the $(k+1)$ th step, there are $2^{k}$ blocks. With the substitutions of 1 for $\left[\begin{array}{l}+ \\ -\end{array}\right]$ and -1 for $\left[\begin{array}{l}- \\ +\end{array}\right]$, these $2^{k}$ blocks forms a complete $k$-dimension vector space, denoted as $S_{1}$. Note the total vectors generated from step 0 to $k$ also forms a $k$-dimension space, denoted as $S_{2}$. Thus, the $k$ orthogonal vectors for $S_{1}$ can be found in a similar way to those in $S_{2}$.

### 2.3 Formula Approach

Another recursive procedure is to construct the $N$ orthogonal vectors based on the $N / 2$ orthogonal vectors for a $N / 2$-neuron network. The first $N / 2$ orthogonal vectors of a $N$-neuron network are constructed in the same manner to that for a $N / 2$-neuron network except that the $N$ components of each of these $N / 2$ orthogonal vectors can be decomposed into $N / 2$ blocks of $\left[\begin{array}{l}1 \\ 1\end{array}\right]$ or $\left[\begin{array}{l}-1 \\ -1\end{array}\right]$. With the substitutions of 1 for $\left[\begin{array}{l}1 \\ 1\end{array}\right]$ and -1 for $\left[\begin{array}{l}-1 \\ -1\end{array}\right]$, these first $N / 2$ orthogonal vectors become the $N / 2$ orthogonal vectors for
a $N / 2$-neuron network. Applying the division procedure to $\left[\begin{array}{l}1 \\ 1\end{array}\right]$ and $\left[\begin{array}{l}-1 \\ -1\end{array}\right]$, they become $\left[\begin{array}{c}1 \\ -1\end{array}\right]$ and $\left[\begin{array}{c}-1 \\ 1\end{array}\right]$ respectively. Consider $\left[\begin{array}{c}1 \\ -1\end{array}\right]$ as 1 and $\left[\begin{array}{c}-1 \\ 1\end{array}\right]$ as -1 , the last $N / 2$ orthogonal vectors can be constructed in exactly the same manner as that for a $N / 2$-neuron network and it is obvious that the resulting vectors are orthogonal to each other.

Therefore, the above algorithm of constructing $N$ orthogonal vectors based on $N / 2$ orthogonal vectors is concluded as follows:

1) For the first $N / 2$ vectors of $N$-neuron network, substitute $\left[\begin{array}{l}1 \\ 1\end{array}\right]$ for 1 and $\left[\begin{array}{l}-1 \\ -1\end{array}\right]$ for -1 in the $N / 2$ vectors of $N / 2$-neuron network.
2) For the second $N / 2$ vectors of $N$-neuron network, substitute $\left[\begin{array}{c}1 \\ -1\end{array}\right]$ for 1 and $\left[\begin{array}{c}-1 \\ 1\end{array}\right]$ for -1 in the $N / 2$ vectors of $N / 2$-neuron network.

The following theorem presents a formula approach and the resulting vectors are proved to be orthogonal each other by using the above algorithm.

Theorem 2.4: Suppose $N=2^{k}, k$ is an integer constant, vectors $V_{l}$ and component $v_{i j}$, where $i, j \in\{0,1, \ldots, N-1\}$. Suppose $i=\sum_{m=0}^{k-1} i_{m} * 2^{m}, i_{m} \in\{0,1\}$, that is binary representation of $i$ in binary digits $i_{m}$. Then the $j$ th component of vector $V_{i}$ is

$$
v_{i j}=\left\{\begin{array}{l}
+1, \text { if } \sum_{m=0}^{k-1} i_{m}\left(\left\lfloor j \frac{2^{m+1}}{N}\right\rfloor \bmod 2\right) \text { is even }  \tag{2.1}\\
-1, \text { if } \sum_{m=0}^{k-1} i_{m}\left(\left\lfloor j \frac{2^{m+1}}{N}\right\rfloor \bmod 2\right) \text { is odd }
\end{array}\right.
$$

In expression

$$
\begin{equation*}
\sum_{m=0}^{k-1} i_{m}\left(\left\lfloor j \frac{2^{m+1}}{N}\right\rfloor \bmod 2\right) \tag{2.2}
\end{equation*}
$$

the notation $\lfloor x\rfloor$ stands for the integer part of the number $x$.
Proof:

It can be proved by induction. - It is easy to see that the theorem holds for $N=2$.

When $k=1, N=2=2^{1}$, we have $i, j \in\{0,1\}$.
When $i=0, i_{0}=i_{1}=0$, from (2.1)
we have $v_{00}=1, v_{01}=1$.
When $i=1, i_{0}=1$ and $\iota_{1}=0$, from (2.1)
we have $v_{10}=1, v_{11}=-1$.
Therefore, $V_{0}=\left[\begin{array}{l}1 \\ 1\end{array}\right]$ and $V_{1}=\left[\begin{array}{c}1 \\ -1\end{array}\right]$ and they are orthogonal each other.
Assuming the theorem holds for $N=2^{p}$, that is, from the formula (2.1) and $\sum_{m=0}^{p-1} i_{m}\left(\left\lfloor j \frac{2^{m+1}}{N}\right\rfloor \bmod 2\right)$, we can obtain those $N$ orthogonal vectors, which are the same as those generated from the above algorithm.

Now we need to prove that the theorem also holds for $N^{\prime}=2^{(p+1)}=2 N$ and generates $2 N$ orthogonal vectors which have $2 N$ components each. Let

$$
\begin{equation*}
X=\sum_{m=0}^{p-1} i_{m}\left(\left\lfloor j \frac{2^{m+1}}{N}\right\rfloor \bmod 2\right) \tag{2.3}
\end{equation*}
$$

Let's consider $\sum_{m=0}^{p} i_{m}\left(\left\lfloor j^{\prime} \frac{2^{m+1}}{N^{\prime}}\right\rfloor \bmod 2\right), j^{\prime} \in\{0,1, \ldots, 2 N-1\}$, the dimension of the vectors is expanded by 2 , also the total number of orthogonal vectors generated will doubled. We denote the first half of the $2^{(p+1)}$ orthogonal vectors $S_{1}$ and the second half $S_{2}$. The most significant bit of the binary representation of $S_{1}$ is 0 . Since in (2.2), the $m$ is ranging from 0 to $p$ instead of ranging from 0 to $p-1$. The binary representation of $i$ has one more bit $i_{p}$ and for those $i<N$, its $i_{p}$ is 0 while for those $N \leq i<2 N, i_{p}$ is 1.

In $S_{1}$, the set of the first half, $l_{p}=0$. So we have

$$
\begin{equation*}
\sum_{m=0}^{p} i_{m}\left(\left\lfloor j^{\prime} \frac{2^{m+1}}{N^{\prime}}\right\rfloor \bmod 2\right)=\sum_{m=0}^{p-1} i_{m}\left(\left\lfloor j^{\prime} \frac{2^{m+1}}{2 N}\right\rfloor \bmod 2\right) \tag{2.4}
\end{equation*}
$$

where $0 \leq j^{\prime}<2^{p+1}$. And for all components of $V^{\prime}{ }^{\prime}$, we can use $2 j$ and $2 j+1(j \in$ $\{0,1, \ldots, N-1\}$ ) instead of $j^{\prime}$ in the space of $j^{\prime} \in\{0,1, \ldots, 2 N-1\}$. The equation of (2.4) can be separated into the following (2.4.1) and (2.4.2).

$$
\begin{equation*}
\sum_{m=0}^{p-1} i_{m}\left(\left\lfloor 2 j \frac{2^{m+1}}{2 N}\right\rfloor \bmod 2\right)=\sum_{m=0}^{p-1} i_{m}\left(\left\lfloor j \frac{2^{m+1}}{N}\right\rfloor \bmod 2\right)=X \tag{2.4.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\sum_{m=0}^{p-1} i_{m}\left(\left\lfloor(2 j+1) \frac{2^{m+1}}{2 N}\right\rfloor \bmod 2\right)=\sum_{m=0}^{p-1} i_{m}\left(\left\lfloor\left(j+\frac{1}{2}\right) \frac{2^{m+1}}{N}\right\rfloor \bmod 2\right) \tag{2.4.2}
\end{equation*}
$$

Since $0 \leq m<p$, we have $2 \leq 2^{m+1} \leq 2^{p}$, dividing all the the three expression in this inequality, we obtain

$$
\frac{1}{2^{p-1}} \leq \frac{2^{m+1}}{2^{p}} \leq 1 .
$$

and the value of $\frac{2^{m+1}}{2^{p}}$ can be $\left\{1, \frac{1}{2}, \frac{1}{4}, \cdot \frac{1}{2^{p-1}}\right\}$. Therefore the value of $\frac{1}{2} \frac{2^{m+1}}{2^{p}}$ can be $\left\{\frac{1}{2}, \frac{1}{4}, \quad \frac{1}{2^{p}}\right\}$.

Then we have $\left\lfloor\left(j+\frac{1}{2}\right) \frac{2^{m+1}}{2^{p}}\right\rfloor=\left\lfloor j \frac{2^{m+1}}{2^{p}}+\frac{1}{2} \frac{2^{m+1}}{2^{p}}\right\rfloor=\left\lfloor j \frac{2^{m+1}}{2^{p}}\right\rfloor$, and $j$ is integer. $\left\lfloor\left(j+\frac{1}{2}\right) \frac{2^{m+1}}{2^{p}}\right\rfloor \bmod 2=\left\lfloor\frac{2^{m+1}}{2^{p}}\right\rfloor \bmod 2$.

From (2.4.2), we have

$$
\begin{equation*}
\sum_{m=0}^{p-1} i_{m}\left(\left\lfloor(2 j+1) \frac{2^{m+1}}{2 N}\right\rfloor \bmod 2\right)=\sum_{m=0}^{p-1} i_{m}\left(\left\lfloor j \frac{2^{m+1}}{N}\right\rfloor \bmod 2\right) \tag{2.4.3}
\end{equation*}
$$

Therefore, in the first half of the vectors, when $j^{\prime}=2 j$ or $J^{\prime}=2 j+1$, from equation (2.4.1) and (2.4.3),

$$
\sum_{m=0}^{p} i_{m}\left(\left\lfloor j^{\prime} \frac{2^{m+1}}{N^{\prime}}\right\rfloor \bmod 2\right)=\sum_{m=0}^{p-1} i_{m}\left(\left\lfloor j \frac{2^{m+1}}{N}\right\rfloor \bmod 2\right)
$$

Frome (2.1), we have $V_{\iota(2 \jmath)^{\prime}}=V_{t(2 \jmath+1)^{\prime}}=V_{\imath \jmath}$, that is the substitutions of $\left[\begin{array}{l}1 \\ 1\end{array}\right]$ for 1 and $\left[\begin{array}{l}-1 \\ -1\end{array}\right]$ for -1 in the assumed $N$ orthogonal vectors.

In $S_{2}$, the set of the second half, $i_{p}=1$. One more item is added to $S_{1}$.

$$
\begin{gathered}
\sum_{m=0}^{p} i_{m}\left(\left\lfloor j^{\prime} \frac{2^{m+1}}{N^{\prime}}\right\rfloor \bmod 2\right) \\
=\sum_{m=0}^{p-1} i_{m}\left(\left\lfloor j^{\prime} \frac{2^{m+1}}{2 N}\right\rfloor \bmod 2\right)+\left\lfloor j^{\prime} \frac{2^{p+1}}{2^{p+1}}\right\rfloor \bmod 2=X+j^{\prime} \bmod 2
\end{gathered}
$$

Again this can be separated into the following (2.5.1) and (2.5.2).

$$
\begin{gather*}
\sum_{m=0}^{p-1} i_{m}\left(\left\lfloor 2 j \frac{2^{m+1}}{2 N}\right\rfloor \bmod 2\right)+(2 j) \bmod 2 \\
\quad=\sum_{m=0}^{p-1} i_{m}\left(\left\lfloor J \frac{2^{m+1}}{N}\right\rfloor \bmod 2\right)=X \tag{2.5.1}
\end{gather*}
$$

and

$$
\begin{gather*}
\sum_{m=0}^{p-1} i_{m}\left(\left\lfloor(2 J+1) \frac{2^{m+1}}{2 N}\right\rfloor \bmod 2\right)+(2 j+1) \bmod 2  \tag{2.5.2}\\
=\sum_{m=0}^{p-1} i_{m}\left(\left\lfloor j \frac{2^{m+1}}{N}\right\rfloor \bmod 2\right)+1=X+1
\end{gather*}
$$

In the last situation (2.5.2), those odd in formula (2.1) will change into even and even will change into odd. $V_{i(2 \jmath)}^{\prime}=V_{l j}$ while $V_{l(2 \jmath+1)}{ }^{\prime}=-V_{i \jmath}$, that is the substitutions of $\left[\begin{array}{c}1 \\ -1\end{array}\right]$ for 1 and $\left[\begin{array}{c}-1 \\ 1\end{array}\right]$ for -1 in the assumed $N$ orthogonal vectors.

We can see that the way we proof the result above is exactly the procedure of producing the orthogonal vectors in the algorithm described at the beginnng the section. $2 N$ orthogonal vectors can be constructed based on $N$ orthogonal vectors with the dimension expanded by 2 .

From this procedure, we can see that the set of resulting $2 N$ orthogonal vectors is constructed from the $N$ orthogonal vectors and the number of components is doubled. For each $V_{1}$ in $S_{1}$ there is a $V_{2}$ in $S_{2}$ such that $i\left(s_{2}\right)=i\left(s_{1}\right)+2^{p}$ and $V_{2}=T\left[V_{1}\right]$, where $T$ stands for the substitutions of $\left[\begin{array}{l}1 \\ 1\end{array}\right]$ by $\left[\begin{array}{c}1 \\ -1\end{array}\right]$ and $\left[\begin{array}{c}-1 \\ -1\end{array}\right]$ by $\left[\begin{array}{c}-1 \\ 1\end{array}\right]$. And $V_{1}$ is constructed by substitution of $\left[\begin{array}{l}1 \\ 1\end{array}\right]$ for 1 and by substitution of $\left[\begin{array}{l}-1 \\ -1\end{array}\right]$ for -1 in the $N$
components' vector. Note that $V_{1}$ and $V_{2}$ differ in the even components.

The following helps to explain the above theorem. From the following table, we can understand the formula constructing rule.

For example:

| Index | Orthogonal Vector | Binary Vector |
| :---: | :---: | :---: |
| 00 | $1 \quad 1 \quad 1 \quad 1$ | 0000 |
| 01 | $1-1-1-1$ | 0011 |
| 10 | $1-1 \quad 1-1$ | 0101 |
| 11 | $1-1-1 \quad 1$ | 0110 |

Denote Base Vectors as those vectors (orthogonal or index or binary) whose Index Vector has one and only one component of 1 . With the substitutions of -1 by 1 and 1 by 0, an Orthogonal Vector in the second column becomes a Binary Vector in the third column, linear combinations of base vectors in the above table generate nonbase vectors.

For instance, the Index Vector 0011 is composed of Base Vectors 0001 and 0010. That is, $0011=0001+0010$. And the corresponding Binary Vectors of Index Vectors 0001 and 0010 are 0011 and 0101. And addition rules are:
$1+1=0,1+0=0+1=1$, and $0+0=0$.
Note that there are no carries in the above additions.
Add the two Binary Vectors, we have $0011+0101=0110$ whose Orthogonal Vector is $\left[\begin{array}{lll}1-1 & -1\end{array}\right]$.

For the orthogonal vectors obtained from those two approaches, we have the following theorem.

Theorem 2.5: Let $V_{1}, V_{2}, \ldots, V_{N}$ be the generated $N$ orthogonal vectors, and $v_{\imath \jmath}$ the $j-t h$ component of $v_{l}$,
(1) For all $1, v_{l 1}=1$, and
(2) $\sum_{i=1}^{N} v_{l j}=0, j \neq 1$

Proof: It is easy to see (1).
(2) It can be proved by induction.

Let $N=2$. The two orthogonal vectors are $\left[\begin{array}{l}1 \\ 1\end{array}\right]$ and $\left[\begin{array}{c}1 \\ -1\end{array}\right)$ and (2) is satısfied.

Assume (2) holds for $N=2^{m-1}$. The theorem can be proved by showing that (2) also holds for $N=2^{m}$, there are m division steps.

After the ( $m-1$ )-th division, there are $2^{m-1}$ orthogonal vectors; the rest $2^{m-1}$ orthogonal vectors are to be generated in the $m-t h$ division. Each of the first $2^{m-1}$ orthogonal vectors has $(m-1)$ subblocks; each subblock is of the form $\left[\begin{array}{l}1 \\ 1\end{array}\right]$ or $\left[\begin{array}{l}-1 \\ -1\end{array}\right]$. By the assumption, it is easy to see that $\sum_{i=1}^{2^{m-1}} v_{i j}=0, j \neq 1$. It remans to be seen that $\sum_{i=2^{m-1}+1}^{2^{m}} v_{l j}=0, j \neq 1$. At the $m-t h$ division $\left[\begin{array}{l}1 \\ 1\end{array}\right]$ and $\left[\begin{array}{c}-1 \\ -1\end{array}\right]$ both become $\left[\begin{array}{c}1 \\ -1\end{array}\right]$ or $\left[\begin{array}{c}-1 \\ 1\end{array}\right]$. By making the same substitution as mentioned earlier $\left[\begin{array}{c}1 \\ -1\end{array}\right] \rightarrow 1$ and $\left[\begin{array}{c}-1 \\ 1\end{array}\right] \rightarrow-1$, the number of components of each vector generated in the $m-t h$ division reduces from $2^{m}$ to $2^{m-1}$. Let the corresponding vectors
be $V^{\prime}{ }_{2^{m-1}+1}, \ldots, V_{2^{m}}^{\prime}$. By the assumption that (2) holds for $N=2^{m-1}, \sum_{i=2^{m-1}+1}^{2^{m}} v^{\prime}{ }_{i j}=0$. This implies that $\left[\begin{array}{c}1 \\ -1\end{array}\right]$ and $\left[\begin{array}{c}-1 \\ 1\end{array}\right]$ appear equally often for each subblock $j \neq 1$ among all $V^{\prime}$ s. Thus $\sum_{i=2^{m-1}+1}^{2^{m}} v_{l j}=0, \jmath=2,3, \ldots, 2^{m}$.

Property: Consider a matrix $M, M=\left(V_{1} V_{2} \cdots V_{N}\right), V_{l}$ is the orthogonal vectors constructed using the above approaches, then $M$ is a symmetric matrix. Notice that the order of the vectors store in the matrix $M$.

Let $N=8$, we have a symmetric matrix

$$
\left(\begin{array}{cccccccc}
1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\
1 & 1 & 1 & 1 & -1 & -1 & -1 & -1 \\
1 & 1 & -1 & -1 & 1 & 1 & -1 & -1 \\
1 & 1 & -1 & -1 & -1 & -1 & 1 & 1 \\
1 & -1 & 1 & -1 & 1 & -1 & 1 & -1 \\
1 & -1 & 1 & -1 & -1 & 1 & -1 & 1 \\
1 & -1 & -1 & 1 & 1 & -1 & -1 & 1 \\
1 & -1 & -1 & 1 & -1 & 1 & 1 & -1
\end{array}\right)
$$

The columns of the matrix are those orthogonal vectors and $V_{1}=1$, and $\sum_{i=1}^{8} v_{l j}=0, j \neq 1$.

## Chapter 3

## Conclusion

Two approaches to find out orthogonal vectors were presented. The formula approach is an efficient one in compare with those recursive approaches. A neural network constructed using those orthogonal vectors will demonstrate some special abilities and properties such as non-increasing energy and performance of convergence. And some properties of the neural network are presented in Appendix.

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## APPENDIX A:

## Some Properties of the Associative Memory built on Orthogonal Vec-

 tors.Base on these orthogonal vectors, the synaptic matrices for autoassociative and heteroassociative neural networks can be constructed.

Considering the autoassociative memory, let the synaptic matrix $W$ be the sum of outer product of $V_{l}$ as follow,

$$
W=V_{1} * V_{1}+V_{2} * V_{2}+\cdots V_{k} * V_{k}=\sum_{l=1}^{k} V_{\imath} * V_{l},
$$

where $0<k \leq N$ and $N=2^{p}, p$ is a integer integer. And we call this method as "C-Method". If a normalization is required for the $W$, then it is

$$
W=\frac{1}{k} \sum_{\imath=1}^{k} V_{\imath} * V_{\imath}=\frac{1}{k} X \cdot X^{T}
$$

The memory is made of outer-product of prescribed state vector, with some ability for recall and error correction and we will see that the neural network constructed using this method has the ability of fault tolerance. For the synaptic matrix $W$, we have the following theorem and lemma.

Theorem a.1: Let $V_{1}, V_{2}, \ldots, V_{N}$ be the constructed orthogonal vectors, then

$$
W=\frac{1}{N}\left(V_{1} * V_{1}+V_{2} * V_{2}+\ldots+V_{N} * V_{N}\right)=I
$$

where $I$ is an $N \times N$ identity matrix and $N=2^{p}, p$ is a integer constant.
Proof: Let $w_{t j}$ be a element of the matrix $W$,

$$
w_{l j}=\frac{1}{N} \sum_{k=1}^{N} v_{k l} \cdot v_{k J},
$$

When $\iota=\jmath$,

$$
w_{l u}=\frac{1}{N} \sum_{k=1}^{N} v_{k l} \cdot v_{k l}=\frac{N}{N}=1
$$

for all $i \neq j, w_{l j}$ can be proven by induction to be zero.

It also can be proved from the property in section $I I$. Since the matrix $M$ whose elements are made of orthogonal vectors is symmetric, the expression

$$
w_{l j}=\frac{1}{N} \sum_{k=1}^{N} v_{k l} \cdot v_{k j} w_{l j}=\frac{1}{N} \sum_{k=1}^{N} v_{l k} \cdot v_{\jmath k}
$$

that is,

$$
w_{l j}=\frac{1}{N}\left(V_{\imath} \cdot V_{\jmath}\right)= \begin{cases}1, & \text { if } i=j \\ 0, & \text { if } i \neq j\end{cases}
$$

Lemma: Let $W$ be a synaptic matrix generated from the sum of outer products of a set of ( $\mathrm{N}-1$ ) orthogonal neuron vectors,

$$
W=\sum_{N-1} \sum_{\text {vectors }} V_{l} * V_{l}
$$

then we have $w_{t j}=1$ or $-1, \forall i, j i!=j$.
Proof: The lemma is a extension of the theorem above.
Suppose the vector not picked up is $V_{m}$, then $V_{m} * V_{m}$ is a $N \times N$ matrix having the elements -1 or $+1 . \quad w_{\imath \jmath}=\frac{1}{N} \sum_{k=1}^{N} v_{k i} v_{k j}$

When $i \neq \jmath, N w_{l j}=\sum_{k=1, k \neq m}^{N} v_{k ı} v_{k j}+v_{m ı} v_{m \jmath}=0, \sum_{k=1, k \neq m}^{N} v_{k ı} v_{k j}=-v_{m ı} v_{m \jmath}$

$$
w_{l \jmath}=-v_{m ı} v_{m \jmath}= \pm 1
$$

Theorem a.2: Let the initial state be $V_{1}^{\prime}$ which differs from $V_{1}$ only in the $j-t h$ component, i.e., $v^{\prime}{ }_{1_{j}}=-v_{1_{j}}$.
(1) $V_{1} \cdot V_{1}^{\prime}=N-2$,
(2) $V_{k} \cdot V_{1}^{\prime}=-2 v_{k_{J}} v_{1_{J}}$, and
(3) $\left(W \cdot V^{\prime}\right)_{k}=N v_{1 k}-2 w_{\jmath k} v_{1 \jmath}, k=1,2, \ldots, N, W=\sum_{i=1}^{p} V_{t} * V_{t}$.
(4) In order to converge to $V_{1}, P<\frac{N}{2}$.

## Proof:

(1) $V_{1} \cdot V_{1}=\sum_{i=1}^{N} v_{1 i} v_{1 i}=\sum_{i=1, \iota \neq j}^{N} v_{1 \iota} v_{1 i}+v_{1 J} v_{1 J}=N$
$V_{1} \cdot V_{1}^{\prime}=\sum_{i=1, \iota \neq j}^{N} v_{1 \iota} v_{1 t}+v_{1 J}\left(-v_{1 \jmath}\right)$
$V_{1} \cdot V_{1}-V_{1} \cdot V_{1}^{\prime}=2 v_{1 J} v_{1 J}=2$.
Hence,
$V_{1} \cdot V_{1}^{\prime}=N-2$.
(2) $V_{k} \cdot V_{1}=0=\sum_{i=1}^{N} v_{k i} v_{1 \imath}=\sum_{i=1, l \neq \jmath}^{N} v_{k l} v_{1 \imath}+v_{k j} v_{1 \jmath}$
$V_{k} \cdot V^{\prime}{ }_{1}=\sum_{i=1, l \neq j}^{N} v_{k l} v_{l l}+v_{k j}\left(-v_{1 \jmath}\right)$
$V_{k} \cdot V_{1}^{\prime}-V_{k} \cdot V_{1}=-2 v_{k \jmath} v_{1 ر}$.
Hence,

$$
V_{k} V_{1}^{\prime}=-2 v_{k j} v_{1 j}
$$

(3) $\left(W \cdot V_{1}^{\prime}\right)=\left(\sum_{t=1}^{p} V_{t} * V_{l}\right) \cdot V_{1}^{\prime}$
$\left(W \cdot V_{1}^{\prime}\right)=V_{1} \cdot\left(V_{1} \cdot V_{1}{ }_{1}\right)+\sum_{i=2}^{p} V_{i} \cdot\left(V_{i} \cdot V_{1}{ }_{1}\right)$
$\left(W \cdot V^{\prime}{ }_{1}\right)=(N-2) V_{1}+\sum_{t=2}^{P}\left(-2 v_{t j} v_{1 j}\right) V_{t}$
$\left(W \cdot V^{\prime}{ }_{1}\right)_{k}=(N-2) v_{1 k}+\sum_{i=2}^{P}\left(-2 v_{l j} v_{1 J}\right) v_{t k}$
$\left(W \cdot V^{\prime}{ }_{1}\right)_{k}=N v_{1 k}-2 v_{1 k} v_{1 J} v_{1 j}+\sum_{i=2}^{P}\left(-2 v_{i j} v_{\imath k}\right) v_{1 j}$
$\left(W \cdot V^{\prime}{ }_{1}\right)_{k}=N v_{1 k}+\sum_{l=1}^{P}\left(-2 v_{t \jmath} v_{t k}\right) v_{1 j}=N v_{1 k}-2 w_{j k} v_{1 \jmath}$
(4) $\left(W \cdot V_{1}^{\prime}\right)_{j}=(N-2) v_{1 j}+\sum_{\imath=2}^{P}\left(-2 v_{\imath \jmath} v_{1 j}\right) v_{\imath j}$
$\left(W V_{1}^{\prime}\right)_{J}=(N-2) v_{1 J}+\sum_{i=2}^{P}(-2) v_{1_{j}}$
$=[N-2 P] v_{1,}$
In order that $\operatorname{sgn}\left(W \cdot V^{\prime}\right)=V_{1}, k=1, \ldots, N, N-2 P>0 . \quad$ That is, $\operatorname{sgn}\left((N-2) v_{j}\right)=-v_{1 ر}$.

Hence $P<\frac{N}{2}$.

Lemma: $\left(W V^{\prime}\right)_{J}=N v_{j}-2 v_{k} w_{k_{j}}$

Proof: This lemma is a straight forward extension of Theorem a. 2.

Theorem a.3: Let $W$ be a synaptic matrix generated from the sum of outer products of a set of orthogonal neuron vectors. $W$ is not normalized and $N$ is the number of neurons. $w_{\max }=\max \left\{w_{\imath \jmath}, \mathrm{i}, \mathrm{j}=1, \ldots, N\right\}$. A corrupted pattern with one bit error can be recovered (i.e., distance of 1) if $N / 2>w_{\max }$.

Proof: Let V be a pattern neural vector and $V^{\prime}$ its corrupted version with $k-t h$ bit in error. From Lemma above, $\left(W V^{\prime}\right)_{j}=N v_{j}-2 v_{k} w_{k j}$, which must have the same sign as $v_{j}$ in order for the network to converge to $V$ in one step. Thus $\left(W V^{\prime}\right)_{j} v_{j}$ must be greater than 0 . The corresponding sufficient condition is $N / 2>w_{\max }$.

In general, a corrupted pattern with $m$ bits of error can be recovered if $N / 2 m>w_{\max }$.

Corollary: Let $M$ be the set of indexes of erroneous bits, still $V^{\prime}$ is the corrupted vector of $V$. We have

$$
\left(W V^{\prime}\right)_{J}=N v_{J}-2 v_{k} \sum_{k \in M} w_{k_{J}}
$$

Proof: This lemma is a straight forward extension of Theorem a 3 .

Theorem a.4: If $N / 2 m>w_{\max }$, then the neural network can be recovered from m bits of errors.

Proof: From corollary above, $(W V)_{J}=N v_{J}-2 v_{k} \sum_{k \in M} w_{k j}$, which must have the same sign as $\nu_{J}$ in order for the network to converge to V in one step. Thus $(W V), v_{J}$ must be greater than 0 . The corresponding sufficient condition is $N / 2 m>w_{\max }$.

One can see that the smaller the entry values of the synaptic matrix, the better the error recovery capability.

It was mentioned in $[10]$ that for orthogonal feature vectors, the capacity is $100 \%$ in comparing with the tradeoff between the memory capacity and the degree of faulttolerance which has been estimated to be about $15 \%$ of $B$ bits in Hopfield-Little

Model [9].

There are some proposition for the symmetric matrix which can be applied for the scheme base on the sum of outer product.

Theorem a. 5 [6]: The trajectories in the state space follow contours of non-increasing energy in the above associative memory.

Proof:
$W$ is symmetric and has non-negative diagonal elements when the mode of operation is asynchronous. And the detail of prove is referred to [6].

Consider $\operatorname{sgn}(W \cdot U)_{t}=U_{t}, i=1, \ldots, k . k \leq n$. It is obvious that the memory $U_{t}$ are true eigenvectors of the weight matrix $W$.

Theorem a.6 : Global energy minima are formed at the memories for the $k$-fold degenerate spectral scheme.
proof:
The synaptic matrix constructed above is by summing of outer product as

$$
W=\sum_{k \text { vectors }} X X^{T}
$$

and the energy function is

$$
E(x)=-\frac{1}{2} X^{T} W X
$$

It is positive definite on the set of $\{-1,0,1\}^{n}$ and the eigenvalues are the same, so it is $k$-fold degenerated. The detail proof can be found in [6].

Theorem a. 7 [1]: The recursive network is free of cycles for synchronous updating.
$H e b b$ 's law as well as the project rule guarantee the absence of cycles for syn-
chronous operation.

Theorem a.8: Parasitic points cannot be formed by linear combinations of prototype vectors generated by the $C$-method.

Proof: This theorem can be proved by induction.

For a 2 -neuron network, the two prototype vectors are $\left[\begin{array}{ll}1 & 1\end{array}\right]^{T}$ and $\left[\begin{array}{ll}1 & -1\end{array}\right]^{T}$, whose linear combination is

$$
\alpha\left[\begin{array}{ll}
1 & 1
\end{array}\right]^{T}+\beta\left[\begin{array}{ll}
1 & -1
\end{array}\right]^{T}=\left[\begin{array}{ll}
-1 & -1]
\end{array} \text { or }\left[\begin{array}{ll}
-1 & 1
\end{array}\right]\right.
$$

where $\alpha$ and $\beta$ are nonzero integers. Thus, $\alpha+\beta=-1$ and $\alpha-\beta=-1$ or 1 No solutions exist such that both $\alpha$ and $\beta$ are nonzero integers.

Now assume the theorem holds for $N_{1}=2^{P}$, we want to prove that it also holds for $N_{2}=2^{P+1}=2 N$. The first $N_{1}$ vectors of the $2 N_{1}$ prototype vectors can be transformed into the $N_{1}$ prototype vectors of the $N_{1}$-neuron network by the [11]->1 and [-1-1]->-1 substitutions. Hence linear combinations of any of these first $N_{1}$ vectors would not produce any parasitic points. By the same token, the last $N_{1}$ components of the $2 N_{1}$ prototype vectors can be transformed into the $N_{1}$ prototype vector of the $N_{1}$ - neuron network by the $[1-1]->1$ and $[-11]->-1$ substitutions. Hence linear combinations of any of these last $N_{1}$ vectors would not produce any parasitic points. We have checked the first two cases of linear combinations of vectors from the $2 N_{1}$ prototype vectors. The only case remained to be checked is that part of vectors in the combination come from the first $N_{1}$ vectors and the rest come from the last $N_{1}$ vectors.

Then $V=V_{t}+\sum_{i \varepsilon Q}$, Let $\mathrm{Q}=i_{1}, \ldots, i_{q}$

$$
\begin{aligned}
\mathrm{E}(\mathrm{~V}) & =-1 / 2 V W V \\
& =-1 / 2\left(V_{t}+\sum_{\mu \varepsilon Q} Y_{\mu}\right) W\left(V_{t}+\sum_{\mu \varepsilon Q} Y_{\mu}\right) \\
& =-1 / 2 V_{t} W V_{t}-1 / 2 \sum_{s \varepsilon Q t} \sum_{\varepsilon Q} Y_{s} W Y_{t}-1 / 2 V_{t} W \sum_{\mu \varepsilon Q} Y_{\mu}-1 / 2 \sum_{\mu \varepsilon Q} Y_{\mu} W V_{t} \\
& =-1 / 2+1 / 2(4 \mathrm{q})-1 / 2 \sum_{s \varepsilon Q} \sum_{t Q} 4 V_{s t} V_{u t} W_{s t}
\end{aligned}
$$

Hence if $h\left(V, V_{l}<4,(\delta E)_{\min }>0\right.$ and $V$ always converge to $V_{1}$.

Lemma: $V_{l} W \sum_{\mu \varepsilon Q} Y_{\mu}$

$$
\begin{aligned}
& =\left(\sum_{\mu \varepsilon Q} Y_{\mu}\right) W V_{\imath} \\
& =-2 q
\end{aligned}
$$

proof:

$$
\begin{aligned}
& V_{\iota} W Y_{\mu} \\
& =V_{i}\left(W_{1 \mu} i, \cdots W_{N \mu}\right)^{T}\left(-2 V_{t \mu}\right) \\
& =V_{\iota}\left(\sum_{e \varepsilon M} V_{e \mu} V_{e}\left(-2 V_{t \mu}\right)\right. \\
& =-2 V_{\imath \mu} V_{\imath \mu} \\
& =-2 \\
& Y_{\mu} W V_{\iota}=Y_{\mu} V_{\iota}=-2 V_{t \mu} V_{t \mu} \\
& =-2
\end{aligned}
$$

$$
\text { Hence } V_{l} W\left(\sum_{\mu \varepsilon Q} Y_{\mu}\right)=\left(\sum_{\mu \varepsilon Q} Y_{\mu}\right) W V_{l}=-2 q
$$

Lemma: $Y_{s} W Y_{t}=4 W_{s t} V_{t s} V_{t t}$
proof:

$$
Y_{s} W Y_{t}=Y_{s}\left(W_{1 t}, \ldots W_{N t}\right)^{I}\left(-2 V_{t t}\right)=4 W_{s t} V_{t s} V_{t t}
$$

For the heteroassociative memory, we present a procedure to synthesize a neural network which has limit cycles with length less than the number of neurons and the states of the limit cycle are orthogonal to each other.

Let $V_{1}, V_{2}, \ldots, V_{n}$ be a set of orthogonal states with $N$ components. The following theorem describes a synaptic matrix which results in a limit cycle whose states are $V_{1}, V_{2}, \cdots, V_{n}$.

Theorem a.9: The neural network with the synaptic matrix $W^{\prime}$ which is

$$
W^{\prime}=V_{2} * V_{1}+V_{3} * V_{2}+V_{4} * V_{3}+\cdots+V_{n} * V_{n-1}+V_{1} * V_{n}
$$

(the sum of outer products) has a limit cycle of $V_{1} \rightarrow V_{2} \rightarrow V_{3 \rightarrow} \cdots \rightarrow V_{n} \rightarrow V_{1}$.
Proof: It is easy to see that $\operatorname{sgn}\left(W^{\prime} V_{1}\right)=V_{2}, \quad \operatorname{sgn}\left(W^{\prime} V_{2}\right)=V_{3}$, $\operatorname{sgn}\left(W^{\prime} V_{n-1}\right)=V_{n}$, and $\operatorname{sgn}\left(W^{\prime} V_{n}\right)=V_{1}$

Remark: $V_{l} * V_{J}$ is an $N \times N$ matrix with entry value of $a_{l m}=v_{l l} v_{j m}$.
Using the orthogonal vectors to synthesize a neural network with a limit cycle of length $m$ (less than $n$ ), just pick any $m$ vectors from $V_{1}, V_{2}, . \quad V_{n}$. Let these $m$ vectors be $V_{t_{1}}, V_{t_{2}}, \cdot V_{t_{m}}$ and the synaptic matrix be $W=V_{l_{2}} * V_{l_{1}}+V_{l_{3}} * V_{l_{2}}+\ldots+V_{l_{1}} * V_{l_{m}}$.

Then $\operatorname{sgn}\left(W V_{i_{1}}\right)=V_{t_{2}}, \operatorname{sgn}\left(W V_{t_{2}}\right)=V_{t_{3}}, \ldots \operatorname{sgn}\left(W V_{i_{m}}\right)=V_{t_{1}}$. Thus the limit cycle is $V_{t_{1}} \rightarrow V_{t_{2}} \rightarrow \cdots \rightarrow V_{i_{m}} \rightarrow V_{t_{1}}$ with length $m$.

The above are some properties and theorem found in those recursive network with orthogonal states. Examples and application of the assocrate memory constructing on the orthogonal vectors are presented in the next section.

## APPENDIX B: Examples

## Example 1:

For $N=4$, let

$$
V_{1}=\left[\begin{array}{l}
1 \\
1 \\
1 \\
1
\end{array}\right] .
$$

There are two possible choices of $V_{2}$ :

$$
\left[\begin{array}{c}
-1 \\
-1 \\
1 \\
1
\end{array}\right] \text { or }\left[\begin{array}{c}
1 \\
1 \\
-1 \\
-1
\end{array}\right] \text {. }
$$

Only one of them can be selected because they are not orthogonal to each other. Pick

$$
V_{2}=\left[\begin{array}{c}
1 \\
1 \\
-1 \\
-1
\end{array}\right]=\left[\begin{array}{l}
V_{2 a} \\
V_{2 b}
\end{array}\right]
$$

where $V_{2 a}=\left[\begin{array}{l}1 \\ 1\end{array}\right]$ and $V_{2 b}=\left[\begin{array}{l}-1 \\ -1\end{array}\right]$ and $V_{1} V_{2}=0$. Now divide $V_{2 a}$ and $V_{2 b}$ into two subblocks:

$$
[1] \text { and }[-1] .
$$

That is $V_{2 a}, V_{2 b} \rightarrow\left[\begin{array}{l}+1 \\ -1\end{array}\right]$ or $\left[\begin{array}{l}-1 \\ +1\end{array}\right]$. Thus there are four possible choices of $V_{3}$ :

$$
\left[\begin{array}{l}
+1 \\
-1 \\
+1 \\
-1
\end{array}\right],\left[\begin{array}{l}
+1 \\
-1 \\
-1 \\
+1
\end{array}\right],\left[\begin{array}{l}
-1 \\
+1 \\
+1 \\
-1
\end{array}\right] \text { and }\left[\begin{array}{l}
-1 \\
+1 \\
-1 \\
+1
\end{array}\right] .
$$

They are all orthogonal to $V_{1}$ and $V_{2}$.

## Example 2:

For $N=8$, using the formula approach, the following orthogonal vectors can be obtained.

$$
\left[\begin{array}{l}
1 \\
1 \\
1 \\
1 \\
1 \\
1 \\
1 \\
1
\end{array}\right]\left[\begin{array}{c}
1 \\
1 \\
1 \\
1 \\
-1 \\
-1 \\
-1 \\
-1
\end{array}\right]\left[\begin{array}{c}
1 \\
1 \\
-1 \\
-1 \\
1 \\
1 \\
-1 \\
-1
\end{array}\right]\left[\begin{array}{c}
1 \\
1 \\
-1 \\
-1 \\
-1 \\
-1 \\
1 \\
1
\end{array}\right]\left[\begin{array}{c}
1 \\
-1 \\
1 \\
-1 \\
1 \\
-1 \\
1 \\
-1
\end{array}\right]\left[\begin{array}{c}
1 \\
-1 \\
1 \\
-1 \\
-1 \\
1 \\
-1 \\
1
\end{array}\right]\left[\begin{array}{c}
1 \\
-1 \\
-1 \\
1 \\
1 \\
-1 \\
-1 \\
1
\end{array}\right]\left[\begin{array}{c}
1 \\
-1 \\
-1 \\
1 \\
-1 \\
1 \\
1 \\
-1
\end{array}\right]
$$

Picking up the vectors $V_{0}, V_{1}$ and $V_{6}$ from the the above orthogonal vectors, we can construct a weight-matrix by applying Strategy 1:

$$
W=\left(V_{0} * V_{0}+V_{1} * V_{1}+V_{6} * V_{6}\right),
$$

or using the normalization factor $\frac{1}{p}$, ensures that $-1 \leq w_{i j} \leq+1$.

$$
W=\frac{1}{3} *\left(V_{0} * V_{0}+V_{1} * V_{1}+V_{6} * V_{6}\right)
$$

where

$$
V_{0}=\left[\begin{array}{l}
1 \\
1 \\
1 \\
1 \\
1 \\
1 \\
1 \\
1
\end{array}\right] \quad V_{1}=\left[\begin{array}{c}
1 \\
1 \\
1 \\
1 \\
-1 \\
-1 \\
-1 \\
-1
\end{array}\right] \quad V_{6}=\left[\begin{array}{c}
1 \\
-1 \\
-1 \\
1 \\
1 \\
-1 \\
-1 \\
1
\end{array}\right]
$$

the matrix:

$$
\left[\begin{array}{cccccccc}
3 & 1 & 1 & 3 & 1 & -1 & -1 & 1 \\
1 & 3 & 3 & 1 & -1 & 1 & 1 & -1 \\
1 & 3 & 3 & 1 & -1 & 1 & 1 & -1 \\
3 & 1 & 1 & 3 & 1 & -1 & -1 & 1 \\
1 & -1 & -1 & 1 & 3 & 1 & 1 & 3 \\
-1 & 1 & 1 & -1 & 1 & 3 & 3 & 1 \\
-1 & 1 & 1 & -1 & 1 & 3 & 3 & 1 \\
1 & -1 & -1 & 1 & 3 & 1 & 1 & 3
\end{array}\right]
$$

or the normalized one.

$$
\left[\begin{array}{cccccccc}
3 & 1 & 1 & 3 & 1 & -1 & -1 & 1 \\
1 & 3 & 3 & 1 & -1 & 1 & 1 & -1 \\
1 & 3 & 3 & 1 & -1 & 1 & 1 & -1 \\
3 & 1 & 1 & 3 & 1 & -1 & -1 & 1 \\
1 & -1 & -1 & 1 & 3 & 1 & 1 & 3 \\
-1 & 1 & 1 & -1 & 1 & 3 & 3 & 1 \\
-1 & 1 & 1 & -1 & 1 & 3 & 3 & 1 \\
1 & -1 & -1 & 1 & 3 & 1 & 1 & 3
\end{array}\right] * \frac{1}{3}
$$

The synaptic matrix is symmetric and the positive definite. By computing the energy $E(v)=-\frac{1}{2} V^{T} \cdot W \cdot V$, following the slope of the energy function, it may go to the local minima. The local minima can be found in the following states,

$$
\left[\begin{array}{l}
1 \\
1 \\
1 \\
1 \\
1 \\
1 \\
1 \\
1
\end{array}\right]\left[\begin{array}{c}
1 \\
-1 \\
-1 \\
1 \\
1 \\
1 \\
1 \\
1
\end{array}\right]\left[\begin{array}{c}
-1 \\
1 \\
1 \\
-1 \\
1 \\
1 \\
1 \\
1
\end{array}\right]\left[\begin{array}{l}
-1 \\
-1 \\
-1 \\
-1 \\
1 \\
1 \\
1 \\
1
\end{array}\right]\left[\begin{array}{c}
1 \\
1 \\
1 \\
1 \\
1 \\
-1 \\
-1 \\
1
\end{array}\right]\left[\begin{array}{c}
1 \\
-1 \\
-1 \\
1 \\
1 \\
-1 \\
-1 \\
1
\end{array}\right]\left[\begin{array}{c}
-1 \\
-1 \\
-1 \\
-1 \\
1 \\
-1 \\
-1 \\
1
\end{array}\right]
$$

$$
\left[\begin{array}{c}
1 \\
1 \\
1 \\
1 \\
-1 \\
1 \\
1 \\
-1
\end{array}\right]\left[\begin{array}{c}
-1 \\
1 \\
1 \\
-1 \\
-1 \\
1 \\
1 \\
-1
\end{array}\right]\left[\begin{array}{c}
-1 \\
-1 \\
-1 \\
-1 \\
-1 \\
1 \\
1 \\
-1
\end{array}\right]\left[\begin{array}{c}
1 \\
1 \\
1 \\
1 \\
-1 \\
-1 \\
-1 \\
-1
\end{array}\right]\left[\begin{array}{c}
1 \\
-1 \\
-1 \\
1 \\
-1 \\
-1 \\
-1 \\
-1
\end{array}\right]\left[\begin{array}{c}
-1 \\
1 \\
1 \\
-1 \\
-1 \\
-1 \\
-1 \\
-1
\end{array}\right]\left[\begin{array}{l}
-1 \\
-1 \\
-1 \\
-1 \\
-1 \\
-1 \\
-1 \\
-1
\end{array}\right]
$$

and global minima are

$$
\left[\begin{array}{l}
1 \\
1 \\
1 \\
1 \\
1 \\
1 \\
1 \\
1
\end{array}\right]\left[\begin{array}{c}
-1 \\
-1 \\
-1 \\
-1 \\
1 \\
1 \\
1 \\
1
\end{array}\right]\left[\begin{array}{c}
1 \\
-1 \\
-1 \\
1 \\
1 \\
-1 \\
-1 \\
1
\end{array}\right]\left[\begin{array}{c}
-1 \\
1 \\
1 \\
-1 \\
-1 \\
1 \\
1 \\
-1
\end{array}\right]\left[\begin{array}{c}
1 \\
1 \\
1 \\
1 \\
-1 \\
-1 \\
-1 \\
-1
\end{array}\right]\left[\begin{array}{l}
-1 \\
-1 \\
-1 \\
-1 \\
-1 \\
-1 \\
-1 \\
-1
\end{array}\right]
$$

which are $V_{0}, V_{1}, V_{6},-V_{6},-V_{1}$ and $-V_{0}$. Note that there are no spurious states.

If there is 1 bit corrupted in vector $V_{6}$, and new vector is named as $V_{6}^{\prime}$,

$$
V_{6}^{\prime}=\left[\begin{array}{c}
1 \\
-1 \\
-1 \\
-1 \\
1 \\
-1 \\
-1 \\
1
\end{array}\right] \text { and } V_{6}=\left[\begin{array}{c}
1 \\
-1 \\
-1 \\
1 \\
1 \\
-1 \\
-1 \\
1
\end{array}\right]
$$

Applying the weight matrix, $V_{6}^{\prime}$ can go back to $V_{6}$ through one step.

$$
\operatorname{sgn}\left(W * V_{6}^{\prime}\right)=V_{6}
$$

That is the result from Theorem $a .3$, and one bit error can be recovered.

## Example 3:

When $N=16$, using those approaches, we can get 16 orthogonal vectors. Still let $W=V_{1} * V_{1}+\cdots+V_{k} * V_{k}$, let $k=3$, pick the vectors $V_{0}, V_{13}$ and $V_{2}$,

$$
\begin{aligned}
& V_{0}^{T}=[+1+1+1+1+1+1+1+1+1+1+1+1+1+1+1+1] \\
& V_{2}^{T}=[+1+1+1+1-1-1-1-1+1+1+1+1-1-1-1-1] \\
& V_{13}^{T}=[+1-1-1+1+1-1-1+1-1+1+1-1-1+1+1-1] .
\end{aligned}
$$

constructing the synaptic matrix using the outer product scheme, the weight matrix is as following:

$$
\left[\begin{array}{cccccccccccccccc}
3 & 1 & 1 & 3 & 1 & -1 & -1 & 1 & 1 & 3 & 3 & 1 & -1 & 1 & 1 & -1 \\
1 & 3 & 3 & 1 & -1 & 1 & 1 & -1 & 3 & 1 & 1 & 3 & 1 & -1 & -1 & 1 \\
1 & 3 & 3 & 1 & -1 & 1 & 1 & -1 & 3 & 1 & 1 & 3 & 1 & -1 & -1 & 1 \\
3 & 1 & 1 & 3 & 1 & -1 & -1 & 1 & 1 & 3 & 3 & 1 & -1 & 1 & 1 & -1 \\
1 & -1 & -1 & 1 & 3 & 1 & 1 & 3 & -1 & 1 & 1 & -1 & 1 & 3 & 3 & 1 \\
-1 & 1 & 1 & -1 & 1 & 3 & 3 & 1 & 1 & -1 & -1 & 1 & 3 & 1 & 1 & 3 \\
-1 & 1 & 1 & -1 & 1 & 3 & 3 & 1 & 1 & -1 & -1 & 1 & 3 & 1 & 1 & 3 \\
1 & -1 & -1 & 1 & 3 & 1 & 1 & 3 & -1 & 1 & 1 & -1 & 1 & 3 & 3 & 1 \\
1 & 3 & 3 & 1 & -1 & 1 & 1 & -1 & 3 & 1 & 1 & 3 & 1 & -1 & -1 & 1 \\
3 & 1 & 1 & 3 & 1 & -1 & -1 & 1 & 1 & 3 & 3 & 1 & -1 & 1 & 1 & -1 \\
3 & 1 & 1 & 3 & 1 & -1 & -1 & 1 & 1 & 3 & 3 & 1 & -1 & 1 & 1 & -1 \\
1 & 3 & 3 & 1 & -1 & 1 & 1 & -1 & 3 & 1 & 1 & 3 & 1 & -1 & -1 & 1 \\
-1 & 1 & 1 & -1 & 1 & 3 & 3 & 1 & 1 & -1 & -1 & 1 & 3 & 1 & 1 & 3 \\
1 & -1 & -1 & 1 & 3 & 1 & 1 & 3 & -1 & 1 & 1 & -1 & 1 & 3 & 3 & 1 \\
1 & -1 & -1 & 1 & 3 & 1 & 1 & 3 & -1 & 1 & 1 & -1 & 1 & 3 & 3 & 1 \\
-1 & 1 & 1 & -1 & 1 & 3 & 3 & 1 & 1 & -1 & -1 & 1 & 3 & 1 & 1 & 3
\end{array}\right]
$$

$V_{0}, V_{2}$ and $V_{13}$ are the fix point of the memory. Suppose there two bits in $V_{13}$ are corrupted, or suppose another state $V_{13}{ }^{\prime}$ near $V_{13}$ whose Hamming Distance is 2 .
$V_{13}^{\prime}=\left[\begin{array}{lllllllllllll}1 & -1 & -1 & 1 & 1 & -1 & -1 & 1 & -1 & 1 & -1 & -1 & 1\end{array} 11-1\right]$ and it is obvious that the different bits are the \#11 and \#13. By applying $\operatorname{sgn}(W X)$, the state $V_{13}{ }^{\prime}$ will converge to the fixed point $V_{13}$ through one step.

$$
\operatorname{sgn}\left(W \cdot V_{13}{ }^{\prime}\right)=V_{13}
$$

That is what stated in the Theorem $a .4$, where $w_{\max }=3, N=16$ and number of the corrupted bit is $m=2, \frac{N}{2 m}>w_{\max }$.

## Example 4:

We have four orthogonal vectors in example 1 ,

$$
V_{1}=\left[\begin{array}{l}
1 \\
1 \\
1 \\
1
\end{array}\right] \quad V_{2}=\left[\begin{array}{c}
1 \\
1 \\
-1 \\
-1
\end{array}\right] \quad V_{3}=\left[\begin{array}{l}
+1 \\
-1 \\
+1 \\
-1
\end{array}\right] \text { and } V_{4}=\left[\begin{array}{c}
+1 \\
-1 \\
-1 \\
+1
\end{array}\right]
$$

To construct a heteroassociative memory described in Section III, the corresponding synaptic matrix is

$$
W=V_{2} * V_{1}+V_{3} * V_{2}+V_{4} * V_{3}+V_{1} * V_{4}=\left[\begin{array}{cccc}
4 & 0 & 0 & 0 \\
0 & 0 & 0 & 4 \\
0 & 0 & -4 & 0 \\
0 & -4 & 0 & 0
\end{array}\right]
$$

It is straightforward to see that

$$
\begin{aligned}
& \operatorname{sgn}\left(W V_{1}\right)=V_{2}, \\
& \operatorname{sgn}\left(W V_{2}\right)=V_{3}, \\
& \operatorname{sgn}\left(W V_{3}\right)=V_{4},
\end{aligned}
$$

and

$$
\operatorname{sgn}\left(W V_{4}\right)=V_{1 .}
$$

Hence the limit cycle is $V_{1} \rightarrow V_{2} \rightarrow V_{3} \rightarrow V_{4} \rightarrow V_{1}$. It is easy to see that $-V_{1} \rightarrow-V_{2} \rightarrow-V_{3} \rightarrow-V_{4} \rightarrow-V_{1}$ is another limit cycle. It is interesting to see whether the rest of 8 vectors are also on certain limit cycles.

Let

$$
V_{5}=\left[\begin{array}{llll}
1 & 1 & 1 & -1
\end{array}\right]^{T}
$$

then

$$
\begin{gathered}
\operatorname{sgn}\left(W V_{5}\right)=\left[\begin{array}{llll}
1 & -1 & -1 & -1
\end{array}\right]^{T}=V_{6}, \\
\operatorname{sgn}\left(W V_{6}\right)=\left[\begin{array}{llll}
1 & -1 & 1 & 1
\end{array}\right]^{T}=V_{7}, \\
\operatorname{sgn}\left(W V_{7}\right)=\left[\begin{array}{llll}
1 & 1 & -1 & 1
\end{array}\right]^{T}=V_{8},
\end{gathered}
$$

and

$$
\operatorname{sgn}\left(W V_{8}\right)=\left[\begin{array}{llll}
1 & 1 & 1 & -1
\end{array}\right]^{T}=V_{5},
$$

Thus there is a limit cycle: $V_{5} \rightarrow V_{6} \rightarrow V_{7} \rightarrow V_{8} \rightarrow V_{5} . \quad-V_{5} \rightarrow-V_{6} \rightarrow-V_{7} \rightarrow-V_{8} \rightarrow-V_{5}$ is also a limit cycle. Thus every state is in some limit cycle and the memory capacity is greatly increased.

A neural network constructed using those orthogonal vectors is introduced and we demonstrated the ability and properties of the neural network and some advantages comparing to those other models, the advantages are especially as no spurious states, energy non-increasing and performance of convergence to fix point.

