## Copyright Warning \& Restrictions

The copyright law of the United States (Title 17, United States Code) governs the making of photocopies or other reproductions of copyrighted material.

Under certain conditions specified in the law, libraries and archives are authorized to furnish a photocopy or other reproduction. One of these specified conditions is that the photocopy or reproduction is not to be "used for any purpose other than private study, scholarship, or research." If $a$, user makes a request for, or later uses, a photocopy or reproduction for purposes in excess of "fair use" that user may be liable for copyright infringement,

This institution reserves the right to refuse to accept a copying order if, in its judgment, fulfillment of the order would involve violation of copyright law.

Please Note: The author retains the copyright while the New Jersey Institute of Technology reserves the right to distribute this thesis or dissertation

Printing note: If you do not wish to print this page, then select "Pages from: first page \# to: last page \#" on the print dialog screen

The Van Houten library has removed some of the personal information and all signatures from the approval page and biographical sketches of theses and dissertations in order to protect the identity of NJIT graduates and faculty.

# ABSTRACT <br> Structural Reliability <br> Using Finite Element Method 

by

## Che-Chen Liou

During the last decade, structural reliability theory has been treated in a large number of research papers; therefore, from being a subject only well known by a relatively small number of researchers, it has become an important engineering discipline. From the application point of view, many practical applications have been made successfully.

In this dissertation some important fundamental concepts in statistics and in reliability theory are presented. The concept of failure mode can be defined as: A set of failed elements turn a structure into a mechanism. Usually, a structure has many possible failure modes; therefore, it will be necessary to estimate the reliability with respect to each specified failure mode, and then to estimate the overall reliability of the structure from a system point of view. In this dissertation the methodology of using ANSYS finite element software to identity the failure modes is introduced in detail.

The modelling used in this dissertation is based on the assumption that the total reliability of the structure can be sufficiently accurately estimated by considering only a finite number of significant failure modes and then combining them in a complex reliability system. Usually, the reliability of a structural system is modeled by a series of failure modes each composed of failure elements assembled in parallel.

# STRUCTURAL RELIABILITY 

 USING FINITE ELEMENT METHODby<br>Che-Chen Liou

A Dissertation<br>Submitted to the Faculty of New Jersey Institute of Technology in Partial Fulfillment of the Requirements for the Degree of<br>Doctor of Philosophy<br>Department of Mechanical and Industrial Engineering<br>May 1992



# APPROVAL PAGE <br> Structure Reliability Using Finite Element Method 

by

Che-Chen Liou

Dr. Nouri Levy, Dissertation Adviser
Associate Professor of Mechanical and Industrial Engineering, NJTT

Dr. Harry Herman, Committee Member
Associate Chairperson for Graduate Studies and Professor of Mechanical and Industrial Engineering, NJIT

Dr. John Droughton, Committee Member
Associate Chairperson and Associate Professor of Mechanical and Industrial Engineering, NJIT

Dr. Ernest Geskin, Committee Member
Professor of Mechanical and Industrial Engineering, NJTT

## BIOGRAPHICAL SKETCH

Author: Che-Chen Liou

Degree: Doctor of Philosophy in Mechanical Engineering

Date: May,1992

## Undergraduate and Graduate Education:

- Doctor of Philosophy in Mechanical and Industrial Engineering, New Jersey Institute of Technology, Newark, NJ, 1992
- Master of Science in Mechanical and Industrial Engineering, New Jersey Institute of Technology, Newark, NJ, 1988
- Bachelor of Science in Marine Engineering, National Taiwan Ocean University, Keelong, Taiwan, 1985

Major: Mechanical Engineering

To my parents and my wife

## ACKNOWLEDGMENT

The author wishes to express his sincere gratitude to his advisors, Professor Nouri Levy and Professor Harry Herman, for their guidance, and moral support.

Special thanks to Professors John Droughton and Ernest Geskin for serving as members of the committee

## TABLE OF CONTENTS

## Page

1 INTRODUCTION ..... 1
2 BASIC STATISTICS .....  .6
2.1 Terminology ..... 6
2.2 Probability ..... 7
2.3 Some Fundamental Probability Rules ..... 7
2.4 Counting Techniques ..... 11
2.4.1 Tree ..... 11
2.4.2 Permutations ..... 13
2.4.3 Combinations ..... 13
2.4.4 Permutations When Some Objects Repeated ..... 13
2.5 Random Variables and Density Functions ..... 14
2.5.1 Discrete Random Variables ..... 15
2.5.2 Marginal and Conditional Distributions ..... 16
2.5.3 Continuous Random Variables ..... 18
3 SOME PROBABILITY DISTRIBUTIONS USED IN RELIABILITY ..... 20
3.1 Introduction ..... 20
3.2 Discrete Distributions ..... 20
3.2.1 Expectation, Moment, and Moment Generating Functions ..... 20
3.2.2 Some Algebra for Random Variables ..... 23
3.2.3 Binomial Distribution ..... 24
3.2.4 Poisson Distribution ..... 25
3.3 Continuous Distributions ..... 25
3.3.1 Expection, Moment, and Moment Generating Functions ..... 26
3.3.2 Uniform Distribution ..... 28
3.3.3 Normal Distribution ..... 28
3.3.4 Gamma Distribution ..... 30
3.3.5 Exponential Distribution ..... 31
3.3.6 Chi-square Distribution. ..... 31
3.3.7 Lognormal Distribution ..... 32
3.3.8 Weibull Distribution ..... 33
4 INTRODUCTION TO SYSTEM RELLABILITY ..... 34
4.1 Definitions ..... 34
4.2 Representation of System Logic ..... 35
4.3 Analysis of Simple System ..... 39
4.4 Reliability of Simple Systems ..... 41
4.5 Reliability of Dynamic System ..... 43
4.6 The Concept of Failure Rate ..... 44
4.7 System Availability Function. ..... 49
4.8 Decomposition of Structure Functions ..... 54
4.9 The Reliability Importance of a Component ..... 55
5 SOME BASIC THEORIES OF STRUCTURAL RELIABILITY ..... 59
5.1 Introduction ..... 59
5.2 The Fundamental Case ..... 59
5.3 The Concept of Failure Surfaces ..... 65
5.4 The Concept of Linearization and Normalization ..... 70
6 MODELLING OF STRUCTURES ..... 84
6.1 Introduction ..... 82
6.2 Modelling of Fundamental Structural Systems ..... 85
6.3 Modelling of Structures ..... 87
6.4 Calculation of The Multivariate Norma Distritution Function ..... 89
7 RELIABILITY OF STRUCTURAL SYSTEMS ..... 93
7.1 Probability of Failure of Series Systems ..... 93
7.2 Approximate Techneques for Series Systems ..... 99
7.3 Probability of Failure of Parallel Systems ..... 101
7.4 Approximate Techniques for Parallel Systems ..... 105
7.5 Equivalent Linear Safety Margin for Parallel Systems ..... 107
8 GENERATION OF SAFETY MARGINS BY ANSYS ..... 112
8.1 Introduction ..... 112
8.2 The Theory of Generation of Safety Margins ..... 112
8.3 Generation of Safety Margins Using Ansys ..... 117
9 STRUCTURAL RELIABILITY ANALYSIS USING ANSYS ..... 153
9.1 Introduction ..... 153
9.2 Transformations of Non-normal Basic Variables ..... 154
9.3 Estimate of Structural Reliability ..... 157
APPENDIX A:ANSYS PROGRAM AND FORCE DISTRIBUTION ..... 224
APPENDIX B:ANSYS PROGRAM AND FORCE DISTRIBUTION ..... 228
APPENDIX C:ANSYS PROGRAM AND FORCE DISTRIBUTION ..... 235
APPENDIX D:ANSYS PROGRAM AND FORCE DISTRIBUTION ..... 242
APPENDIX E:ANSYS PROGRAM AND FORCE DISTRIBUTION ..... 248
APPENDIX F:ANSYS PROGRAM AND FORCE DISTRIBUTION ..... 254
APPENDIX G:ANSYS PROGRAM AND FORCE DISTRIBUTION ..... 261
APPENDIX H:ANSYS PROGRAM AND FORCE DISTRIBUTION ..... 267
APPENDIX I:ANSYS PROGRAM AND FORCE DISTRIBUTION. ..... 274
APPENDIX J:ANSYS PROGRAM AND FORCE DISTRIBUTION ..... 280
APPENDX K:ANSYS PROGRAM AND FORCE DISTRIBUTION ..... 287
BIBLIOGRAPHY ..... 293

## CHAPTER 1

## INTRODUCTION

During the last decade structural reliability theory has been used in a large number of research reports and conference papers; therefore, from being a subject only well known by a relatively small number of researchers, it now becomes an important engineering discipline. From the application point of view, structural reliability is a relatively new area. However, many practical applications have been made successfully.

In this thesis, some important fundamental concepts in statistics and in reliability theory are presented. In the process of solving a real-life problem in statistics, three steps must be considered. First, a mathematical model is selected. Second, a check is made of the reasonableness of the model. Third, an appropriate conclusion is obtained from this model to solve the specified problem. The theory of statistics can be treated as a fundamental part of reliability analysis in which probability is the basic tool.

The reliability of a structure in this thesis can be defined as: the ability of a structure to perform its design purpose, under some specified conditions, for a reasonably accepted probability of failure. The reliability of a structure is denoted by $R$ and is defined as $R=1-P_{f}$ where $P_{f}$ is the probability of failure of the structure. An individual's approach to probability depends on the nature of one's interest in the subject. The applied engineers usually think of probability as the proportion of times that a certain event will occur if the experiment related to the event is repeated indefinitely. Some statisticians think of probability of a system as its ability to perform a required function, under stated conditions, for a stated period of time. The probability should be a number between zero and one. The term reliability is also used to denote the probability of success.

In evaluating structural reliability, the first step is usually to identify the variables by which the reliability of the structure can be described. Typically, these variables include material strengths, geometrical quantities, and external loads; These variables are called basic variables and are modelled as random variables or as stochastic process, but only those modelled by random variables are considered in this thesis. Usually, a structure has many possible failure modes; therefore, we will usually estimate the reliability with respect to each specified failure mode, and then estimate the overall reliability of the structure from a system point of view. A failure mode can be defined as: A set of failure members forms a mechanism which causes the structure to fail, then this set of failure members is called failure mode. A failure mode can be represented by a parallel system.

It is a common recognition that an estimate of the reliability of a structure must be based on a system approach. Sometimes it is sufficient to estimate the individual reliability of each member in a structure: for instance, for a statically determinate structure where failure in any member will result in the failure of the whole structure. However, failure of a single member will not always result in failure of the whole structure because the existing members may be able to sustain the external loads by redistribution of the internal load effects. For instance, a statically indeterminate (redundant) structure, where failure of the structure needs that more than one member fail.

In practice, a structure is usually so complex that the number of possible different failure modes is so large that they can not all be taken into account; therefore, the model must be built up carefully so that the most significant failure modes of the structure are chosen in the model. In order to assess the reliability of a structure, those failure modes and their safety margins must be given. For a simple structure the safety margins can be obtained by hand calculation. In the conventional analysis the failure modes and their safety margines are derived by using the priciple of virtual work. However, it is very difficultto derive significant failure modes for a large redundant structure. In this thesis we will describe how
to use ANSYS (a finite element software) to derive the failure modes in detail and the modelling used in this thesis is based on the assumption that the total reliability of the structure can be sufficiently accurately estimated by considering only a finite number of significant failure modes and then combining them in a complex reliability system.

Usually, it is assumed that the reliability of a structure is estimated on the basis of a series system modelling, where the components are failure modes, and the failure modes are modelling by parallel systems. When the reliability of a structural system is modelled by a series system of parallel systems, the reliability of the structure can be estimated by the following steps: the first step is to calculate the probability of failure for each parallel system, the second step is to evaluate the correlationship between the parallel systems, and the final step is to calculate the probability of failure of the series system.

For some structures, the reliabilities of structures are calculated on the basis of failure of single components, where the probability of failure of any component and the correlation between failed components are taken into account. Then all the failure components are combined to make up the series system. Modelling of this type is called system reliability at level 1 . The evaluation of the structural reliability can be obtained with satisfactory accuracy by only including failure components with high probabilities of failure. Such significant failure components can be selected by choosing those failure components with $P_{f}$ values in an interval $\left[P_{f m a x}, P_{f m a x}-\Delta P_{f}\right]$, where $\Delta P_{f}$ must be chosen properly.

For some structures, the reliabilities of the structures are calculated on the basis of failure of two faillure components, where the probability of failure of any pair of failure components and the correlation between failure pairs are taken into account, and then all the failure pairs are combined to make up the series system. The modelling of this type is called system reliability at level 2 . The evaluation of structural reliability can be obtained with satisfactory accuracy by only including failure pairs with high probability of failure.

To obtain the so-called significant pairs of failure components, the structure is modified by assuming failure in the significant failure components and applying artificial loads which are the strength capacities of the failure components if the components are ductile. No artificial loads are applied if the failure components are brittle. Then the modified structure is analysed elastically and new $P_{f}$ values are calculated for all surving components. Surviving components with high $P_{f}$ values are then combined with the significant failure components so that the significant pairs of failure components can be determined. By continuing in the same procedure, system reliability at level $\mathrm{N}, \mathrm{N}=3,4,5 \ldots \ldots$. can be defined.

The most frequently used modelling of system reliability is system reliability at the mechanism level. Usually the number of mechanisms (failure modes) is very large; therefore, only some reasonable number of significant mechanisms should be considered. The procedure described above can be continued until formation of mechanisms, but when a structure is very complex it is better to base the ANSYS reliability analysis on the fundamental mechanisms and on the linear combinations of fundamental mechanisms.

In order to assess the reliability of a structure, the failure modes and safety margins must be given. Automatic generation of failure modes was initiated by using an incremental method suggested by Moses, F., 1983. A method for generation basic mechanism was proposed by Watwood, V.B., 1979. A general procedure for expressing the safety margins in terms of the random variables was developed by Murotsu, Y., 1980.

During last decade, many papers have been published, but in most of these papers it is only shown how the reliability of single structural members can be evaluated. Some of these papers have a limited scope and some are more general. In this thesis, the joint probability distribution of relevant variables is simplified and the failure criteria are idealized in such a way that the reliability evaluations can be treated for very complex structures.

The most difficult part of evaluating structural reliability is to identify the failure modes. Several methods to identify the failure modes have been suggested. In this thesis Using ANSYS finite element software to accurately identify the failure modes is describes in detail, and this method can be used extensively.

The problem of calculating the reliability of a structure is complex. The complexity is due to the large number of failure modes that have to be considered. As the structures become larger, the number of failure mechanisms grows very rapidly. Large computational resources are needed for discovering and ranking the possible failure modes. It is therefore suggested that heuristic methods should be developped in order to direct the search towards failure modes which result in the highest probability of structure failure.

This thesis is a first step towards automating the generation of all possible failure mechanisms. It is clear from the above that future work should be directed toward efficient methods of enumerating only the most significant modes of failures so that the mothods can be scaled up to tackle practical structures.

# CHAPTER 2 <br> BASIC STATISTICS 

### 2.1 TERMINOLOGY

SAMPLE SPACE: It is a set which represents all possible outcomes to the experiment. It can be a continuous set or can be a discrete set.

EVENT ( SAMPLE POINT ): An event is an outcome from experiment, and an event is a subset of a sample space. An event can also be called as a sample point.

UNION: The union of two sets, say set A and B , is a new set denoted by $A \cup B$, and this new set has in it all the elements in either A or B or both.

INTERSECTION: The intersection of two sets, say set A and B , is another set denoted by $A \cap B$, and this set has in it only those elements in both A and B .

COMPLEMENT: The complement of a set is the collection of all elements in the sample space that are not in the given set. The complement of a set A is denoted by $\bar{A}$.(Assume that A and $\bar{A}$ consist of the entire sample space).

DE MORGAN'S LAW ( FOR COMPLEMENTARITY):
$\overline{(A \cup B)}=\bar{A} \cap \bar{B} ; \overline{(A \cap B)}=\bar{A} \cup \bar{B}$.

DISJOINT ( INDEPENDENT ): If two sets, A and B, have no outcomes in common they are called as disjoint sets, or disjoint events.

### 2.2 PROBABILITY

In the applied engineers point of view, the probability can be described as the proportion of times that a certain event will occur if the experiment related to the event is repeated indefinitely. The probability should be a number between 0 and 1 , and the probability of the whole sample space should be 1 . Finally, if two sets $A$ and $B$ are disjont, the probability of the union of these two sets should be equal to the sum of the probabilities of these two sets. Therefore, the probability P should satisty:
(1) $0 \leq P(A) \leq 1$, for every set A .
(2) $P(S)=1$, for whole sample space $S$.
(3) $P(A \cup B \cup \ldots)=P(A)+P(B)+\ldots$, for disjoint sets $A, B, \ldots$

### 2.3 SOME FUNDAMENTAL PROBABILITY RULES

ADDITION RULE (OR):

$$
P(A \cup B)=P(A)+P(B)-P(A \cap B)
$$

When $A$ and $\bar{A}$ consist of the entire sample space, $P(A)=1-P(\bar{A})$, where $\bar{A}$ is the set that A will not occur. This formula is useful for calculating the probability that an event will occur when it is easier to calculate the probability that the event will not occur.

Addition Rule can be written in a general form:

$$
\begin{aligned}
& P\left(\bigcup_{i=1}^{n} A_{i}\right)=\sum_{i=1}^{n} P\left(A_{i}\right)-\sum_{i<j} P\left(A_{i} \cap A_{j}\right)+\sum_{i<j<k} P\left(A_{i} \cap A_{j} \cap A_{k}\right) \\
& \quad+\ldots+(-1)^{n-1} P\left(A_{1} \cap A_{2} \cap \ldots \cap A_{n}\right)
\end{aligned}
$$

CONDITIONAL RULE:

$$
P(B / A)=\frac{P(A \cap B)}{P(A)}
$$

The probability that B will occur given that A has already occured.

MULTIPLICATION
RULE
(AND):

$$
P(A \cap B)=P(A) P(B / A)=P(B) P(A / B)
$$

If A and B are independent to each other, $P(B / A)=P(B)$, and $P(A / B)=P(A)$.This means that the probability of B ( or A ) occuring is not affected by that $\mathrm{A}($ or B$)$.

When A and B are independent, $P(A \cap B)=P(A) P(B)$

Multiplication Rule can be written in a general form

$$
\begin{aligned}
& P\left(A_{1} \cap A_{2} \cap \ldots \cap A_{n}\right)=P\left(A_{1}\right) P\left(A_{2} / A_{1}\right) P\left(\frac{A_{3}}{A_{1} \cap A_{2}}\right) \ldots \\
& \ldots P\left(A_{n} / A_{1} \cap A_{2} \cap \ldots A_{n-1}\right)
\end{aligned}
$$

## BAYES' FORMULA:



From the multiplication rule, it gives:

$$
P(B \cap A)=P(A / B) P(B)=P(B / A) P(A)
$$

From the figure shown above, the probability of A can be derived as following:

$$
\begin{aligned}
& P(A)=P\left(B_{1} \cap A\right)+P\left(B_{2} \cap A\right)+\ldots+P\left(B_{5} \cap A\right) \\
& \quad=P\left(A / B_{1}\right) P\left(B_{1}\right)+\ldots+P\left(A / B_{5}\right) P\left(B_{5}\right)=\sum_{k=1}^{5} P\left(A / B_{k}\right) P\left(B_{k}\right) \\
& \text { Therefore, } P\left(B_{1} / A\right)=\frac{P\left(B_{1} \cap A\right)}{P(A)}=\frac{P\left(A / B_{1}\right) P\left(B_{1}\right)}{\sum_{k=1}^{5} P\left(A / B_{k}\right) P\left(B_{k}\right)}
\end{aligned}
$$

The result may be summarized as follows:

$$
P\left(B_{i} / A\right)=\frac{P\left(B_{i}\right) P\left(A / B_{i}\right)}{\sum_{j=1}^{k} P\left(A / B_{j}\right) P\left(B_{j}\right)}, i=1,2, \ldots, k
$$

Therefore,the total probability is defined as follows:
$P(A)=\sum_{j=1}^{\infty} P\left(A \cap B_{j}\right)=\sum_{j=1}^{\infty} P\left(A / B_{j}\right) P\left(B_{j}\right)$

Where, $A$ is an event that occured when the experiment was performed, and calculate the probability $B_{i}$ that was the cause of the occurrence of A. Where, all B's are disjoint.

Example 1. There are two identical boxes; One box contains two white balls, and the second box contains one white ball and one black ball,if a box is selected randomly and one ball is drawn from it. What is the probability that the second box was selected, if the drawn ball turns out to be white?

Let $X_{1}$ and $X_{2}$ represent box 1 and box 2 respectively, and let $W$ represent the event of getting a white ball. Therefore, $P\left(X_{1}\right)=P\left(X_{2}\right)=\frac{1}{2}, P\left(W / X_{1}\right)=1$,

$$
P\left(W / X_{2}\right)=\frac{1}{2} \cdot \text { By Bayes' formula: }
$$

$$
\begin{gathered}
P\left(X_{2} / W\right)=\frac{P\left(X_{2}\right) P\left(W / X_{2}\right)}{\sum_{i=1}^{2} P\left(X_{i}\right) P\left(W / X_{i}\right)} \\
=\frac{P\left(X_{2}\right) P\left(W / X_{2}\right)}{P\left(X_{1}\right) P\left(W / X_{1}\right)+P\left(X_{2}\right) P\left(W / X_{2}\right)}
\end{gathered}
$$

$$
=\frac{\frac{1}{2} \frac{1}{2}}{\frac{1}{2} 1+\frac{1}{2} \frac{1}{2}}=\frac{\frac{1}{4}}{\frac{3}{4}}=\frac{1}{3}
$$

### 2.4 COUNTING TECHNIQUES

Sometimes, the counting of various events is very tedious unless compact counting methods are used. Some of the formulas that provide such methods are described in this section.

### 2.4.1 TREE

If an experiment can be treated as a multiple-stage experiment, the problem of counting sample outcomes can be considerably simplified by using the tree diagram. For example, toss a fair coin three times. This is a three-stage experiment where the various possibilities
that can occur may be represented by a tree diagram as shown below: ( H stands for head; T stands for tail ).


Each stage of a multiple-stage experiment has as many branches as there are possibilities at that stage. Here there are two main branches for each stage. The total number of terminating points in the tree gives the all possible outcomes and therefore, the end points of a tree may be treated as the sample outcomes of a sample space corresponding to the experiment.

If there are many stages in the experiment and many possibilities at each stage, the tree will become too large to be manageable. For such problems the counting of sample outcomes can be simplified by means of other algebraic formulas.

### 2.4.2 PERMUTATIONS

An ordered arrangement of n different objects taken k at a time is called a permutation of the k objects. If two of the k objects are interchanged in their respective positions, a different permutation results.

$$
{ }_{n} P_{k}=n(n-1) \ldots(n-k+1)=\frac{n!}{(n-k)!} \text { where, } \mathrm{n}_{\mathrm{n}} \text { is called the number of }
$$ permutations of $n$ objects taken $k$ at a time, It is ususlly read " given $n$ objects select $k$ ".

### 2.4.3 COMBINATIONS

An unordered arrangement of $n$ different objects taken $k$ at a time is called a combination of n objects taken k at a time. Thus, if two of the k objects are interchanged in their respective positions, the same combination results.

$$
\binom{n}{k}={ }_{n} C_{k}=\frac{n!}{k!(n-k)!} \text { where, }{ }_{\mathrm{n}} \mathrm{C}_{\mathrm{k}} \text { is called the number of combinations of } \mathrm{n}
$$ objects taken k at a time.

### 2.4.4 PERMUTATIONS WHEN SOME OBJECTS ARE REPEATED

In the preceding sections, it is assumed that all the n objects are different. Sometimes, the n objects contain some similar objects. Now suppose that there are only P different kinds of objects and that there are $k_{1}$ of the first kind, $k_{2}$ of the second kind, and $k_{p}$ of the $p$ th kind, where $\mathrm{k}_{1}+\mathrm{k}_{2}+\ldots+\mathrm{k}_{\mathrm{p}}=\mathrm{n}$.

The total number of different permutations of $\mathbf{n}$ objects is as follows:

$$
\frac{n!}{k_{1}!k_{2}!\ldots k_{p}!}
$$

Example 2. There are four balls, two balls are white and two balls are black. What are the permutations for these four balls ? ( W stands for white ball, and B stands for black ball ).

$$
\frac{4!}{2!\times 2!}=\frac{4 \times 3 \times 2 \times 1}{2 \times 1 \times 2 \times 1}=6
$$

BBWW, BWBW, WBBW, BWWB, WBWB, WWBB

### 2.5 RANDOM VARIABLES AND DENSITY FUNCTION

RANDOM VARIABLE: A random variable is a numerical value determined by the outcome of an experiment. Therefore, a random variable is defined on a sample space.

A sample space that contains a finite number, or an infinite sequence, of outcomes is called discrete sample space, while one that contains one or many intervals of outcomes is called a continuous sample space.

Example 3. Toss a fair coin twice, Let $\mathrm{X}=$ number of heads obtained, where X is a discrete random variable. $S=\{X \mid x=(0,1,2)\}$, where $S$ is a discrete sample space.

Example 4. To measure how long a lightbulb lasts, Let $X=$ time elapsed before bum off, Where X is a continuous random variable. $\mathrm{S}=\{0 \leq x \leq \infty\}$, where $S$ is a continuous sample space.

### 2.5.1 DISCRETE RANDOM VARIABLES

Let $X$ be a discrete random variable. Then the function $f(x)=P(X=x)=$ The probability that the random variable $X$ assumes the value x , and $\mathrm{f}(\mathrm{x})$ is called the discrete density function of X .
$P(X \in R)=\sum_{x \in R} f(x) ; P(S)=\sum_{\text {all } \mathrm{x}} f(x)=1$

Where R is some set of outcomes in the sample space S , and $X \in R$ represents the event that X will assume some values in the set of R values.

The discrete distribution function $\mathrm{F}(\mathrm{x})$ : It is a function closely related to the discrete density function $f(x)$, and is defined as follows:
$F(x)=P(X \leq x)=\sum_{t \leq x} f(t)$, where the summation is over all those values of the random variable that are less than or equal to the specified value x .

The discrete joint density functions: Many experiments involve some random variables rather than one. For simplicity, consider only two discrete random variables X and Y here. A function $f(x, y)$ gives the probability that $X$ will be a specified value $x$ at the same time $Y$
will be a specified value y . This function $\mathrm{f}(\mathrm{x}, \mathrm{y})$ that gives such probabilities is called a discrete joint density function of the two random variables X and Y . It can be written as:
$f(x, y)=P(X=x, Y=y)$

INDEPENDENT RANDOM FUNCTIONS: The random variables $X_{1}, X_{2}, \ldots, X_{n}$ whose joint density function is $f\left(x_{1}, x_{2}, \ldots, x_{n}\right)$ and whose individual density functions are $\mathrm{f}_{1}\left(\mathrm{x}_{1}\right), \mathrm{f}_{2}\left(\mathrm{x}_{2}\right), \ldots, \mathrm{f}_{\mathrm{n}}\left(\mathrm{x}_{\mathrm{n}}\right)$ are said to be independent if and only if $f\left(x_{1}, x_{2}, \ldots, x_{n}\right)=f_{1}\left(x_{1}\right) f_{2}\left(x_{2}\right) \ldots f_{n}\left(x_{n}\right)$. It can be shown that functions of independent random variables are also independent random variables.

### 2.5.2 MARGINAL AND CONDITIONAL DISTRIBUTIONS

Consider a two variable experiment for which a random variable X will assume the value x and the second variable Y will assume the value y .

From the multiplication formula:

$$
P(X \cap Y)=P(X) P(Y / X) \cdots-\cdots(\text { a })
$$

Equation (a) can be expressed in terms of density function. Since $P(X \cap Y)$ gives the probability that the two random variables will assume the valures x and y , respectively, it is equivalent to $f(x, y)$. Similarly, $P(Y / X)$ is equivalent to $f(y / x) ; P(Y)$ is equivalent to $f(y)$, and $P(Y / X)$ is equivalent to $f(y / x)$.

Therefore, equation (a) can be written as:
$f(x, y)=f(x) f(y / x) \cdots(b)$

Since $f(y / x)$ is the conditional probability that $Y$ will assume the value $y$ when $X$ is a fixed value $x$, the sum of $f(y / x)$ over all possible values of $y$ for this fixed value of $x$ must be equal to 1 . Therefore, if both sides of (b) are summed over all possible values of $y$, one can get:

X MARGINAL DENSITY FUNCTION: $f(x)=\sum_{\text {all } y} f(x, y)$

In connection with the joint density function $f(x, y)$, the function $f(x)$ is only the density function of $X$.

Similarly, one can get:

Y MARGINAL DENSITY FUNCTION: $h(y)=\sum_{\text {all } \mathrm{x}} f(x, y)$

These results show that one can get any density function from the joint density function of two random variables and it only sums the joint density function over all values of the other variable.

From equation (b),one can obtain:

CONDITIONAL DENSITY FUNCTION of $Y$ for $X$ given:
$f(y / x)=\frac{f(x, y)}{f(x)}$

In a similar manner, one can obtain:

CONDITIONAL DENSITY FUNCTION of X for Y given:
$f(x / y)=\frac{f(x, y)}{f(y)}$

These results show that, if the joint density function of two random variables is given, the conditional density function can be obtained by dividing the joint density function by the density function of the given variable.

### 2.5.3 CONTINUOUS RANDOM VARIABLES

For a continuous random variable X , its corresponding density function possesses the properties as follows:

$$
\begin{equation*}
f(x) \geq 0 \tag{1}
\end{equation*}
$$

$$
\begin{equation*}
\int_{-\infty}^{\infty} f(x) d x=1 \tag{2}
\end{equation*}
$$

$$
\begin{equation*}
\int_{a}^{b} f(x) d x=P(a \leq x \leq b) \tag{3}
\end{equation*}
$$

$$
\begin{equation*}
f(x, y)=\frac{\partial^{2}}{\partial x \partial y} F(x, y) \tag{4}
\end{equation*}
$$

$$
\begin{equation*}
F(x, y)=\int_{-\infty}^{x} \int_{-\infty}^{y} f(s, t) d s d t \tag{5}
\end{equation*}
$$

Therefore, probabilities for continuous variables are always calculated by integrals, and those for discrete variables are given by sums.

THE DISTRIBUTION FUNCTION $F(x)$ for the continuous variable $X$ is defined by:
$F(x)=P(X \leq x)=\int_{-\infty}^{x} f(t) d t$

Sometimes, it is easier to find the distribution function of a random variable. After the distribution function has been found, the density function can be obtained by differentiating the distribution function. $\frac{d}{d x} F(x)=f(x)$

A density function $f(x, y)$ of two continuous random variables $X$ and $Y$ represents geomet-
rically a surface in three dimensions, just as a density function $f(x)$ of one random variable represents a curve in two dimensions. The integrals of $f(x, y)$ can produce probabilities, and the total volume under this surface should be equal to 1 . Therefore, a joint density function of two continuous random variables X and Y will possess the following properties:

$$
\begin{equation*}
f(x, y) \geq 0 \tag{1}
\end{equation*}
$$

$$
\begin{equation*}
\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) d x d y=1 \tag{2}
\end{equation*}
$$

$$
\begin{equation*}
\int_{a}^{b} \int_{c}^{d} f(x, y) d x d y=P(c<X<d, a<Y<b) \tag{3}
\end{equation*}
$$

If two continuous random variables are unrelated they are said to be independent of each other. The definition of independence is defined by: $f(x, y)=f(x) f(y)$

By using integrals in place of sums, formulas can be derived for marginal and conditional density functions just as in the cases of discrete variables.

X MARGINAL DENSITY FUNCTION: $f(x)=\int_{\text {all } y} f(x, y) d y$

Y MARGINAL DENSITY FUNCTION: $h(y)=\int_{\text {all } \mathbf{x}} f(x, y) d x$

CONDITIONAL DENSITY FUNCTION: $f(y / x)=\frac{f(x, y)}{f(x)}$

CONDITIONAL DENSITY FUNCTION: $f(x / y)=\frac{f(x, y)}{f(y)}$

## CHAPTER 3

## SOME PARTICULAR PROBABLITY DISTRIBUTIONS USED IN RELIABILITY

### 3.1 INTRODUCTION

This chapter will present some properties of the main probability distributions used in reliability. Some distributions are for discrete variables, some are for continuous variables. In each case the probability distribution will be defined by its probability density function. In many problems, it suffices to consider certain low order moments of a distribution rather than to study the entire distribution. Therefore, this chapter will introduce the moments of particular distributions and density functions.

### 3.2 DISCRETE DISTRIBUTIONS

### 3.2.1 EXPECTATION, MOMENT, AND MOMENT GENERATING FUNCTIONS

EXPECTATION: The expected value of the function $h(X)$ of the discrete random variable $X$, whose density is $f(x)$, is defined by:

$$
E[h(X)]=\mu=\sum_{i=1}^{\infty} h\left(x_{i}\right) f\left(x_{i}\right)
$$

The expected value of the random variable is usually called the mean or mean value of the random variable.

MOMENTS:

The $k^{\text {th }}$ moment of the discrete random variable $X$, whose density is $f(x)$ is defined by:
$E\left[X^{k}\right]=\mu_{k}^{\prime}=\sum_{i=1}^{\infty} x_{i}^{k} f\left(x_{i}\right)$

The first moment $\mu_{1}^{\prime}$ will be used so often that it is given a special symbol $\mu$

The $\mathrm{k}^{\text {th }}$ moment about the mean of the distribution of the discrete random variable X whose density function is $f(x)$ is defined by:
$\mu_{k}=E\left[(X-\mu)^{k}\right]=\sum_{i=1}^{\infty}\left(x_{i}-\mu\right)^{k} f\left(x_{i}\right)$

The moments of a distribution are very useful for describing a distribution when the density function is not available.

Usually, only the first two moments are used often to describe two important properties of the distribution. The first moment, $\mu$, is used to determine where is the center of the distribution, and the second moment about mean, $\mu_{2}$, is used to determine the degree of concentration of the distribution about mean. Since the second moment about mean is used so often it is denoted by a special symbol $\sigma^{2}$ and is called the variance of the distribution.

The square root of the variance is called the standard deviation of the distribution and is denoted by symbol $\sigma$.

Sometimes, it is convenient to evaluate variance, $\sigma^{2}$, by evaluating the first two moments about the origin and then calculate $\sigma^{2}$ from them rather then calculate it directly.
$\mu_{2}=\sigma^{2}=E\left[(X-\mu)^{2}\right]=\sum_{i=1}^{\infty}\left(x_{i}-\mu\right)^{2} f\left(x_{i}\right)=\mu_{2}^{\prime}-\mu^{2}$

MOMENT GENERATING FUNCTION:

The moment generating function is a function that can generate moments. The moment generating function of the discrete random variable $X$ whose density function is $f(x)$ is defined by:

$$
\begin{aligned}
& M_{X}(\theta)=E\left[e^{\theta X}\right]=\sum_{i=1}^{\infty} e^{\theta x_{i}} f\left(x_{i}\right)=\sum_{i=1}^{\infty}\left[1+\theta x_{i}+\frac{\theta^{2} x_{i}^{2}}{2!}+\ldots\right] f\left(x_{i}\right) \\
& =\sum_{i=1}^{\infty} f\left(x_{i}\right)+\theta \sum_{i=1}^{\infty} x_{i} f\left(x_{i}\right)+\frac{\theta^{2}}{2!} \sum_{i=1}^{\infty} x_{i}^{2} f\left(x_{i}\right)+\ldots \\
& =1+\theta \mu_{1}^{\prime}+\frac{\theta^{2}}{2!} \mu_{2}^{\prime}+\ldots . \text { This series is a function of parameter } \theta \text { only }
\end{aligned}
$$

If a particular moment is desired, it may be obtained by evaluating the proper derivative of $M_{X}(\theta)$ at $\theta=0$.

$$
\mu_{k}^{\prime}=\left.\frac{d^{k} M}{d \theta^{k}}\right|_{\theta=0}
$$

### 3.2.2SOME ALGEBRA FOR RANDOM VARIABLES

From the basic definitions, it is easy to derive the following relations which are true for a constant c :

$$
\begin{equation*}
E[c X]=c E[X] \tag{1}
\end{equation*}
$$

$$
\begin{equation*}
E[c+X]=c+E[X] \tag{2}
\end{equation*}
$$

$$
\begin{equation*}
\operatorname{VAR}[c X]=c^{2} V A R[X] \tag{3}
\end{equation*}
$$

$$
\begin{equation*}
\operatorname{VAR}[c+X]=\operatorname{VAR}[X] \tag{4}
\end{equation*}
$$

$$
\begin{equation*}
\operatorname{VAR}[X]=E\left[X^{2}\right]-(E[X])^{2} \tag{5}
\end{equation*}
$$

$$
\begin{equation*}
E[X+Y]=E[X]+E[Y] \tag{6}
\end{equation*}
$$

$$
\begin{align*}
& \operatorname{VAR}[X+Y]=\operatorname{VAR}[X]+\operatorname{VAR}[Y]+2\left[\left(X-\mu_{X}\right)\left(Y-\mu_{Y}\right)\right]  \tag{8}\\
& \quad=\operatorname{VAR}[X]+\operatorname{VAR}[Y]+2 \operatorname{COV}[X, Y]
\end{align*}
$$

$$
\begin{equation*}
\rho_{X Y}=\frac{\operatorname{COV}[X, Y]}{\sigma_{X} \sigma_{Y}},-1 \leq \rho_{X Y} \leq 1 \tag{9}
\end{equation*}
$$

$$
\begin{align*}
& \operatorname{VAR}[X-Y]=\operatorname{VAR}[X]+\operatorname{VAR}[Y]-2 \operatorname{COV}[X, Y]  \tag{10}\\
& E[X Y]=E[X] E[Y]+\operatorname{COV}[X, Y] \tag{11}
\end{align*}
$$

When X and Y are non-correlated:

$$
\begin{align*}
& \operatorname{VAR}[X+Y]=\operatorname{VAR}[X]+\operatorname{VAR}[Y]  \tag{12}\\
& E[X-Y]=E[X]-E[Y] \tag{13}
\end{align*}
$$

Where COV[. ] stands for the covariance of $X$ and $Y, \rho_{X Y}$ stands for the correlation coefficient, VAR[. ] stands for variance, and $E[$. $]$ stands for mean. If $\operatorname{Cov}[X, Y]=0$, then $X$ and Y are uncorrelated.Independent must be uncorrelated(inverse not applied).

### 3.2.3BINOMIAL DISTRIBUTION

Consider an experiment which consists of n trials; each trial has only two possible outcomes $(A, \bar{A})$. Let p be the probability of A , and $\mathrm{q}=1-\mathrm{p}$ be the probability of $\bar{A}$. The trials are assumed to be independent so p doesn't change. The discrete random variable X representing the number of occurrences of event $A$ in the $n$ trials is binomially distributed with parameters (p,n):

$$
f(x)=P(X=x)=\frac{n P n}{x!(n-x)!} p^{x} q^{n-x}=\binom{n}{x} p^{x} q^{n-x}, \mathrm{x}=0,1,2, \ldots, \mathrm{n}
$$

The corresponding distribution function is:

$$
F(X)=P(X \leq x)=\sum_{i=0}^{x}\binom{n}{x} p^{x} q^{n-x} \text {,and }
$$

$$
\mu=E[X]=n p ; \operatorname{VAR}[X]=n p q
$$

### 3.2.4POISSON DISTRIBUTION:

Poisson density function is an approximation to the binomal density function. This approxition may be applied when the number of trials is large or the probability $p$ is very small. The probability density function of Poisson distribution is defined as follows:
$f(x)=\frac{e^{-\mu} \mu^{x}}{x!}$

The corresponding distribution function is:

$$
\begin{aligned}
& F(x)=\sum_{i=0}^{x} \frac{e^{-\mu} \mu^{x}}{x!}, \text { and } \\
& E[X]=\mu ; \operatorname{VAR}[X]=\mu
\end{aligned}
$$

### 3.3COUNTINUOUS DISTRIBUTIONS

In this section we will briefly consider some main distributions used in reliability. Since it is necessary to calculate the moments of these distributions, the definition of the $\mathrm{k}^{\text {th }}$ moment of a continuous random variable is discussed first.

### 3.3.1EXPECTION, MOMENT, AND MOMENT GENERATING FUNCTION

EXPECTATION: The expected value of the function $h(X)$ of the continuous random variable $X$, whose density is $f(x)$ is defined by:
$E[h(X)]=\mu=\int_{-\infty}^{\infty} h(x) f(x) d x$

MOMENTS: The $k^{\text {th }}$ moment of the continuous random variable $X$, whose density is $f(x)$ is defined by:
$E\left[X^{k}\right]=\mu_{k}^{\prime}=\int_{-\infty}^{\infty} x^{k} f(x) d x$

The $\mathrm{k}^{\text {th }}$ moment about the mean is defined by:
$E\left[(X-\mu)^{k}\right]=\mu_{k}=\int_{-\infty}^{\infty}(x-\mu)^{k} f(x) d x$

Usually, only the first two moments are used:

$$
\begin{align*}
& \mu_{1}^{\prime}=\mu=E[X]=\int_{-\infty}^{\infty} x f(x) d x  \tag{1}\\
& \mu_{2}=\sigma^{2}=E\left[(X-\mu)^{2}\right]=\int_{-\infty}^{\infty}(x-\mu)^{2} f(x) d x=\mu_{2}^{\prime}-\mu^{2}
\end{align*}
$$

MOMENT GENERATING FUNCTION:
The moment generating function of the continuous random variable X whose density function is $f(x)$ is defined by:
$M_{X}(\theta)=E\left[e^{\theta X}\right]=\int_{-\infty}^{\infty} e^{\theta x} f(x) d x$

SOME MAIN DISTRIBUTIONS USED IN RELIABILITY AND THEIR CORRESPONDING MOMENTS:

DISTRIBUTIONS:DENSITY FUNCTION: MEAN VARIANCE:
$\operatorname{UNIFORM} \quad f(x)=\left\{\begin{array}{c}\frac{1}{(b-a)}, a \leq x \leq b \\ 0, \text { elsewhere }\end{array} \quad \frac{a+b}{2} \quad \frac{1}{3}\left(b^{2}+a b+a^{2}\right)\right.$

NORMAL $f(x)=\frac{1}{\sigma \sqrt{2 \pi}} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^{2}} \quad \mu \quad \sigma^{2}$

GAMMA $\quad f(x)=\frac{x^{\alpha-1} e^{-\left(\frac{x}{\beta}\right)}}{\beta^{\alpha} \Gamma(\alpha)} \quad \beta \alpha \quad \beta^{2} \alpha$
$\operatorname{EXPONENTIAL} f(x)=\frac{e^{-x / \beta}}{\beta} \quad \beta \quad \beta^{2}$
$\operatorname{CHI-SQUARE} f(x)=\frac{x^{\left(\frac{v}{2}-1\right)} e^{-\left(\frac{x}{2}\right)}}{2^{v / 2} \Gamma\left(\frac{v}{2}\right)} \quad v \quad 2 v$
$\operatorname{LOGNORMAL} f(x)=\frac{1}{x \beta \sqrt{2 \pi}} e^{\left[-\frac{1}{2}\left(\frac{\ln x-\lambda}{\beta}\right)^{2}\right]}$ (see section 3.3.7)

### 3.3.2UNIFORM DISTRIBUTION

The uniform distribution is the simplest continuous distribution whose density is a constant over an interval ( $\mathrm{a}, \mathrm{b}$ ) and is zero elsewhere; therefore, its density function can be defined as follows:
$f(x)=\left\{\begin{array}{c}\frac{1}{(b-a)}, a \leq x \leq b \\ 0, \text { elsewhere }\end{array}\right.$

From the moment generating function or direct calculation, its mean value and variance can be obtained:
$\mu=\frac{a+b}{2}$

$$
\sigma^{2}=\frac{1}{3}\left(b^{2}+a b+a^{2}\right)
$$

### 3.3.3NORMAL ( OR GAUSSIAN ) DISTRIBUTION

The normal distribution is symmetrical about the mean $\mu$, and it is usually denoted by $N(\mu, \sigma)$. When its mean value is zero and variance is 1 , the distribution $N(0,1)$ is called a standard normal distribution.

The density function of normal distribution is defined as follows:
$f(x)=\frac{1}{\sigma \sqrt{2 \pi}} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^{2}}$

Therefore, the normal distribution is given by:
$F(x)=\int_{-\infty}^{x} \frac{1}{\sigma \sqrt{2 \pi}} e^{-\frac{1}{2}\left(\frac{t-\mu}{\sigma}\right)^{2}} d t$

Using the moment generating function, the mean value and the variance of the normal distribution can be obtained: mean $=\mu$, variance $=\sigma^{2}$.

Usually, it is convenient to use standard normal distribution instead of normal distribution, because this allows use of standard normal tables for evaluation of probability.

The standard normal density function is defined as follows:
$\varphi(x)=\frac{1}{\sqrt{2 \pi}} e^{-\frac{1}{2} x^{2}}$

Therefore, the standard normal distribution is given by:

$$
\Phi(\beta)=\int_{-\infty}^{\beta} \frac{1}{\sqrt{2 \pi}} e^{-\frac{1}{2} x^{2}} d x
$$

The relationship between normal and standard normal distributions is given by:

$$
F(x)=\Phi(\beta), \text { where } \beta=\frac{x-\mu}{\sigma}
$$

For standard normal distribution, its mean value is equal to zero and standard distribution is equal to 1 .

From the above definitions, it can be shown that a normal (or standard normal) distribution can be completely determined by specifying its mean value and standard deviation.

### 3.3.4GAMMA DISTRIBUTION

The gamma density function is defined by:
$f(x)=\frac{x^{\alpha-1} e^{-\left(\frac{x}{\beta}\right)}}{\beta^{\alpha} \Gamma(\alpha)}$, where $\Gamma(\alpha)=\int_{0}^{\infty} x^{\alpha-1} e^{-x} d x$ is the gamma function.

Therefore, the gamma distribution is given by:
$F(x)=\int_{0}^{x} \frac{t^{\alpha-1} e^{-\left(\frac{t}{\beta}\right)}}{\beta^{\alpha} \Gamma(\alpha)} d t=\frac{1}{\Gamma(\alpha)} \Gamma(\alpha, t / \beta)$, nd
the mean value and variance of gamma distribution are given by:
$\mu=\beta \alpha ; \sigma^{2}=\beta^{2} \alpha$

When parameter $\alpha$ is an integer, it is known as the Erlangian distribution:
$F(t)=1-e^{-t / \beta} \sum_{k=1}^{\alpha} \frac{(t / \beta)^{k-1}}{(k-1)!}$
when $\alpha=1$, the distribution becomes exponential distribution.

### 3.3.5EXPONENTIAL DISTRIBUTION

Exponatial distribution is a special case of gamma distribution, when $\alpha=1$; Its density function is defined by:
$f(x)=\frac{e^{-x / \beta}}{\beta}$

Therefore, the exponential distribution is given by:
$F(x)=\int_{0}^{x} \frac{e^{-t / \beta}}{\beta} d t=1-e^{x / \beta}$,and
mean $=\beta ;$ variance $=\beta^{2}$

### 3.3.6CHI-SQUARE DISTRIBUTION

Chi-square distribution is another special case of gamma distribution, when $\beta=2$ and $\alpha=\frac{v}{2}$, and its density function is defined by:
$f(x)=\frac{x^{\left(\frac{v}{2}-1\right)} e^{-\left(\frac{x}{2}\right)}}{2^{v / 2} \Gamma\left(\frac{v}{2}\right)}$

Therefore, the chi-square distribution is given by:
$F(x)=\int_{0}^{x} \frac{\frac{v}{t^{2}-1} e^{-t / 2}}{2^{v / 2} \Gamma\left(\frac{v}{2}\right)} d t$, and
mean $=v$, variance $=2 v$

### 3.3.7 LOGNORMAL DISTRIBUTION

In this distribution, the natural logrithm of the random variable X has a normal distribution, and the lognormal dendity function is defined by:
$f(x)=\frac{1}{x \beta \sqrt{2 \pi}} e^{\left[-\frac{1}{2}\left(\frac{\ln x-\lambda}{\beta}\right)^{2}\right]}$

Therefore, the lognormal distribution is given by:

$$
F(x)=\int_{-\infty}^{x} f(t) d t=\Phi\left(\frac{\ln x-\lambda}{\beta}\right), \text { where } \lambda=E[\ln X], \beta^{2}=V A R[\ln X]
$$

The mean and variance are given by:

$$
\text { mean }=e^{\left(\lambda+\frac{1}{2} \beta^{2}\right)}, \text { variance }=e^{2\left(\lambda+\frac{1}{2} \beta^{2}\right)}\left(e^{\beta^{2}}-1\right)
$$

The lognormal distribution has this useful property:

$$
P(a<x \leq b)=\Phi\left(\frac{\ln b-\lambda}{\beta}\right)-\Phi\left(\frac{\ln a-\lambda}{\beta}\right) ; \text { This allows use of standard nor- }
$$ mal tables for evaluation of probabilities with $X$ lognormal.

### 3.3.8WEIBULL DISTRIBUTION

Its density function is defined by:
$f(x)=\frac{\lambda}{\beta}\left(\frac{x-\alpha}{\beta}\right)^{\lambda-1} e^{\left(-\left(\frac{x-\alpha}{\beta}\right)^{\lambda}\right)} ; x \geq \alpha$
When $\lambda=1, \alpha=0, f(x)=\frac{1}{\beta} e^{\left(-\frac{x}{\beta}\right)}$. So, exponential distribution is a special case of Weibull distribution.

$$
\text { mean }=\beta \Gamma(1+\lambda)+\alpha ; \text { variance }=\beta^{2}\left(\Gamma\left(\frac{2}{\lambda}+1\right)-\Gamma^{2}\left(1+\frac{1}{\lambda}\right)\right)
$$

# CHAPTER 4 <br> INTRODUCTION TO SYSTEM RELIABILITY 

### 4.1DEFINITIONS

The reliability of a system is its ability to perform a required function, under stated conditions, for a stated period of time. The term reliability is also used to denote a probability of success or a success ratio.

RELIABILITY FUNCTION $\mathrm{R}(\mathrm{t})$ : $\mathrm{P}(\mathrm{S}$ will be operable during the interval $[0, \mathrm{t}]$ ), where $P($.$) stands for probability measure, and S$ stands for system.

AVAILABILITY FUNCTION A(t): $\mathrm{P}(\mathrm{S}$ will be operable at time t ). For non-repairable systems $A(t)=R(t)$.

MAINTAINABILITY FUNCTION M(t): 1-P ( S will not be repaired during the interval $[0, t])$.

MEAN TIME TO FAILURE (MTTF): MTTF $=\int_{0}^{\infty} t f(t) d t=\int_{0}^{\infty} R(t) d t$.

Where $f(t)$ is failure density function;
$f(t)=\frac{d}{d t} F(t)=\frac{d}{d t}(1-R(t))=-\frac{d}{d t} R(t)$

MEAN TIME TO REPAIR (MTTR): MTTR $=\int_{0}^{\infty}(1-M(t)) d t$

### 4.2REPRESENTATION OF SYSTEM LOGIC

Assume that each component has only a finite number of states; Now consider two cases:
(a) The component is normally operating (active) in a system and usually has two states: operating or failure.
(b) The component is normally non-operating (passive) in a system and only begins to operate if the main component fails. (stand-by redundency or auxiliary component).

Representing the logic of a system means representing all the operating and non-operating states of the system and the connections between these various states.

There are three common methods to describe a system:
(1) RELIABILITY BLOCK DIAGRAM: (operating state)

The blocks represent the components,equipments,events,...etc.



Reliability block diagram is a circuitless diagram with input and output points, and the system operates if there exists a path from input point to output point. The list of all successful paths represent all the operating states of the system.
(2) FAULT TREE: (failure state)

The starting point is a single failure event, and the failure tree provides a diagrammatic representation of the event combination resulting in the occurrence of the system failure.

Example 1. There is a system as shown below.Use the fault tree method to represent the logic of the system.



If A or B fails, path 1 fails.
If C or D fails, path 2 fails.
If path 1 and path 2 fail, the sytstem fails.
(3) MINIMAL CUT SETS:

A cut set is a set of failure components, and this set causes the system to be in a failure state. A minimal cut set has the propertiy that a subset of the minimal cut set, which is also a cut set, does not exist.

## HOW TO FIND THE MINIMAL CUT SETS:

(a) Fault tree approach (by Boolean function).

The minimal cut sets (or system failure functions) can be expressed by converting the fault tree to a Boolean expression, associated with each basic event.

Example 2. There is a system as shown below.Now use a Boolean function to express the minimal cut sets.

$F=A+B+C D$. There are three minimal cut sets: $A, B$, and $C D$.

In general, the boolean expression for a failure system can be written as:
$\mathrm{F}=\mathrm{A}_{1}+\mathrm{A}_{2}+\ldots+\mathrm{A}_{i}+\ldots+\mathrm{A}_{n}$, where $\mathrm{A}_{i} \mathrm{c}$ an be the product of some basic events.
(b) Structural function (or operating function).
$x_{i}= \begin{cases}1 \text { if } i^{\text {th }} & \text { component works } \\ 0 \text { if } i^{\text {th }} & \text { component fails }\end{cases}$
$\phi(X)= \begin{cases}1 & \text { if system works } \\ 0 & \text { if system fails }\end{cases}$
$\phi(X)=\phi\left(x_{1}, x_{2}, \ldots, x_{i}, \ldots x_{n}\right)$, where vector $X=\left(x_{1}, x_{2}, \ldots, x_{n}\right)$ is the state of the system.

The structural function has the following properties:
(1) $\phi$ is a nondecreasing function for each variable.
i.e if $x_{1}>x_{2}$ then $\phi\left(x_{1}\right)>\phi\left(x_{2}\right)$ or $\phi\left(x_{1}, y, z\right)>\phi\left(x_{2}, y, z\right)$
(2) $\phi(0,0, \ldots, 0)=0$ If all components fail then the system fails.
(3) $\phi(1,1, \ldots, 1)=1$ If all components work then the system works.

### 4.3ANALYSIS OF SIMPLE SYSTEMS

1. SERIES SYSTEM: $\phi(X)=\prod_{i=1}^{n} x_{i}=\min \left(x_{1}, x_{2}, \ldots x_{n}\right)$. If any component fails then the system fails.
2. PARALLEL SYSTEM: $\phi(X)=1-\prod_{i=1}^{n}\left(1-x_{i}\right)=\max \left(x_{1}, x_{2}, \ldots, x_{3}\right)$.

Any component works then system works.

## COMPUTE STRUCTURE FUNCTION USING MINIMAL PATH:

A path set is a set of non-failure components and this set causes the system to be in a nonfailure state. A minimal path set has the property that a subset of the minimal path set, which is also a path set, doesn't exist.

Suppose $\mathrm{A}_{1}, \mathrm{~A}_{2}, \ldots, \mathrm{~A}_{s}$ are all minimal path sets. The structure function of the $\mathrm{j}^{\text {th }}$ path is: $\alpha_{j}(X)=\min _{i \in A_{j}} x_{i}=\prod_{i \in A_{j}} x_{i}=\left\{\begin{array}{c}1, \text { all component works } \\ 0, \text { otherwise }\end{array}\right.$

The system will function if at least one minimal path works (similar to a parallel system):
$\phi(X)=\underset{1 \leq j \leq s}{=\max _{j}} \alpha_{j}(X)=\max _{1 \leq j \leq\{ } \prod_{i \in A_{j}} x_{i}$

Example 3. Compute the structure function using minimal path method, and the system is shown below:


The minimal path sets are : $\{(1,5),(2,5),(1,3,4),(2,3,4)\}$

Therefore, $\quad \phi(X)=\max \left(x_{1} x_{5}, x_{2} x_{5}, x_{1} x_{3} x_{4}, x_{2} x_{3} x_{4}\right)$

$$
=1-\left(1-x_{1} x_{5}\right)\left(1-x_{2} x_{5}\right)\left(1-x_{1} x_{3} x_{4}\right)\left(1-x_{2} x_{3} x_{4}\right)
$$

## COMPUTE STRUCTURE FUNCTION USING MINIMAL CUT SETS:

Suppose $B_{1}, B_{2}, \ldots, B_{n}$ are all minimal cut sets. The structure function of th $j^{\text {th }}$ cut set is:
$\beta_{j}(X)=\max _{i \in \beta_{j}} x_{i}=\left\{\begin{array}{l}1, \text { if at least one component in } j^{\text {th }} \text { cut is functioning } \\ 0, \text { otherwise (similar to a parallel system) }\end{array}\right.$

The system will be functioning if each cut $\beta_{j}(X)=1$ is functioning, (similar to a series system).

$$
\phi(X)=\min _{1<j<k} \beta_{j}(X)=\prod_{j=1}^{k} \beta_{j}(X)=\prod_{j=1}^{k} \max _{i \in \beta_{j}} x_{i}
$$

Example 4. Compute the structure function using the minimal cut set method, and the system is shown below:


The minimal cut sets are: $\{(1,2),(4,5),(1,3,5),(2,3,4)\}$

$$
\begin{aligned}
& \phi(X)=\max \left(x_{1}, x_{2}\right) \max \left(x_{4}, x_{5}\right) \max \left(x_{1}, x_{3}, x_{5}\right) \max \left(x_{2}, x_{3}, x_{4}\right) \\
& \quad=\left[1-\left(1-x_{1}\right)\left(1-x_{2}\right)\right]\left[1-\left(1-x_{4}\right)\left(1-x_{5}\right)\right] \\
& \quad \times\left[1-\left(1-x_{1}\right)\left(1-x_{3}\right)\left(1-x_{5}\right)\right]\left[1-\left(1-x_{2}\right)\left(1-x_{3}\right)\left(1-x_{5}\right)\right]
\end{aligned}
$$

### 4.4RELIABILITY OF SIMPLE SYSTEMS

Reliabilityfunction
$R(p)=P\{\phi(X=1)\}=E[\phi(X)]=R\left(p_{1}, p_{2}, \ldots, p_{n}\right)$

If $i^{\text {th }}$ component works: $\mathrm{P}\left\{\mathrm{x}_{i}=1\right\}=\mathrm{p}_{i}$
If $\mathrm{i}^{\text {th }}$ component fails: $\mathrm{P}\left\{\mathrm{x}_{i}=0\right\}=1-\mathrm{p}_{i}$
where vector $\mathrm{P}=\left(\mathrm{p}_{1}, \mathrm{p}_{2}, \ldots, \mathrm{p}_{n}\right)$.

$$
\begin{aligned}
& \text { 1.SERIES SYSTEM: } \phi(X)=\min \left(x_{1}, x_{2}, \ldots, x_{n}\right)=\prod_{i=1}^{n} x_{i} \\
& \begin{aligned}
R(p)=P\{\phi(X)=1\}=P\left\{\min \left(x_{1}, x_{2}, \ldots, x_{n}\right)=1\right\}=E[\phi(X)] \\
\quad=P\left\{x_{1}=1, x_{2}=1, \ldots, x_{n}=1\right\}=p_{1} p_{2} p_{3} \ldots p_{n} \\
=\prod_{i=1}^{n} p_{i}=\prod_{i=1}^{n} E\left[x_{i}\right], \text { where } E\left[x_{i}\right]=p_{i} \times 1+\left(1-p_{i}\right) \times 0=p_{i}
\end{aligned}
\end{aligned}
$$

Therefore, the reliability function for series systems is:

$$
R(p)=E[\phi(X)]=E\left[\prod_{i=1}^{n} x_{i}\right]=\prod_{i=1}^{n} E\left[x_{i}\right]=\prod_{i=1}^{n} p_{i}
$$

2. PARALLEL SYSTEM: $\phi(X)=\max \left(x_{1}, x_{2}, \ldots, x_{n}\right)=1-\prod_{i=1}^{n}\left(1-x_{i}\right)$
$R(p)=P\{\phi(X)=1\}=P\left\{\max \left(x_{1}, x_{2}, \ldots, x_{n}\right)=1\right\}$
$=1-P\left\{\min \left(x_{1}, x_{2}, \ldots, x_{n}\right)=0\right\}$
$=1-P\left\{x_{1}=0, x_{2}=0, \ldots, x_{n}=0\right\}$, where components are independent.
$=1-P\left\{x_{1}=0\right\} P\left\{x_{2}=0\right\} \ldots P\left\{x_{n}=0\right\}$
$=1-\left(1-p_{1}\right)\left(1-p_{2}\right) \ldots\left(1-p_{n}\right)=1-\prod_{i=1}^{n}\left(1-p_{i}\right)$

Therefore, the reliability function for parallel systems is:

$$
R(p)=E[\phi(X)]=1-\prod_{i=1}^{n}\left(1-p_{i}\right)
$$

### 4.5RELIABILITY OF DYNAMIC SYSTEMS ( TIME CONSIDERATION )

$\lambda$ and $\mu$ are constants in the static systems, but one should consider time variable in the dynamic system, (see sections 4.6 and 4.7 for details).

RELIABILITY FUNCTION $\mathrm{R}(\mathrm{t})$ : (for non-repair systems)
$R(t)=P\{S$ is functioning in $[0, t]\}=P\{$ lifetime of system $>t$ )
$=1-F(t)=\bar{F}(t),($ tail function $)$
where $\mathrm{F}(\mathrm{t})$ stands for system's life time distribution, and $\mathrm{P}\{$.$\} stands for probability mea-$ sure. At time t , the reliability of $\mathrm{i}^{\text {th }}$ component is $1-F_{i}(t)=\bar{F}_{i}(t)$; therefore, for a non-repair system the reliability function is defined by:
$R(t)=\bar{F}(t)=R\left(\bar{F}_{1}(t), \bar{F}_{2}(t), \ldots, \bar{F}_{n}(t)\right)$
$F(t)=1-\bar{F}(t)=1-R\left(\bar{F}_{1}(t), \bar{F}_{2}(t), \ldots, \bar{F}_{n}(t)\right)$

1. SERIES SYSTEM:

Reliability function: $R(p)=\prod_{i=1}^{n} p_{i}$ (for static systems)

Reliability function: $R(t)=\prod_{i=1}^{n} \bar{F}_{i}(t)=\prod_{i=1}^{n}\left(1-F_{i}(t)\right)$ (for dynamic sys-
tems)

Distribution function
$F(t)=1-R(t)=1-\bar{F}(t)=1-\prod_{i=1}^{n} \bar{F}_{i}(t)=1-\prod_{i=1}^{n}\left(1-F_{i}(t)\right)$
2. PARALLEL SYSTEM:

Reliability function: $R(p)=1-\prod_{i=1}^{n}\left(1-p_{i}\right)$ (for static systems)

Reliability function: $R(t)=1-\prod_{i=1}^{n}\left(1-\bar{F}_{i}(t)\right)=1-\prod_{i=1}^{n} F_{i}(t)$
(for dynamic systems)

Distribution function: $F(t)=1-R(t)=\prod_{i=1}^{n} F_{i}(t)$

### 4.6THE CONCEPT OF FAILURE RATE

Assume that the component works at time $t$, but it will fail after $\Delta t$, then this probability density is called failure rate $\lambda(t)$ :
$P\{X \leq(t+\Delta t) /(X>t)\}=\frac{P\{t<X \leq t+\Delta t\}}{P\{X>t\}}$

$$
=\frac{\int_{t}^{(t+\Delta t)} f(x) d x}{\bar{F}(t)}=\frac{f(t) \Delta t}{\bar{F}(t)}=\lambda(t) \Delta t .
$$

$\lambda(t)=\frac{f(t)}{\bar{F}(t)}=\frac{-\frac{d}{d t} \bar{F}(t)}{\bar{F}(t)}=\frac{-\frac{d}{d t} R(t)}{R(t)}=\frac{f(t)}{R(t)}$

Therefore, failure rate $\lambda(t)$ represents the probability intensity that a t-year-old component will fail.

From the distribution function, one can find the failure rate:
$\lambda(t)=\frac{f(t)}{\bar{F}(t)}, \quad \frac{d}{d t} F(t)=f(t), \quad \bar{F}(t)=1-F(t)$

From the failure rate, one can find the distribution function:
$F(t)=1-e^{-\int_{0}^{t} \lambda(u) d u}, \quad \bar{F}(t)=e^{-\int_{0}^{t} \lambda(u) d u}$

HOW TO CALCULATE THE FAILURE RATE OF A RELIABILITY SYSTEM:

$$
\begin{aligned}
& \bar{F}(t)=R\left(\bar{F}_{1}(t), \ldots, \bar{F}_{n}(t)\right) \\
& F(t)=1-\bar{F}(t)=1-R\left(\bar{F}_{1}(t), \bar{F}_{2}(t), \ldots, \bar{F}_{n}(t)\right)
\end{aligned}
$$

$\lambda(t)=\frac{f(t)}{\bar{F}(t)}=\frac{\frac{d}{d t} F(t)}{\bar{F}(t)}=\frac{-\frac{d}{d t} \bar{F}(t)}{\bar{F}(t)}=\frac{-\frac{d}{d t} R\left(\bar{F}_{1}(t), \ldots, \bar{F}_{n}(t)\right)}{R\left(\bar{F}_{1}(t), \ldots, \bar{F}_{n}(t)\right)}$

## THE FALLURE RATE OF SERIES SYSTEMS:

Assume that the $\mathrm{i}^{\text {th }}$ component's failure rate is $\lambda_{i}(t)$.
$F(t)=1-\bar{F}(t)=1-R\left(\bar{F}_{1}(t), \ldots, \bar{F}_{n}(t)\right)=1-\prod_{i=1}^{n} \bar{F}_{i}(t)$
$=1-\prod_{i=1}^{n} e^{-\int_{0}^{t} \lambda_{i}(t) d t}=1-e^{-\sum_{i=1}^{n} \int_{0}^{t} \lambda_{i}(t) d t}=1-e^{-\int_{0}^{t} \sum_{i=1}^{n} \lambda_{i}(t) d t}$
$\bar{F}(t)=1-F(t)=e^{-\int_{0}^{t} \sum_{i=1}^{n} \lambda_{i}(t) d t}$
$f(t)=\frac{d}{d t} F(t)=e^{-\int_{0}^{t} \sum_{i=1}^{n} \lambda_{i}(t) d t} \sum_{i=1}^{n} \lambda_{i}(t)$
$\lambda(t)=\frac{f(t)}{\bar{F}(t)}=\sum_{i=1}^{n} \lambda_{i}(t)$

Therefore, the failure rate of a series system is equal to the sum of each component's failure rate.

THE FAILURE RATE OF PARALLEL SYSTEMS:

$$
F(t)=1-\bar{F}(t)=1-\left(1-\prod_{i=1}^{n}\left(1-\bar{F}_{i}(t)\right)\right)=1-\left(1-\prod_{i=1}^{n} F_{i}(t)\right)
$$

$$
=\prod_{i=1}^{n} F_{i}(t)=\prod_{i=1}^{n}\left(1-\bar{F}_{i}(t)\right)
$$

$$
F(t)=\prod_{i=1}^{n}\left(1-\bar{F}_{i}(t)\right)=\prod_{i=1}^{n}\left(1-e^{-\int_{0}^{t} \lambda_{i}(u) d t}\right)
$$

From formula:

$$
\prod_{i=1}^{n}\left(1-a_{i}\right)=1-\sum_{i=1}^{n} a_{i}+\sum_{i \neq j} a_{i} a_{j}-\sum_{i \neq j \neq k} a_{i} a_{j} a_{k}+\ldots+(-1)^{n} a_{1} a_{2} \ldots a_{n}
$$

one can obtain: $R(t)=\bar{F}(t)=1-\prod_{i=1}^{n}\left(1-e^{-\int_{0}^{t} \lambda_{i}(u) d u}\right)$

$$
=\sum_{i=1}^{n} e^{-\int_{0}^{t} \lambda_{i}(u) d u}-\sum_{i \neq j} e^{-\int_{0}^{t}\left(\lambda_{i}(u)+\lambda_{j}(u)\right) d u}+\ldots+(-1)^{n} e^{-\int_{0}^{t} \sum_{i=1}^{n} \lambda_{i}(u) d u}
$$

Since $R(t)=\bar{F}(t), \lambda(t)$ is given by:
$\lambda(t)=\frac{-\frac{d}{d t} \bar{F}(t)}{\bar{F}(t)}=\frac{-\frac{d}{d t} \bar{F}(t)}{R(t)}=\frac{-\frac{d}{d t} R(t)}{R(t)}$


The reliability function for a series-parallel system is given by:
$R(t)=\bar{F}(t)=\prod_{i=1}^{p}\left(1-\prod_{j=1}^{n_{i}}\left(1-\bar{F}_{i j}(t)\right)\right)=\prod_{i=1}^{p}\left(1-\prod_{j=1}^{n_{i}} F_{i j}(t)\right)$
where $F_{i j}(t):$ at $\mathrm{i}^{\text {th }}$ stage, the $\mathrm{j}^{\text {th }}$ node's distribution function.

THE RELIABILITY FUNCTION OF A PARALLEL-SERIES SYSTEM:


The reliability function for a parallel-series system is given by:
$R(t)=1-\prod_{i=1}^{p}\left(1-\prod_{j=1}^{n_{i}} \bar{F}_{i j}(t)\right)$
where $F_{i j}(t):$ in $\mathrm{i}^{\text {th }}$ branch, the $\mathrm{j}^{\text {th }}$ component's distribution function, and each $\mathrm{i}^{\text {th }}$ branch has $\mathrm{n}_{i}$ components in series.

### 4.7SYSTEM AVAILABILITY FUNCTION A(t)

When the system is repairable, assume that the system has failed then the repair starts immediately. If the distribution function of repair time is $\mathrm{G}(\mathrm{t})$, the repair rate $\mu(t)$ can be defined by:
$\mu(t)=\frac{\frac{d}{d t} G(t)}{\bar{G}(t)}$
$M T T R=\int_{0}^{\infty}[1-G(t)] d t ; M T T F=\int_{0}^{\infty}[R(t)] d t=\int_{0}^{\infty}[1-F(t)] d t$

In the case, where the repair rate $\mu(t)$ is a constant $\mu$, it can be proved that:

$$
G(t)=1-e^{\mu t} \quad \text { and } \quad M T T R=\frac{1}{\mu}=\tau
$$

If component i has a failure rate $\lambda_{i}$ and a repair rate $\mu_{i}$, it can be proved that:

$$
q_{i}(t)=\frac{\mu_{i}}{\lambda_{i}+\mu_{i}}+\frac{\lambda_{i}}{\lambda_{i}+\mu_{i}} e^{-\left(\lambda_{i}+\mu_{i}\right) t} \text {, and }
$$

$$
\begin{aligned}
A(t) & =R\left(q_{1}(t), q_{2}(t), \ldots, q_{n}(t)\right) \\
& =R\left(\frac{\mu_{1}}{\lambda_{i}+\mu_{1}}+\frac{\lambda_{1}}{\lambda_{1}+\mu_{1}} e^{-\left(\lambda_{1}+\mu_{1}\right) t}, \ldots, \frac{\mu_{n}}{\lambda_{n}+\mu_{n}}+\frac{\lambda_{n}}{\lambda_{n}+\mu_{n}} e^{-\left(\lambda_{n}+\mu_{n}\right) t}\right)
\end{aligned}
$$

where $q_{i}(t)$ is the availability function of component i at time t , and $A(t)$ is the availability function of system $S$ at time $t$.

If $t \rightarrow \infty$ (long run), like a static system, the stationary availability function can be given by: $A(\infty)=R\left(\frac{\mu_{1}}{\lambda_{1}+\mu_{1}}, \ldots, \frac{\mu_{n}}{\lambda_{n}+\mu_{n}}\right)$

SYSTEM AVAILABILITY FUNCTION FOR SERIES SYSTEMS

1. transient: $A(t)=R\left(q_{1}(t), \ldots, q_{n}(t)\right)=\prod_{i=1}^{n} q_{i}(t)$
$=\prod_{i=1}^{n}\left(\frac{\mu_{i}}{\lambda_{i}+\mu_{i}}+\frac{\lambda_{i}}{\lambda_{i}+\mu_{i}} e^{-\left(\lambda_{i}+\mu_{i}\right) t}\right)$
2. stationary: $A(\infty)=\prod_{i=1}^{n} q_{i}(\infty)=\prod_{i=1}^{n}\left(\frac{\mu_{i}}{\lambda_{i}+\mu_{i}}\right)$

## SYSTEM AVAILABILITY FUNCTION FOR PARALLEL SYSTEMS

1. transient: $A(t)=R\left(q_{1}(t), \ldots, q_{n}(t)\right)=1-\prod_{i=1}^{n}\left(1-q_{i}(t)\right)$
$=1-\prod_{i=1}^{n}\left(1-\frac{\mu_{i}}{\lambda_{i}+\mu_{i}}-\frac{\lambda_{i}}{\lambda_{i}+\mu_{i}} e^{-\left(\lambda_{i}+\mu_{i}\right) t}\right)$
$=1-\prod_{i=1}^{n} \frac{\lambda_{i}}{\lambda_{i}+\mu_{i}}\left(1-e^{-\left(\lambda_{i}+\mu_{i}\right) t}\right)$
2. stationary: $A(\infty)=1-\prod_{i=1}^{n} \frac{\lambda_{i}}{\lambda_{i}+\mu_{i}}$

## MINIMAL PATH METHOD FOR SYSTEM AVAILABILITY FUNCTIONS

The following notations are defined as:
$\mathrm{p}_{i}(\mathrm{t})$ : the probability of the $\mathrm{i}^{\mathrm{th}}$ minimal path which is functioning at time t .
n components with availability function $\mathrm{q}_{i}(\mathrm{t}), \mathrm{i}=1, \ldots, \mathrm{n}$.
m possible minimal paths: $\mathrm{p}_{1}, \ldots, \mathrm{p}_{m}$.

$$
\begin{aligned}
& A(t)=P\left\{\bigcup_{i=1}^{m} p_{i}(t)\right\}=\sum_{i=1}^{m} P\left(p_{i}(t)\right)-\sum_{i<j} P\left(p_{i}(t) p_{j}(t)\right) \ldots \ldots . \\
& +(-1)^{m-1} P\left(p_{1}(t), \ldots, p_{m}(t)\right)
\end{aligned}
$$

where $P\left(p_{j}(t)\right)=\prod_{i \in p_{j}} q_{i}(t),($ series in the minimal path $)$.

Example 5. Build up the availability function by the minimal path method, and the system is shown below:


The minimal paths are: $(1,3),(1,4),(2,4),(2,5)$.

$$
\begin{aligned}
& A(t)=P\left\{\bigcup_{i=1}^{4} p_{i}(t)\right\}=\left[q_{1}(t) q_{3}(t)+q_{1}(t) q_{4}(t)+q_{2}(t) q_{4}(t)\right] \\
& +\left[q_{2}(t) q_{5}(t)\right]-\left[q_{1}(t) q_{3}(t) q_{4}(t)\right]-\left[q_{1}(t) q_{2}(t) q_{3}(t) q_{4}(t)\right] \\
& -\left[q_{1}(t) q_{2}(t) q_{3}(t) q_{5}(t)+q_{1}(t) q_{2}(t) q_{4}(t)\right] \\
& -\left[q_{1}(t) q_{2}(t) q_{4}(t) q_{5}(t)+q_{2}(t) q_{4}(t) q_{5}(t)\right] \\
& +\left[q_{1}(t) q_{2}(t) q_{3}(t) q_{4}(t)+q_{1}(t) q_{2}(t) q_{3}(t) q_{4}(t) q_{5}(t)\right] \\
& \quad+\left[q_{1}(t) q_{2}(t) q_{3}(t) q_{4}(t) q_{5}(t)+q_{1}(t) q_{2}(t) q_{4}(t) q_{5}(t)\right] \\
& -\left[q_{1}(t) q_{2}(t) q_{3}(t) q_{4}(t) q_{5}(t)\right]
\end{aligned}
$$

MINIMAL CUT SET METHOD FOR SYSTEM AVAILABILITY FUNCTIONS
$\bar{A}(t)=1-A(t)=P\{$ system is not functioning at time $t\}$.

Assume that a system has $m$ minimal cut sets $\mathrm{c}_{I}, \ldots \mathrm{c}_{m}$

$$
\begin{aligned}
& \bar{A}(t)=\left\{\bigcup_{i=1}^{m} c_{i}(t)\right\}=\sum_{i=1}^{m} P\left(c_{i}(t)\right)-\sum_{i<j} P\left(c_{i}(t) c_{j}(t)\right) \\
& \quad+\sum_{i<j<k} P\left(c_{i}(t) c_{j}(t) c_{k}(t)\right)+\ldots \ldots .+(-1)^{m-1} P\left(c_{1}(t), \ldots, c_{m}(t)\right)
\end{aligned}
$$

where $P\left(c_{i}(t)\right)=\prod_{j \in c_{i}} \bar{q}_{j}(t)=\prod_{j \in c_{i}}\left(1-q_{j}(t)\right)$.

Example 6. Build up the availability function by using the minimal cut set method, and the system is the same as the system in example 5.

The minimal cut sets are: $(1,2),(1,4,5),(2,3,4),(3,4,5)$.

$$
\begin{aligned}
& \bar{A}(t)=\left\{\bigcup_{i=1}^{4} c_{i}(t)\right\}=\left(\bar{q}_{1} \bar{q}_{2}+\bar{q}_{1} \bar{q}_{4} \bar{q}_{5}+\bar{q}_{2} \bar{q}_{3} \bar{q}_{4}+\bar{q}_{3} \bar{q}_{4} \bar{q}_{5}\right)- \\
& \left(\bar{q}_{1} \bar{q}_{2} \bar{q}_{4} \bar{q}_{5}+\bar{q}_{1} \bar{q}_{2} \bar{q}_{3} \bar{q}_{4}+\bar{q}_{1} \bar{q}_{2} \bar{q}_{3} \bar{q}_{4} \bar{q}_{5}+\bar{q}_{1} \bar{q}_{2} \bar{q}_{3} \bar{q}_{4} \bar{q}_{5}\right)- \\
& \left(\bar{q}_{1} \bar{q}_{3} \bar{q}_{4} \bar{q}_{5}+\bar{q}_{2} \bar{q}_{3} \bar{q}_{4} \bar{q}_{5}\right)+\left(\bar{q}_{1} \bar{q}_{2} \bar{q}_{3} \bar{q}_{4} \bar{q}_{5}+\bar{q}_{1} \bar{q}_{2} \bar{q}_{3} \bar{q}_{4} \bar{q}_{5}+\bar{q}_{1} \bar{q}_{2} \bar{q}_{3} \bar{q}_{4} \bar{q}_{5}\right)+ \\
& \left(\bar{q}_{1} \bar{q}_{2} \bar{q}_{3} \bar{q}_{4} \bar{q}_{5}\right)-\left(\bar{q}_{1} \bar{q}_{2} \bar{q}_{3} \bar{q}_{4} \bar{q}_{5}\right) . \text { where } \bar{q}_{i} \text { stands for } \bar{q}_{i}(t), \text { and } i=1,2,3,4,5 .
\end{aligned}
$$

### 4.8DECOMPOSITION OF STRUCTURE FUNCTIONS

Any structure function of order $n$ ( $n$ components) can be written as a linear combination of two structure functions of order $\mathrm{n}-1$ :

$$
\begin{aligned}
& \phi(X)=\phi\left(x_{1}, x_{2}, \ldots, x_{n}\right)=x_{1} \phi\left(1, x_{2}, \ldots, x_{n}\right)+\left(1-x_{1}\right) \phi\left(0, x_{2}, \ldots, x_{n}\right) \\
& \quad=\left[x_{1} x_{2} \phi\left(1,1, x_{3}, \ldots, x_{n}\right)+x_{1}\left(1-x_{2}\right) \phi\left(1,0, x_{3}, \ldots x_{n}\right)\right] \\
& \quad+\left[\left(1-x_{1}\right) x_{2} \phi\left(0,1, x_{3}, \ldots, x_{n}\right)+\left(1-x_{1}\right)\left(1-x_{2}\right) \phi\left(0,0, x_{3}, \ldots, x_{n}\right)\right]
\end{aligned}
$$

DECOMPOSITION FORMULA
$\phi(X)=\phi\left(x_{1}, x_{2}, \ldots, x_{n}\right)=\sum_{Y \in A} \prod_{j=1}^{n} x_{j}^{y_{j}}\left(1-x_{j}\right)^{1-y_{j}}$
where $y_{i}=\left\{\begin{array}{l}1 \\ 0\end{array}\right.$, and A is the set of state $a$ such that $\phi(a)=1$.

Example 7. Build up a structure function by using the decomposition formula, and the system is shown below:


$$
\begin{aligned}
& A=\{(1,1,0),(1,0,1),(1,1,1)\}= \\
& \left\{\left(y_{1}, y_{2}, y_{3}\right),\left(y_{1}, y_{2}, y_{3}\right),\left(y_{1}, y_{2}, y_{3}\right)\right\} . \text { where } \phi(a)=1
\end{aligned}
$$

$$
\begin{aligned}
& \phi(X)=\phi\left(x_{1}, x_{2}, x_{3}\right)=\sum_{Y \in A}\left[x_{1}^{y_{1}}\left(1-x_{1}\right)^{1-y_{1}}\right]\left[x_{2}^{y_{2}}\left(1-x_{2}\right)^{1-y_{2}}\right] \times \\
& {\left[x_{3}^{y_{3}}\left(1-x_{3}\right)^{1-y_{3}}\right]=\left[x_{1}^{1}\left(1-x_{1}\right)^{0}\right]\left[x_{2}^{1}\left(1-x_{2}\right)^{0}\right]\left[x_{3}^{0}\left(1-x_{3}\right)^{1}\right]} \\
& \quad+\left[x_{1}^{1}\left(1-x_{1}\right)^{0}\right]\left[x_{2}^{0}\left(1-x_{2}\right)^{1}\right]\left[x_{3}^{1}\left(1-x_{3}\right)^{0}\right] \\
& \quad+\left[x_{1}^{1}\left(1-x_{1}\right)^{0}\right]\left[x_{2}^{1}\left(1-x_{2}\right)^{0}\right]\left[x_{3}^{1}\left(1-x_{3}\right)^{0}\right] \\
& \quad=x_{1} x_{2}\left(1-x_{3}\right)+x_{1}\left(1-x_{2}\right) x_{3}+x_{1} x_{2} x_{3}=x_{1} x_{2}+x_{1} x_{3}-x_{1} x_{2} x_{3}
\end{aligned}
$$

CHECK: The structure function can also be obtained by the combination of parallel and series systems.

For parallel systems: $\phi(X)=1-\prod_{i=1}^{n}\left(1-x_{i}\right)$
For series systems: $\phi(X)=\prod_{i=1}^{n} x_{i}$

Therefore, $\phi(X)=x_{1}\left[1-\left(1-x_{2}\right)\left(1-x_{3}\right)\right]=x_{1} x_{2}+x_{1} x_{3}-x_{1} x_{2} x_{3}$

### 4.9THE RELIABILITY IMPORTANCE OF A COMPONENT

From the previous sections, the following equations are given:
$\phi(X)=x_{1} \phi\left(1, x_{2}, \ldots, x_{n}\right)+\left(1-x_{1}\right) \phi\left(0, x_{2}, \ldots, x_{n}\right)$
$R(p)=E[\phi(X)]$, when components are independent, $E[X, Y]=E[X] E[Y]$

$$
\begin{aligned}
& R(p)=E[\phi(X)]=E\left[x_{1}\right] E\left[\phi\left(1, x_{2}, \ldots, x_{n}\right)\right]+E\left[\left(1-x_{1}\right)\right] \times \\
& E\left[\phi\left(0, x_{2}, \ldots, x_{n}\right)\right]=p_{1} R\left(1, p_{2}, \ldots, p_{n}\right)+\left(1-p_{1}\right) R\left(0, p_{2}, \ldots, p_{n}\right)
\end{aligned}
$$

The reliability importance of component $i$ is defined as follows:

$$
\begin{aligned}
& I(i)=\frac{\partial}{\partial p_{i}} R(p) \\
& \quad=\frac{\partial}{\partial p_{i}}\left[p_{i} R\left(p_{1}, p_{2}, \ldots, 1, \ldots, p_{n}\right)+\left(1-p_{i}\right) R\left(p_{1}, \ldots, 0, \ldots, p_{n}\right)\right] \\
& \quad=R\left(p_{1}, p_{2}, \ldots, 1, \ldots, p_{n}\right)-R\left(p_{1}, \ldots, 0, \ldots, p_{n}\right) .
\end{aligned}
$$

Therefore, $\frac{\partial}{\partial p_{i}} R(p)=R\left(p_{1}, p_{2}, \ldots, 1, \ldots, p_{n}\right)-R\left(p_{1}, \ldots, 0, \ldots, p_{n}\right)$

SERIES SYSTEM: $R(p)=\prod_{i=1}^{n}\left(1-p_{i}\right)$.

$$
\begin{aligned}
I & (i) \\
& =R\left(p_{1}, p_{2}, \ldots, 1, \ldots, p_{n}\right)-R\left(p_{1}, p_{2}, \ldots, 0, \ldots, p_{n}\right) \\
& =p_{1} p_{2} \cdots p_{i-1} \times 1 \times p_{i+1} \ldots p_{n}-p_{1} p_{2} \ldots p_{i-1} \times 0 \times p_{i+1} \ldots p_{n} \\
& =\prod_{j \neq i}^{n} p_{j} . \text { Therefore, } I(i)=\prod_{j \neq i}^{n} p_{j}
\end{aligned}
$$

PARALLEL SYSTEM: $R(p)=1-\prod_{i=1}^{n}\left(1-p_{i}\right)$

$$
\begin{aligned}
& I(i)=R\left(p_{1}, p_{2}, \ldots, 1, \ldots, p_{n}\right)-R\left(p_{1}, p_{2}, \ldots, 0, \ldots, p_{n}\right) \\
& \quad=\left[1-\prod_{j \neq i}\left(1-p_{j}\right)(1-1)\right]-\left[1-\prod_{j \neq i}\left(1-p_{i}\right)(1-0)\right] \\
& \quad=1-1+\prod_{j \neq i}\left(1-p_{j}\right)=\prod_{j \neq i}^{n}\left(1-p_{j}\right) . \text { Therefore, } I(i)=\prod_{j \neq i}^{n}\left(1-p_{j}\right)
\end{aligned}
$$

Example 8. A system as shown below has three components, and each component's reliability is given $\left(p_{1}=0.5, p_{2}=0.7, p_{3}=0.6\right)$. Find the reliability importance for each component.


$$
\begin{aligned}
& R(p)=p_{1}\left[1-\left(1-p_{2}\right)\left(1-p_{3}\right)\right]=p_{1} p_{2}+p_{1} p_{3}-p_{1} p_{2} p_{3} \\
& I(i)=\frac{\partial}{\partial p_{i}} R(p)=R\left(p_{1}, \ldots, 1, \ldots p_{n}\right)-R\left(p_{1}, \ldots, 0, \ldots p_{n}\right) \\
& I(1)=R(1,0.7,0.6)-R(0,0.7,0.6) \\
& \quad=(1 \times 0.7+1 \times 0.6-1 \times 0.7 \times 0.6)-(0 \times 0.7+0 \times 0.6-0 \times 0.7 \times 0.6) \\
& \quad=1.3-0.42=0.88
\end{aligned}
$$

$$
I(2)=R(0.5,1,0.6)-R(0.5,0,0.6)=(0.5 \times 1+0.5 \times 0.6-0.5 \times 1 \times 0.6)
$$

$$
-(0.5 \times 0+0.5 \times 0.6-0.5 \times 0 \times 0.6)=0.5-0.3=0.2
$$

$$
\begin{aligned}
& I(3)=R(0.5,0.7,1)-R(0.5,0.7,0)=(0.5 \times 0.7+0.5 \times 1-0.5 \times 0.7 \times 1) \\
& -(0.5 \times 0.7+0.5 \times 0-0.5 \times 0.7 \times 0)=0.5-0.35=0.15
\end{aligned}
$$

# CHAPTER 5 <br> SOME BASIC THEORIES OF STRUCTURAL RELIABLITY 

### 5.1INTRODUCTION

The reliability of a structure is its ability to perform its design purpose, under some specified conditions, for a reasonably accepted probability of failure. The reliability of a structure is denoted by R and is defined as $\mathrm{R}=1-\mathrm{P}_{f}$, where $\mathrm{P}_{f}$ is the probability of failure of the structure. Usually, a structure has many possible failure modes; therefore, the first step will usually be to estimate the reliability with respect to each specified failur mode, and then the next step is to estimate the overall reliability of the structure from a system point of view.

With regard to resistance variables it will be assumed that they can be modelled as timeindependent random variables, and load variables can only be modelled as stochastic processes. However, in many cases the distribution of the extreme value of a load in the specified period of time can be used.

### 5.2THE FUNDAMENTAL CASE

In some simple cases the structural reliability is determined by only two independent random variables( a load effect variable $S$ and a resistance variable $R$ ) and one failure criterion $R-S \leq 0$. Such a case is called the fundamental case and is shown in figure (a). In
this fundamental case the probability of failure $P_{f}$ can be calculated as follows. The probability that the load effect $S$ lies in the interval $[x, x+d x]$ is equal to $f_{S}(x) d x$. Failure will occur if resistance $R$ is smaller than $x$, and its probability is $F_{R}(x)$. Therefore, in the inter$\operatorname{val}[x, x+d x]$ the probability of failure is $F_{R}(x) f_{S}(x) d x$.

Therefore, the total probability of failure is:
$P_{f}=\int_{-\infty}^{\infty} F_{R}(x) f_{S}(x) d x$
Figure


In a similar manner, the probability of failure for the fundamental case can also be written as:

$$
P_{f}=\int_{-\infty}^{\infty}\left(1-F_{S}(x)\right) f_{R}(x) d x
$$

Figure (b):


Example 1. There are two independent random variables $R$ and $S$, where $R$ represent $s$ resistance and $S$ represents load effect, and their distributions are shown below. Find the reliability of this sytem.

$f_{S}(t)=a+b t$
$f_{S}(2)=a+2 b=0.5 \ldots-(1)$
$f_{S}(2.5)=a+2.5 b=0$

From (2)-(1), $0.5 b=-0.5, b=-1 ;$ from (1) $a+2(-1)=0.5, a=2.5$
$f_{S}(t)=a+b t=2.5-t$
$f_{R}(t)=a+b t$
$f_{R}(2)=a+2 b=0$
$f_{R}(2.5)=a+2.5 b=0.5$

From (4)-(3), $0.5 b=0.5, b=1$; from (3) $a+2.1=0, a=-2$
$f_{R}(t)=a+b t=-2+t$
$F_{R}(t)=\int_{2}^{t} f_{R}(x) d x=\int_{2}^{t}(-2+x) d x=\frac{1}{2}\left(t^{2}-4 t+4\right), 2 \leq t \leq 2.5$
$f_{S}(t)=2.5-t=\frac{1}{4}(10-4 t), 2 \leq t \leq 2.5$
Therefore, the probability of failure is given by:
$P_{f}=P(R-S \leq 0)=\int_{2}^{2.5} F_{R}(t) f_{S}(t) d t$
$=\int_{2}^{2.5} \frac{1}{2}\left(t^{2}-4 t+4\right) \frac{1}{4}(10-4) t d t=0.0026$
$R=1-P_{f}=1-0.0026=0.9974$

If $R$ and $S$ are independent and normally distributed, the probability of failure can be calculated as following:

Let $M=R-S$, then $M$ is also normally distributed, and
$\mu_{M}=\mu_{R}-\mu_{S}$
$\sigma_{M}^{2}=\sigma_{R}^{2}+\sigma_{S}^{2}$

Therefore,
$P_{f}=P(R-S \leq 0)=P(M \leq 0)=$
$\Phi\left(\frac{0-\mu_{M}}{\sigma_{M}}\right)=\Phi\left(\frac{-\mu_{M}}{\sigma_{M}}\right)=\Phi\left(-\frac{\mu_{R}-\mu_{S}}{\sqrt{\sigma_{R}^{2}+\sigma_{S}^{2}}}\right)=\Phi(-\beta)$
where $\Phi$ stands for the standard normal distribution function, and $M=R-S$ is called the safety margin. $\mu_{M}$ and $\sigma_{M}$ are the mean and standard deviation of $M$.

For the fundamental case the reliability index $\beta$ is defined by:
$\beta=\frac{\mu_{M}}{\sigma_{M}}$

Since, $P_{f}=\Phi(-\beta), \quad \beta=-\Phi^{-1}\left(P_{f}\right)$; Hence, the one-and-one relationship between the probability of failure $P_{f}$ and the reliability index $\beta$ is proven.

Example 2. GIVEN: A simple supported beam loaded as shown below, and

$$
\mu_{Q}=3 \mathrm{KN}, \sigma_{Q}^{2}=1 \mathrm{KN}^{2}, \mu_{R}=10 \mathrm{KNm}, \sigma_{R}^{2}=2.25 \mathrm{KN}^{2} \mathrm{~m}^{2}
$$

FIND: The failure probability of the structure.


Usually,this beam will fail by the maximum bending moment at the midpoint.

$$
\begin{aligned}
& \text { load effect } S=\frac{Q}{2} \frac{L}{2}=\frac{Q}{2} \frac{5}{2}=\frac{5}{4} Q, \text { and } \\
& \mu_{S}=\frac{5}{4} \mu_{Q}=\frac{5}{4} 3=3.75 \mathrm{KNm} \\
& \sigma_{S}^{2}=\left(\frac{5}{4}\right)^{2} \sigma_{Q}^{2}=\frac{25}{16} \times 1=1.56 \mathrm{KN}^{2} \mathrm{~m}^{2} \\
& \mu_{M}=\mu_{R}-\mu_{S}=10-3.75=6.25 \\
& \sigma_{M}^{2}=\sigma_{R}^{2}+\sigma_{S}^{2}=2.25+1.56=3.81 \\
& \beta=\frac{\mu_{M}}{\sigma_{M}}=\frac{6.25}{\sqrt{3.81}}=3.20: P_{f}=\Phi(-3.20)=7 \times 10^{-4} \text { (from the TABLE) }
\end{aligned}
$$

If $R$ and $S$ are correlated and normally distributed, the probability of failure can be calculated as following:
safety margin $M=R-S$

$$
\mu_{M}=\mu_{R}-\mu_{S}
$$

$$
\sigma_{M}^{2}=\sigma_{R}^{2}+\sigma_{S}^{2}-2 \rho \sigma_{R} \sigma_{S}
$$

$$
\beta=\frac{\mu_{M}}{\sigma_{M}}
$$

$$
P_{f}=\Phi(-\beta)
$$

where $\rho$ is the correlation coefficient, which is defined by: $\rho=\frac{\operatorname{Cov}(R, S)}{\sigma_{R} \sigma_{S}}$, and $\operatorname{Cov}(R, S)$ is called the covariance of $R$ and $S$.

### 5.3THE CONCEPT OF FAILURE SURFACES

In evaluating the structural reliability, the first step is usually to identify the variables by which the reliability of the structure can be described. Typically, these variables include material strengths, geometrical quantities, and external loads; These variables are called basic variables and are modelled as random variables or as stochastic processes, but only modelled by random variables are considered here. Therefore, for a given structure each basic variable has a fixed value. A structure usually has a finite number of basic variables.

Assume that all basic variables are normally distributed with the multivariate joint normal density function $f_{\bar{X}}$ defined by:
$f_{\bar{X}}(\bar{x})=\frac{1}{(2 \pi)^{n / 2}|\bar{C}|^{1 / 2}} e^{\left[-\frac{1}{2} \sum_{i, j=1}^{n}\left(x_{i}-\mu_{i}\right) M_{i j}\left(x_{j}-\mu_{j}\right)\right]}$
where $\bar{x}=\left(x_{1}, \ldots, x_{n}\right) ;$ It is convenient to consider the variable $\bar{x}$ as a point in an $n$ dimensional basic variable space $\omega, \bar{M}=\bar{C}^{-1}$, where $\bar{C}$ is the covariance matrix defined by:

$$
\left[\begin{array}{cccc}
\operatorname{Var}\left[X_{1}\right] & \operatorname{Cov}\left[X_{1}, X_{2}\right] & \ldots & \operatorname{Cov}\left[X_{1}, X_{n}\right] \\
\operatorname{Cov}\left[X_{2}, X_{1}\right] & \operatorname{Var}\left[X_{2}\right] & \ldots \operatorname{Cov}\left[X_{2}, X_{n}\right] \\
\ldots & \ldots & \ldots & \ldots \\
\operatorname{Cov}\left[X_{n}, X_{1}\right] \operatorname{Cov}\left[X_{n}, X_{2}\right] & \ldots & \operatorname{Var}\left[X_{n}\right]
\end{array}\right]
$$

Sometimes, basic variables can not be obtained as normal distributions. If this happens a transformation from the non-normal distribution to a normal distribution should be made.

For each failure mode of a given set of basic variables, it is possible to determine whether the structure is in a failure state or in a safe state. In other words, the basic variable space $\omega$ can be divided into two parts called the failure region $\omega_{f}$ and the safe region $\omega_{s}$.The separation of these two parts is called the failure surface and is described by a failure function:
$f(\bar{x})=f\left(x_{1}, \ldots x_{n}\right)=0$
When failure function is positive, this means the structure is in safe region, and when failure function is negative or zero, this means the structure is in failure region, i.e.
$f(\bar{x})>0$, when $\bar{x} \in \omega_{s}$ (safe region).
$f(\bar{x}) \leq 0$, when $\bar{x} \in \omega_{f}$ (failure region).

Note that the same failure surfaces can be represented by many different failure functions, and this means that the failure of a structure can happen in a number of different ways (modes).

The structural reliability can be calculated by:
$R=1-P_{f}=1-\int_{\omega_{f}} f_{\bar{X}}(\bar{x}) d \bar{x}$
where $f_{\bar{X}}(\bar{x})$ is a joint probability density function with n basic variables and the integral is in n-dimension.

Let $f($ ) be a failure function. The safety margin (or failure margin) $M$ can be expressed as $M=f(\bar{x})$; therefore, the safety margin is not unique for a given failure surface.

For example, A failure surface described by two random variables is shown below:


The failure function can be expressed by: $f_{1}(r, s)=r-s$
The corresponding safety margin is: $M_{1}=f_{1}(r, s)=r-s$
The failure function can also be expressed by: $f_{2}(r, s)=(r-s)^{5}$
The corresponding safety margin is: $M_{2}=f_{2}(r, s)=(r-s)^{5}$

When $\mathrm{X}_{i}, \mathrm{i}=1, \ldots, \mathrm{n}$ are normally distributed and uncorrelated variables with a linear safety margin:
$M=R-S=a_{0}+a_{1} X_{1}+\ldots+a_{n} X_{n}$, where $a_{i}, i=1, \ldots n$ are constants.

Therefore,
$\mu_{M}=a_{0}+a_{1} \mu_{X_{1}}+\ldots+a_{n} \mu_{X_{n}}$
$\sigma_{M}^{2}=a_{1}^{2} \sigma_{X_{1}}^{2}+\ldots+a_{n}^{2} \sigma_{X_{n}}^{2}$
The reliability index $\beta$ can be used unchanged: $\beta=\frac{\mu_{M}}{\sigma_{M}}$

When $\mathrm{X}_{i}, \mathrm{i}=1, \ldots, \mathrm{n}$ are normally distribution and correlated variables with a linear safety margin:

$$
M=R-S=a_{0}+a_{1} X_{1}+\ldots+a_{n} X_{n}
$$

Therefore,

$$
\begin{aligned}
& \mu_{M}=a_{0}+a_{1} \mu_{X_{1}}+\ldots+a_{n} \mu_{X_{n}} \\
& \sigma_{M}^{2}=a_{1}^{2} \sigma_{X_{1}}^{2}+\ldots+a_{n}^{2} \sigma_{X_{n}}^{2}+\sum_{i=1}^{n} \sum_{j=1, j \neq i}^{n} \rho_{X_{i} X_{j}} a_{i} a_{j} \sigma_{X_{i}} \sigma_{X_{j}}, \mathrm{OR} \\
& \sigma_{M}^{2}=a_{1}^{2} \sigma_{X_{1}}^{2}+\ldots+a_{n}^{2} \sigma_{X_{n}}^{2}+\sum_{i=1}^{n} \sum_{j=1, j \neq i}^{n} a_{i} a_{j} \operatorname{Cov}\left[X_{i}, X_{j}\right] \\
& \rho_{X_{i} X_{j}}=\frac{\operatorname{Cov}\left[X_{i}, X_{j}\right]}{\sigma_{X_{i} X_{j}}}, i \neq j, \text { and } \beta=\frac{\mu_{M}}{\sigma_{M}} .
\end{aligned}
$$

Example 3. GIVEN: A simply supported beam loaded as shown below. Assume that the beam fails when $|\mathrm{M}| \geq M_{F}$ at midpoint, where $\mathrm{M}_{F}$ is a critical limit moment and M is the bending moment at the midpoint, and the random variables $\bar{X}=\left(P, Q, M_{F}\right)$
with $\mu_{\bar{X}}=\left(30 K N, 20 \frac{K N}{m}, 250 K N m\right)$

$$
\text { and } \bar{C}=\left[\begin{array}{ccc}
9 K N^{2} & 3 \frac{K N^{2}}{m} & 0 \\
3 \frac{K N^{2}}{m} & 6\left(\frac{K N}{m}\right)^{2} & 0 \\
0 & 0 & 50(K N m)^{2}
\end{array}\right]
$$

FIND: calculate the probability of failure for the structure

$$
\begin{aligned}
& |M|=M_{1}+M_{2}=\frac{1}{4} P L+\frac{1}{8} Q L^{2} \\
& M=R-S=a_{0}+a_{1} X_{1}+a_{2} X_{2}+a_{3} X_{3}=M_{F}-|M|=M_{F}-\frac{1}{4} P L-\frac{1}{8} Q L^{2} \\
& =M_{F}-\frac{1}{4} 8 P-\frac{1}{8} 8^{2} Q=-2 P-8 Q+M_{F}
\end{aligned}
$$

Therefore, $a_{0}=0, a_{1}=-2, a_{2}=-8, a_{3}=1$

$$
\mu_{M}=a_{1} \mu_{X_{1}}+a_{2} \mu_{X_{2}}+a_{3} \mu_{X_{3}}=-2 \mu_{P}-8 \mu_{Q}-\mu_{M_{F}}=-2 \times 30-8 \times 20+
$$

$$
250=30
$$

$$
\sigma_{M}^{2}=a_{1}^{2} \sigma_{X_{1}}^{2}+a_{2}^{2} \sigma_{X_{2}}^{2}+a_{3}^{2} \sigma_{X_{3}}^{2}+a_{1} a_{2} \operatorname{Cov}\left[X_{1}, X_{2}\right]
$$

$$
+a_{1} a_{3} \operatorname{Cov}\left[X_{1}, X_{3}\right]+a_{2} a_{1} \operatorname{Cov}\left[X_{2}, X_{1}\right]+a_{2} a_{3} \operatorname{Cov}\left[X_{2}, X_{3}\right]
$$

$$
+a_{3} a_{1} \operatorname{Cov}\left[X_{3}, X_{1}\right]+a_{3} a_{2} \operatorname{Cov}\left[X_{3}, X_{2}\right]
$$

$$
=4 \times 9+64 \times 6+50+16 \times 3+16 \times 3=566
$$

$$
\begin{aligned}
& \sigma_{M}=\sqrt{566}=23.79 \\
& \beta=\frac{\mu_{M}}{\sigma_{M}}=\frac{30}{23.79}=1.26 \\
& P_{f}=\Phi(-\beta)=\Phi(-1.26)=0.1038
\end{aligned}
$$

### 5.4 THE CONCEPT OF LINEARIZATION AND NORMALIZATION

In practice, it is almost impossible to describe a failure surface by a linear failure function; therefore, if the failure surface is hyperplane, then there exists a linear failure function and it should be used in favior of a non-linear failure function because the probability of failure can easily be calculated for a linear function, but is more complex for a non-linear failure function. However, the choice of linearization point should be considered. Let the nonlinear safety margin be given by:
$M=f(\bar{R})=f\left(r_{1}, \ldots, r_{n}\right)$
Expanding M by Taylor series about the linearization point $\bar{r}^{0}=\left(r_{1}^{0}, \ldots, r_{n}^{0}\right)$ and keeping only the linear terms:

$$
M=f(\bar{R}) \cong f\left(\bar{r}^{0}\right)+\sum_{i=1}^{n} \frac{\partial}{\partial r_{i}} f\left(r_{i}-r_{i}^{0}\right)
$$

Therefore, the approximation values for $\mu_{M}$ and $\sigma_{M}$ are given by:

$$
\mu_{M} \cong f\left(\bar{r}^{0}\right)+\sum_{i=1}^{n} \frac{\partial}{\partial r_{i}} f\left(\mu_{r_{i}}-r_{i}^{0}\right)
$$

$\sigma_{M}^{2} \cong \sum_{i=1}^{n} \sum_{j=1}^{n} \frac{\partial}{\partial r_{i}} \frac{\partial}{\partial r_{j}} f \operatorname{Cov}\left[r_{i}, r_{j}\right]$
and $\beta=\frac{\mu_{M}}{\sigma_{M}}$

In a two-dimensional space, a straight line can be expressed by a unit normal vector and a distance from the origin.


$$
\begin{aligned}
& f\left(r_{1}, r_{2}\right)=a r_{1}+b r_{2}+c=\frac{\partial f}{\partial r_{1}} r_{1}+\frac{\partial f}{\partial r_{2}} r_{2}+c, \text { since } a=\frac{\partial f}{\partial r_{1}}, b=\frac{\partial f}{\partial r_{2}} . \\
& \quad=\frac{\frac{\partial f}{\partial r_{1}}}{\sqrt{\frac{\partial f^{2}}{\partial r_{1}}+\frac{\partial f^{2}}{\partial r_{2}}} r_{1}+\frac{\frac{\partial f}{\partial r_{2}}}{\sqrt{\frac{\partial f^{2}}{\partial r_{1}}+\frac{\partial f r^{2}}{\partial r_{2}}} r_{2}+\frac{c}{\sqrt{\frac{\partial f x^{2}}{\partial r_{1}}+\frac{\partial f x^{2}}{\partial r_{2}}}}}} \begin{array}{l}
=\frac{a}{\sqrt{a^{2}+b^{2}}} r_{1}+\frac{b}{\sqrt{a^{2}+b^{2}}} r_{2}+\frac{c}{\sqrt{a^{2}+b^{2}}}
\end{array}
\end{aligned}
$$


distance $\overline{O A}=\frac{c}{\sqrt{\frac{\partial f^{2}}{\partial r_{1}}+\frac{\partial f^{2}}{\partial r_{2}}}}$, or $\frac{c}{\sqrt{a^{2}+b^{2}}}$

Now consider a fundamental case with two independent variables $R$ and $S$ and the safety $\operatorname{margin} \mathrm{M}=\mathrm{R}-\mathrm{S}$; its mean values are $\mu_{R}$ and $\mu_{S}$, and the standard deviations are $\sigma_{R}$ and $\sigma_{S}$.

By using the normalization formula, one can get:
$r_{1}=\frac{R-\mu_{R}}{\sigma_{R}}, R=\sigma_{R} r_{1}+\mu_{R}, \quad$ and $\quad r_{2}=\frac{S-\mu_{S}}{\sigma_{S}}, S=\sigma_{S} r_{2}+\mu_{S}$

The failure function $f(R, S)$ will be transformed into a straight line in the normalized coordinate system $\left(r_{1}, r_{2}\right)$, and then the failure function $f\left(r_{1}, r_{2}\right)$ is given by:

$$
\begin{aligned}
& f(R, S)=R-S=\left(\sigma_{R} r_{1}+\mu_{R}\right)-\left(\sigma_{S} r_{2}+\mu_{S}\right) \\
& \quad=\sigma_{R} r_{1}-\sigma_{S} r_{2}+\left(\mu_{R}-\mu_{S}\right)=0
\end{aligned}
$$

therefore,

$$
f\left(r_{1}, r_{2}\right)=\sigma_{R} r_{1}-\sigma_{S} r_{2}+\left(\mu_{R}-\mu_{S}\right)=0
$$

Therefore, the shortest distance from the origin can be given by:

$$
\frac{\mu_{R}-\mu_{S}}{\sqrt{\sigma_{R}^{2}+\sigma_{S}^{2}}}, \text { and }=\beta
$$

From the geometrical definition, it can be proven that the reliability index $\beta$ is the shortest distance from the origin to the linear failure surface; therefore, the linearization point must be chosen at the reliability index point. The so-called Hasofer and Lind reliability index is defined as the shortest distance from the origin to the failure surface in the normalized coordinate system, and by this definition the reliability index for a non-linear failure surface is equal to the reliability index for the linear tangent hyperplane.

In the general case, a non-linear failure function usually consists of $\mathbf{n}$ basic variables; therefore, the calculation of the reliability index must be done by an iterative method:
$f(\bar{Z})=f(\beta \bar{U}) \Rightarrow f\left(z_{1}, \ldots, z_{n}\right)=f\left(\beta u_{1}, \ldots, \beta u_{n}\right)=0$, and
$u_{i}=-\frac{1}{g} \frac{\partial}{\partial z_{i}}(\beta \bar{U}), i=1, \ldots, n$ and $g=\sqrt{\sum_{j=1}^{n}\left(\frac{\partial f}{\partial z_{j}}(\beta \bar{U})\right)^{2}}$

Example 4. Consider a simply supported beam loaded as shown below, and assume that the beam will fail when $|M| \geq M_{F}$, where $M_{F}$ is the critical bending moment and $M$ is the maximum bending moment. Assume that $P$ and $Q$ are correlated, where $\operatorname{Cov}[P, Q]=0.2 \mathrm{KN}^{2}$, and other random variables are uncorrelated to one another with:

$$
\begin{aligned}
& \mu_{P}=2 K N, \mu_{Q}=15 K N, \mu_{L}=5 m, \mu_{M_{F}}=16 \mathrm{KNm} \\
& \sigma_{P}=0.4 \mathrm{KN}, \sigma_{Q}=3 \mathrm{KN}, \sigma_{L}=0.5 \mathrm{~m}, \sigma_{M_{F}}=3 \mathrm{KNm}
\end{aligned}
$$

Find: the reliability index and its corresponding probability of failure.

$\sum M_{B}=0 \quad R_{C} \times \frac{4}{5} L-P L-Q \frac{2}{5} L=0, \quad R_{C}=\frac{5}{4}\left(P+\frac{2}{5} Q\right)$
$\sum F_{y}=0 \quad R_{C}+R_{B}=P+Q \quad R_{B}=P+Q-R_{C}=\frac{1}{2} Q-\frac{1}{4} P$
From strength of materials, one can expect that the maximum bending moment $M$ will occur at point D .

$$
\begin{aligned}
& M=R_{B} \times \frac{2}{5} L=\frac{1}{10}(2 Q-P) L=\frac{1}{10} L S, \text { where } S=2 Q-P ; \text { therefore, } \\
& \mu_{S}=2 \mu_{Q}-\mu_{P}=2 \times 15-2=28 \\
& \sigma_{S}^{2}=4 \sigma_{Q}^{2}+\sigma_{P}^{2}-2 \times 1 \times 2 \times \operatorname{Cov}[P, Q]=4 \times 9+0.16-4 \times 0.2=35.36 \\
& \sigma_{S}=5.95
\end{aligned}
$$

The failure function can be given by:
$f\left(M_{F}, L, S\right)=M_{F}-\frac{1}{10} L S=0$

The random variables $M_{F}, L$ and $S$ are normalized by

$$
\begin{aligned}
& Z_{1}=\frac{M_{F}-\mu_{M_{F}}}{\sigma_{M_{F}}}, M_{F}=\mu_{M_{F}}+\sigma_{M_{F}} Z_{1}=16+3 Z_{1} \\
& Z_{2}=\frac{L-\mu_{L}}{\sigma_{L}}, L=\mu_{L}+\sigma_{L} Z_{2}=5+0.5 Z_{2} \\
& Z_{3}=\frac{S-\mu_{S}}{\sigma_{S}}, S=\mu_{S}+\sigma_{S} Z_{3}=28+5.95 Z_{3} \\
& M_{F}-\frac{1}{10} L S=\left(16+3 Z_{1}\right)-\frac{1}{10}\left(5+0.5 Z_{2}\right)\left(28+5.95 Z_{3}\right) \\
& \quad=2+3 Z_{1}-1.4 Z_{2}-2.98 Z_{3}-0.3 Z_{2} Z_{3} \\
& \quad=2+3 \beta u_{1}-1.4 \beta u_{2}-2.98 \beta u_{3}-0.3 \beta \beta u_{2} u_{3}=0 \\
& f(\bar{Z})=f(\beta \bar{U})=2+3 \beta u_{1}-1.4 \beta u_{2}-2.98 \beta u_{3}-0.3 \beta \beta u_{2} u_{3}=0 \\
& u_{1}=-\frac{1}{g} 3, u_{2}=\frac{1}{g}\left(1.4+0.3 \beta u_{3}\right), u_{3}=\frac{1}{g}\left(2.98+0.3 \beta u_{2}\right) \\
& g=\sqrt{3^{2}+\left(1.4+0.3 \beta u_{3}\right)^{2}+\left(2.98+0.3 \beta u_{2}\right)^{2}}
\end{aligned}
$$

Therefore, one can obtain:

$$
\begin{aligned}
& \beta=0.446, u_{1}=-0.66, u_{2}=0.33, u_{3}=0.67 \\
& P_{f}=\Phi(-\beta)=\Phi(-0.446)=0.33 \\
& f(\bar{Z})=\beta+u_{1} Z_{1}+u_{2} Z_{2}+u_{3} Z_{3}=0.446-0.66 Z_{1}+0.33 Z_{2}+0.67 Z_{3}
\end{aligned}
$$

When the basic variables $\bar{X}=\left(x_{1}, \ldots, x_{n}\right)$ are correlated and the failure surface is non-linear:

The first step is: to find the uncorrelated variables $\bar{Y}=\left(y_{1}, \ldots, y_{n}\right)$ i.e. to find the eigenvalues and eigenvectors.

The second step is: to normalize these uncorrelated variables and to obtain the normalized and uncorrelated variables $\bar{Z}=\left(z_{1}, \ldots, z_{n}\right)$ by this transformation formula: $z_{i}=\frac{y_{i}-\mu_{y_{i}}}{\sigma_{y_{i}}}, i=1, \ldots, \dot{n}$

The last step is: to find the linear tangent hyperplane to the failure surface of $f(\bar{Z})=0$, and then to solve the probability index $\beta$ value, and $P_{f}=\Phi(-\beta)$

Assume that the covariance matrix of vector $\bar{X}$ is:
$\bar{C}_{\bar{X}}=\left[\begin{array}{cccc}\operatorname{Var}\left[x_{1}\right] & \operatorname{Cov}\left[x_{1}, x_{2}\right] & \ldots & \operatorname{Cov}\left[x_{1}, x_{n}\right] \\ \ldots & \ldots & \ldots & \ldots \\ \operatorname{Cov}\left[x_{n}, x_{1}\right] & \operatorname{Cov}\left[x_{n}, x_{2}\right] & \ldots & \operatorname{Var}\left[x_{n}\right]\end{array}\right]$

By the linear algebra theorems, the transformation from the correlated variables $\bar{X}$ to the uncorrelated variables $\bar{Y}$ can be obtained by:
$\bar{Y}=\bar{A}^{T} \bar{X}$
where $\bar{A}$ is an orthogonal matrix, and each column of $\bar{A}$ is the orthonormal eigenvectors of $\bar{C}_{\bar{X}}$, and $\bar{A}^{T}=A^{-1}$.

Then, the uncorrelated diagonal matrix $\bar{C}_{\bar{Y}}$ can be obtained by:

$$
\bar{C}_{\bar{Y}}=\bar{A}^{T} \bar{C}_{\bar{X}} \bar{A}=\left[\begin{array}{ccc}
\operatorname{Var}\left[y_{1}\right] & \ldots & 0 \\
\ldots & \ldots & \ldots \\
0 & \ldots & \operatorname{Var}\left[y_{n}\right]
\end{array}\right]
$$

Each element in the uncorrelated diagonal matrix $\bar{C}_{\bar{Y}}$ is the eigenvalue of correlated matrix $\bar{C}_{\bar{X}}$ i.e. $\operatorname{Var}\left[y_{i}\right], i=1, \ldots, n$, are equal to the eigenvalues of $\bar{C}_{\bar{X}}$

From $\bar{Y}=\bar{A}^{T} \bar{X}$, one can get:
$E[\bar{Y}]=\bar{A}^{T} E[\bar{X}]$ or $\left[\begin{array}{c}E\left[y_{1}\right] \\ \ldots \\ E\left[y_{n}\right]\end{array}\right]=\bar{A}^{T}\left[\begin{array}{c}E\left[x_{1}\right] \\ \ldots \\ E\left[x_{n}\right]\end{array}\right]$

The transformation form, $z_{i}=\frac{y_{i}-\mu_{y_{i}}}{\sigma_{y_{i}}}, i=1, \ldots, n$ can be written as the vectorial
form: $\bar{Z}=\bar{C}_{\bar{Y}}^{-1 / 2}(\bar{Y}-E[\bar{Y}])$, where $\bar{C}_{\bar{Y}}=\bar{A}^{T} \bar{C}_{\bar{X}} \bar{A}, \bar{Y}=\bar{A}^{T} \bar{X}$, and $E[\bar{Y}]=\bar{A}^{T} E[\bar{X}]$

Therefore, the transformation from the correlated variables $\bar{X}$ to the uncorrelated and normalized variables $\bar{Z}$ can be given by:

$$
\begin{aligned}
\bar{Z} & =\left(\bar{A}^{T} \bar{C}_{\left.\bar{X}^{\bar{A}}\right)}{ }^{-1 / 2}\left(\bar{A}^{T} \bar{X}-\bar{A}^{T} E[\bar{X}]\right)\right. \\
& =\left(\bar{A}^{T} \bar{C}_{\bar{X}^{\bar{A}}}\right)^{-1 / 2} \bar{A}^{T}(\bar{X}-E[\bar{X}])
\end{aligned}
$$

Example 5. Consider a simply supported beam loaded as shown below, and assume that the beam will fail when $|M| \geq M_{F}$, where $M_{F}$ is the critical bending moment and $M$ is the maximum bending moment. Let the basic variables $\bar{X}=\left(P, Q, L, M_{F}\right)$ be given by the mean vector:
$E[\bar{X}]=\left[\mu_{P}, \mu_{Q}, \mu_{L}, \mu_{M_{F}}\right]=\left[2 K N, 1.5 \frac{K N}{m}, 5 m, 3 K N m\right]$
and by the covariance matrix:
$\bar{C}_{\bar{X}}=\left[\begin{array}{cccc}0.16 & 0.1 & 0 & 0 \\ 0.1 & 0.09 & 0 & 0 \\ 0 & 0 & 0.25 & 0 \\ 0 & 0 & 0 & 0.36\end{array}\right]$


From strength of materials, one can find that the maximum bending moment will occur at D, where length $=\frac{L}{3}$ from the right edge.

$$
\begin{aligned}
& \sum M_{B}=0 ; \quad R_{C} \times 4-P \times 5-4 Q \times 2=0 \\
& 4 R_{C}=5 P+8 Q, R_{C}=\frac{5}{4} P+2 Q \\
& \sum F_{y}=0 ; \quad R_{B}=P+4 Q-R_{C}=2 Q-\frac{1}{4} P \\
& |M|=\frac{1}{2} \times \frac{L}{3} \times R_{B}=\frac{1}{6} L\left(2 Q-\frac{1}{4} P\right)=\frac{1}{24} L(8 Q-P)
\end{aligned}
$$

Only P and Q are correlated; therefore, eigenvalues are calculated for the matrix:

$$
\begin{aligned}
& \bar{C}=\left[\begin{array}{cc}
0.16 & 0.1 \\
0.1 & 0.09
\end{array}\right] \\
& \left\lvert\,\left[\begin{array}{cc}
0.16-\lambda & 0.1 \\
0.1 & 0.09-\lambda
\end{array}\right]=0\right. ;(0.16-\lambda)(0.09-\lambda)-0.1 \times 0.1=0 \\
& \lambda_{1}=0.01905, \lambda_{2}=0.2309 \\
& {\left[\begin{array}{cc}
0.16-\lambda & 0.1 \\
0.1 & 0.09-\lambda
\end{array}\right]\left[\begin{array}{l}
x \\
y
\end{array}\right]=\left[\begin{array}{l}
0 \\
0
\end{array}\right]}
\end{aligned}
$$

for $\lambda_{1}=0.01905$, it gives the corresponding orthonormal eigenvector:

$$
\left[\begin{array}{cc}
0.14095 & 0.1 \\
0.1 & 0.07095
\end{array}\right]\left[\begin{array}{l}
x \\
y
\end{array}\right]=\left[\begin{array}{l}
0 \\
0
\end{array}\right] \quad 0.14095 x+0.1 y=0 ; \quad y=-1.4095 x
$$

$$
\left[\begin{array}{l}
x \\
y
\end{array}\right]=\left[\begin{array}{c}
1 \\
-1.4095
\end{array}\right] \Rightarrow\left[\begin{array}{c}
\frac{1}{\sqrt{1^{2}+(-1.4095)^{2}}} \\
-\frac{-1.4095}{\sqrt{1^{2}+(-1.4095)^{2}}}
\end{array}\right]=\left[\begin{array}{c}
0.5786 \\
-0.8156
\end{array}\right]
$$

for $\lambda_{2}=0.2309$, it gives the corresponding orthonormal eigenvector:

$$
\begin{aligned}
& {\left[\begin{array}{cc}
-0.0709 & 0.1 \\
0.1 & -0.1409
\end{array}\right]\left[\begin{array}{l}
x \\
y
\end{array}\right]=\left[\begin{array}{l}
0 \\
0
\end{array}\right] ;-0.0709 x+0.1 y=0, \quad y=0.709 x} \\
& {\left[\begin{array}{l}
x \\
y
\end{array}\right]=\left[\begin{array}{c}
1 \\
0.709
\end{array}\right] \Rightarrow\left[\begin{array}{c}
\frac{1}{\sqrt{1^{2}+0.709^{2}}} \\
\frac{0.709}{\sqrt{1^{2}+0.709^{2}}}
\end{array}\right]=\left[\begin{array}{c}
0.8158 \\
0.5784
\end{array}\right]}
\end{aligned}
$$

Therefore, the transformation matrix $\bar{A}$ is given by:

$$
\bar{A}=\left[\begin{array}{cc}
0.5786 & 0.8158 \\
-0.8156 & 0.5784
\end{array}\right]
$$

and the uncorrelated variables $Y_{1}$ and $Y_{2}$ are given by $\bar{Y}=\bar{A}^{T} \bar{X}$ :

$$
\begin{aligned}
& {\left[\begin{array}{l}
Y_{1} \\
Y_{2}
\end{array}\right]=\left[\begin{array}{cc}
0.5786 & -0.8156 \\
0.8158 & 0.5784
\end{array}\right]\left[\begin{array}{l}
P \\
Q
\end{array}\right]=\left[\begin{array}{cc}
0.5786 P-0.8156 Q \\
0.8158 P+0.5784 Q
\end{array}\right]} \\
& {\left[\begin{array}{l}
P \\
Q
\end{array}\right]=\left[\begin{array}{cc}
0.5786 & -0.8156 \\
0.8158 & 0.5784
\end{array}\right]^{-1}\left[\begin{array}{l}
Y_{1} \\
Y_{2}
\end{array}\right]=\left[\begin{array}{cc}
0.5786 & 0.8158 \\
-0.8156 & 0.5784
\end{array}\right]\left[\begin{array}{l}
Y_{1} \\
Y_{2}
\end{array}\right]}
\end{aligned}
$$

$$
\left[\begin{array}{l}
P \\
Q
\end{array}\right]=\left[\begin{array}{c}
0.5786 Y_{1}+0.8158 Y_{2} \\
-0.8156 Y_{1}+0.5784 Y_{2}
\end{array}\right]
$$

Therefore, the uncorrelated variables are

$$
\bar{Y}=\left[Y_{1}, Y_{2}, Y_{3}, Y_{4}\right]=\left[(0.579 P-0.816 Q),(0.8158 P+0.5784 Q), L, M_{F}\right]
$$

The safety margin

$$
M=M_{F}-|M|=M_{F}-\frac{1}{24} L(8 Q-P)=M_{F}-\frac{1}{3} L Q+\frac{1}{24} L p=0
$$

can be written in uncorrelated variables by

$$
\begin{aligned}
& M=Y_{4}-\frac{1}{3} Y_{3}\left(-0.8156 Y_{1}+0.5784 Y_{2}\right)+\frac{1}{24} Y_{3}\left(0.5786 Y_{1}+0.8158 Y_{2}\right)=0 \\
& M=Y_{4}+0.296 Y_{1} Y_{3}-0.159 Y_{2} Y_{3}=0 \\
& \mu_{Y_{1}}=E\left[Y_{1}\right]=0.5786 \mu_{P}-0.8156 \mu_{Q}=0.5338 \\
& \sigma_{Y_{1}}^{2}=0.5786^{2} \sigma_{P}^{2}+0.8156^{2} \sigma_{Q}^{2}-2 \times 0.5786 \times 0.8156 \times 0.1=0.0191 \\
& \sigma_{Y_{1}}=0.138 \\
& \mu_{Y_{2}}=E\left[Y_{2}\right]=0.8158 \mu_{P}+0.5784 \mu_{Q}=2.4992 \\
& \sigma_{Y_{2}}^{2}=0.8158^{2} \sigma_{P}^{2}+0.5784^{2} \sigma_{Q}^{2}+2 \times 0.8158 \times 0.5784 \times 0.1=0.231 \\
& \sigma_{Y_{2}}=0.4806
\end{aligned}
$$

$$
\begin{aligned}
& Z_{1}=\frac{Y_{1}-\mu_{Y_{1}}}{\sigma_{Y_{1}}}=\frac{Y_{1}-0.5338}{0.138}, \quad Y_{1}=0.138 Z_{1}+0.5338 \\
& Z_{2}=\frac{Y_{2}-\mu_{Y_{2}}}{\sigma_{Y_{2}}}=\frac{Y_{2}-2.4992}{0.4806}, \quad Y_{2}=0.4806 Z_{2}+2.4992 \\
& Z_{3}=\frac{Y_{3}-\mu_{Y_{3}}}{\sigma_{Y_{3}}}=\frac{Y_{3}-5}{0.25}, \quad Y_{3}=0.25 Z_{3}+5 \\
& Z_{4}=\frac{Y_{4}-\mu_{Y_{4}}}{\sigma_{Y_{4}}}=\frac{Y_{4}-3}{0.36}, \quad Y_{4}=0.36 Z_{4}+3 \\
& M=Y_{4}+0.296 Y_{1} Y_{3}-0.159 Y_{2} Y_{3} \\
& =\left(0.36 Z_{4}+3\right)+0.296\left(0.138 Z_{1}+0.5338\right)\left(0.25 Z_{3}+5\right) \\
& -0.159\left(0.4806 Z_{2}+2.4992\right)\left(0.25 Z_{3}+5\right)=0 \\
& M=1.8031+0.2024 Z_{1}-0.3821 Z_{2}-0.0598 Z_{3}+0.36 Z_{4}+0.0102 Z_{1} Z_{3} \\
& -0.0191 Z_{2} Z_{3}=0 \\
& f(\bar{Z})= \\
& 1.8031+0.2024 Z_{1}-0.3821 Z_{2}-0.0598 Z_{3}+0.36 Z_{4}+0.0102 Z_{1} Z_{3} \\
& -0.0191 Z_{2} Z_{3}=0 \\
& f(\bar{Z})=f(\beta \bar{U})=1.8031+0.2042 \beta u_{1}-0.3821 \beta u_{2}-0.0598 \beta u_{3}
\end{aligned}
$$

$$
\begin{aligned}
& +0.36 \beta u_{4}+0.0102 \beta^{2} u_{1} u_{3}-0.0191 \beta^{2} u_{2} u_{3}=0 \\
& \beta=\frac{1.8031}{-0.2042 u_{1}+0.3821 u_{2}+0.0598 u_{3}-0.36 u_{4}-0.01 \beta u_{1} u_{3}+0.0191 \beta u_{2} u_{3}} \\
& u_{1}=-\frac{1}{g} 0.2042 ; u_{2}=\frac{1}{g}\left(0.3821+0.0191 \beta u_{3}\right) \\
& u_{3}=\frac{1}{g}\left(0.0598-0.0102 \beta u_{1}+0.0191 \beta u_{2}\right) ; u_{4}=-\frac{1}{g} 0.36 \\
& g=\sqrt{0.204^{2}+\left(0.382+0.019 \beta u_{3}\right)^{2}+\left(0.06-0.01 \beta u_{1}+0.019 \beta u_{2}\right)^{2}+0.36^{2}}
\end{aligned}
$$

Therefore, one can obtain:

$$
\begin{aligned}
& \beta=3.14, u_{1}=-0.352, u_{2}=0.676, u_{3}=0.196, u_{4}=-0.621 \\
& P_{f}=\Phi(-\beta)=\Phi(-3.14)=0.0008447 \\
& f(\bar{Z})=\beta+u_{1} Z_{1}+u_{2} Z_{2}+u_{3} Z_{3}+u_{4} Z_{4} \\
& f(\bar{Z})=3.41-0.352 Z_{1}+0.676 Z_{2}+0.196 Z_{3}-0.621 Z_{4}
\end{aligned}
$$

# CHAPTER 6 MODELLING OF STRUCTURES 

### 6.1INTRODUCTION

A real structure is so complex that a complete calculation of the failure probability is impossible. Usually, there are a large number of different failure modes so that they cannot all be taken into account; therefore, it is necessary to idealize the structure so that the calculation of the probability of failure becomes manageable, and to build up the model carefully so that the most important failure modes are chosen to reflect the real structure closely. It is assumed that the reliability of a structure is estimated on the basis of a series system modelling, where the components are failure modes, and the failure modes are modelled by parallel systems.

The modelling used in this thesis is based on the assumption that the probability of failure of a structure can be sufficiently accurately estimated by choosing only a finite number of significant failure modes and then by combining them in a complex system. One of the main problems in the structural reliability analysis is to identify the significant failure modes; Several methods to identify the failure modes have been suggested in the last decade, In this thesis Using ANSYS finite element software to accurately identify the failure modes is described in detail. In this thesis only truss structures are considered, but the method used can be extended easily.

### 6.2MODELLING OF FUNDAMENTAL STRUCTURAL SYSTEMS

Two fundamental systems, series systems and parallel systems, will be discussed in this section, and these two fundamental systems occupy the most important parts in the modelling of structural systems.

HOW TO DECIDE A TRUSS STRUCTURE IS STATICALLY DETERMINATE OR STATICALLY INDETERMINATE:

Let $b$ stand for the number of bars, $j$ stand for the number of joints, $r$ stand for the number of reaction components, and e stand for the number of incomplete equilibrium equations. Therefore, for a two-dimensional structure, one may defind:
for a statically determinate structure, $b+r=2 j-e$
for a statically indeterminate structure, $\mathrm{b}+\mathrm{r}>2 \mathrm{j}-\mathrm{e}$
for a mechanism, $b+r<2 j-e$
Since there are $\mathrm{b}+\mathrm{r}$ unknowns, and $2 \mathrm{j}-\mathrm{e}$ equilibrium equations.

In three-dimensional structures. The definition for statical determinacy becomes :
$b+r=3 j-e$

Consider a statically determinate structure with seven bars as shown below. The total number of failure modes is also seven, because for a statically determinate structure the whole structure fails as soon as any structural member fails. This can be symbolized by the series system as shown below:


Let the random variable $R$ be the strength of a series system, and let the random variable $R_{i}$ be the strength of member $i$, where $i=1, \ldots, n$. Let a random load $S$ with the density function $f_{S}$ be loaded on the series system, and result in a load effect $S_{i}$ in menber $i$. Let $F_{R_{i}}$ be the distribution function for the variable $R_{i}$, then the distribution function $F_{R}$ for the total series system is given by:

$$
\begin{aligned}
& F_{R}(S)=P(R \leq S)=1-P(R>S) \\
& \quad=1-P\left[\left(R_{1}>S_{1}\right) \cap\left(R_{2}>S_{2}\right) \cap \ldots \cap\left(R_{n}>S_{n}\right)\right] \\
& \quad=1-\left(1-F_{R_{1}}\left(S_{1}\right)\right)\left(1-F_{R_{2}}\left(S_{2}\right)\right) \ldots\left(1-F_{R_{n}}\left(S_{n}\right)\right) \\
& \quad=1-\prod_{i=1}^{n}\left(1-F_{R_{i}}\left(S_{i}\right)\right)
\end{aligned}
$$

where it is assumed that $R_{i}$ are independent.

Then the probability of failure $P_{f}$ for the series system is given by:

$$
P_{f}=\int_{-\infty}^{\infty} F_{R}(S) f_{S}(S) d S=1-\int_{-\infty}^{\infty} \prod_{i=1}^{n}\left(1-F_{R_{i}}\left(S_{i}\right)\right) f_{S}(S) d S
$$

Therefore, the reliability index for the series system can be calculated by:
$\beta=-\Phi^{-1}\left(P_{f}\right)$

Consider a statically indeterminate structure; Failure in a single bar will not necessarily result in failure of the whole structure. A failure mode can be defined as follows: A set of failure members forms a mechanism which causes the structure to fail, then this set of failure members is called failure mode. Therefore, a failure mode can be represented by a parallel system. In practice, a redundent structure usually has a large number of different failure modes, and each failure mode will be modelled by a parallel system. Therefore, the failure modes (parallel systems) are joined in a series system as shown below:

failure mode n

### 6.3MODELLING OF STRUCTURES

For some structures the reliability of the structure is calculated on the basis of failure of a single component, where the probability of failure of any component and the correlation between them are taken into account, and then all the failure compoonents are combined
to make up the series system. The modelling of this series system is called systems modelling at level 1 as shown:


Usually the probability of failure of structural systems can be estimated with sufficient accuracy only by considering a finite number of significant failure components.

For some structures the reliability of the structure is calculated on the basis of failure of a pair of components, where the probability of failure of any pair of components and the correlation between them are taken into account, and then all the failure pairs are combined to make up the series system. The modelling of this series system is called system modelling at level 2 , where a failure mode is a parallel system with two failure components as shown:


In a same manner system modelling at level $N$, where $N=1,2,3, \ldots$ can be defined.

The most frequently used failure mode of structural systems is a mechanism which is modelled by a parallel system. These mechanisms are then combined in a series system; The modelling of this series system is called system modelling at mechanism level. Usually the number of mechanisms of structures is very large, and it is impossible to consider all possible mechanisms. Therefore, only some reasonable amount of significant mechanisms should be considered.

### 6.4CALCULATION OF THE MULTIVARIATE NORMAL DISTRIBUTION FUNCTION

For a significant pair of failure components, estimation of the bivariate normal distribution function with zero mean values $\Phi_{2}\left(-\beta_{1},-\beta_{2} ; \rho\right)$, where $\rho$ is the correlation coefficient between $\beta_{1}$ and $\beta_{2}$ is given by:

$$
\Phi_{2}\left(-\beta_{1},-\beta_{2} ; \rho\right)=\int_{-\infty}^{\beta_{1}} \int_{-\infty}^{\beta_{2}} \varphi\left(x_{1}, x_{2} ; \rho\right) d x_{1} d x_{2}
$$

where the bivariate normal density function with zero mean values is given by:
$\varphi_{2}\left(x_{1}, x_{2} ; \rho\right)=\frac{1}{2 \pi \sqrt{1-\rho^{2}}} e^{-\frac{1}{2\left(1-\rho^{2}\right)}\left(x_{1}^{2}+x_{2}^{2}-2 \rho x_{1} x_{2}\right)}$

This equation is useful in estimation of the probability of failure for a pair of failure components, where the corresponding safety margins $M_{1}$ and $M_{2}$ are linear.


$$
M_{1}=u_{0}+u_{1} Z_{1}+\ldots+u_{n} Z_{n}
$$

$$
M_{2}=v_{0}+v_{1} Z_{1}+\ldots+v_{n} Z_{n}
$$

where $Z_{i}, i=1, \ldots, n$ are standardized normally distributed and uncorrelated, and $M_{1}$ and $M_{2}$ are also standardized normally distributed with a correlation coefficient $\rho$ :
$\rho=\sum_{i=1}^{n} u_{i} v_{i}$
$\bar{u}=\left(u_{0}, \ldots, u_{n}\right)$ and $\bar{v}=\left(v_{0}, \ldots, v_{n}\right)$ are unit normal vectors, and the correlation coefficient $\rho$ can be written as
$\rho=\cos t$
where $t$ is the angle between the unit vectors $\bar{u}$ and $\bar{v}$. The reliability indices $\beta_{1}$ and $\beta_{2}$ corresponding to the safety margins $M_{1}$ and $M_{2}$ are equal to $u_{0}$ and $v_{0}$.


The probability of failure $P_{f}$ is equal to the intersection area of $M_{1} \leq 0$ and $M_{2} \leq 0$ in the angle $A B C$, and equal to
$P_{f}=\Phi_{2}\left(-\beta_{1},-\beta_{2} ; \rho\right)$

The n-dimensional multivariate standardized normal distribution function $\Phi_{n}$ is definded by
$\Phi_{n}(-\bar{\beta} ; \bar{C})=\int_{-\infty}^{-\beta_{1}} \cdots \int_{-\infty}^{-\beta_{n}} \frac{1}{(2 \pi)^{n / 2} \mid \bar{C}^{1 / 2}} e^{-\frac{1}{2} \sum_{i, j=1}^{n}\left(x_{i}^{T} M_{i j} x_{j}\right)} d x_{1} \ldots d x_{n}$
where $-\bar{\beta}=\left(-\beta_{1}, \ldots,-\beta_{n}\right), \bar{M}=\bar{C}^{-1}$, where $\bar{C}$ is the covariance matrix defined by:

$$
\left[\begin{array}{cccc}
\operatorname{Var}\left[x_{1}\right] & \operatorname{Cov}\left[x_{1}, x_{2}\right] & \ldots & \operatorname{Cov}\left[x_{1}, x_{n}\right] \\
\operatorname{Cov}\left[x_{2}, x_{1}\right] & \operatorname{Var}\left[x_{2}\right] & \ldots & \operatorname{Cov}\left[x_{2}, x_{n}\right] \\
\ldots & \ldots & \ldots & \ldots \\
\operatorname{Cov}\left[x_{n}, x_{1}\right] & \operatorname{Cov}\left[x_{n}, x_{2}\right] & \ldots & \operatorname{Var}\left[x_{n}\right]
\end{array}\right]
$$

In general the calculation of $\Phi_{n}$ for $n \geq 3$ can only be estimated in an approximate way.

Alternatively, $\Phi_{n}$ can be calculated by
$\Phi_{n}(-\bar{\beta} ; \bar{\rho})=\int_{-\infty}^{-\beta} \cdots \int_{-\infty}^{-\beta_{n}} \frac{1}{(2 \pi)^{n / 2}|\bar{\rho}|^{1 / 2}} e^{-\frac{1}{2} \sum_{i, j=1}^{n} x_{i}^{T} M_{i j} x_{j}} d x_{1} \ldots d x_{n}$
where $\bar{M}=\bar{\rho}^{-1}$, and the correlation matrix $\bar{\rho}$ is defined by:

$$
\bar{\rho}=\left[\begin{array}{cccc}
1 & \rho_{12} & \cdots & \rho_{1 n} \\
\rho_{21} & 1 & \ldots & \rho_{2 n} \\
\ldots & \ldots & \cdots & \cdots \\
\rho_{n 1} & \rho_{n 2} & \cdots & 1
\end{array}\right]
$$

# CHAPTER 7 <br> RELIABILITY OF STRUCTURAL SYSTEMS 

### 7.1PROBABILITY OF FAILURE OF SERIES SYSTEMS

It has been suggested that the reliability of a structure be estimated on the basis of a series system modelling, where the components are failure modes, and the failure modes are modelled by parallel systems. Now, consider a simple series system which consists of two failure modes denoted by the safety margins $M_{1}=f_{1}\left(X_{1}, X_{2}\right)$ and $M_{2}=f_{2}\left(X_{1}, X_{2}\right)$

If $F_{i}=\left\{M_{i} \leq 0\right\}=f_{i}\left(X_{1}, X_{2}\right) \leq 0, \quad i=1,2$
Then the probability of failure $P_{f}$ of the series system is given by:

$$
P_{f}=P\left(F_{1} \cup F_{2}\right)=P\left(M_{1} \leq 0 \cup M_{2} \leq 0\right)
$$



The safety margins $M_{1}$ and $M_{2}$ can be linearized in their respective reliability index points $\beta_{1}$ and $\beta_{2}$.
$M_{1}=\beta_{1}+u_{1} X_{1}+u_{2} X_{2}=\beta_{1}+u^{T} \bar{X}$
$M_{2}=\beta_{2}+v_{1} X_{1}+v_{2} X_{2}=\beta_{2}+v^{T} \bar{X}$
where $\bar{u}=\left(u_{1}, u_{2}\right), \bar{v}=\left(v_{1}, v_{2}\right)$ are unit vectors.

Then the approximation of $P_{f}$ can be given by:

$$
\begin{aligned}
P_{f} & \approx P\left(\left(M_{1} \leq 0\right) \cup\left(M_{2} \leq 0\right)\right)=P\left(\left(\beta_{1}+u^{T} \bar{X} \leq 0\right) \cup\left(\beta_{2}+v^{T} \bar{X} \leq 0\right)\right) \\
& =P\left(\left(u^{T} \bar{X} \leq-\beta_{1}\right) \cup\left(v^{T} \bar{X} \leq-\beta_{2}\right)\right) \\
& =1-P\left(\left(u^{T} \bar{X}>-\beta_{1}\right) \cap\left(v^{T} \bar{X}>-\beta_{2}\right)\right)
\end{aligned}
$$

$$
=1-P\left(\left(-u^{T} \bar{X}<\beta_{1}\right) \cap\left(-v^{T} \bar{X}<\beta_{2}\right)\right)=1-\Phi_{2}\left(\beta_{1}, \beta_{2} ; \rho\right)
$$

where $X_{1}$ and $X_{2}$ are independent standard normal variables, and $\rho$ is the correlation coefficient given by:
$\rho=\sum_{i=1}^{n} u_{i} v_{i}=u_{1} v_{1}+u_{2} v_{2}$
$\Phi_{2}$ is the bivariate normal distribution function.

Therefore, the reliability index $\beta$ for the whole series system can be given by:
$\beta=-\Phi^{-1}\left(P_{f}\right) \approx-\Phi^{-1}\left(1-\Phi_{2}\left(\beta_{1}, \beta_{2} ; \rho\right)\right)$

Now, consider a general series system with n components as shown below and let the safety margin for component $i$ be given by:
$M_{i}=f_{i}(\bar{X}), i=1,2, \ldots, n$
where $\bar{X}=\left(X_{1}, X_{2}, \ldots, X_{m}\right)$ are the basic random variables, and $f_{i}$ are non-linear failure functions.


Usually, basic random variables $\bar{X}=\left(X_{1}, \ldots, X_{m}\right)$ are not independent; therefore, one should find out the corresponding uncorrelated variables $\bar{Y}=\left(Y_{1}, \ldots, Y_{m}\right)$ and then find out the corresponding independent standard normal variables
$\bar{Z}=\left(Z_{1}, \ldots, Z_{m}\right)$ (see chapter 5) so that the probability of failure $P_{f_{i}}$ of component i can be evaluated as follows:
$P_{f_{i}}=P\left(M_{i} \leq 0\right)=P\left(f_{i}(\bar{X}) \leq 0\right)=P\left(g_{i}(\bar{Z}) \leq 0\right)$

Then the approximation of $P_{f_{i}}$ can be calculated by linearization of $g_{i}$ at the reliability index $\beta$ point.
$P_{f_{i}} \approx P\left(g_{i}(\bar{Z}) \leq 0\right) \approx P\left(\beta_{i}+\bar{u}_{i}^{T} \bar{Z} \leq 0\right)=P\left(\bar{u}_{i}^{T} \bar{Z} \leq-\beta_{i}\right)=\Phi\left(-\beta_{i}\right)$
where $\bar{u}_{i}$ is the unit vector, $\beta_{i}$ is reliability index, and $\Phi$ is the standard normal distribution function.

Therefore, the approximation of the probability of failure $P_{f}$ of the series system can be estimated as follows:

$$
\begin{aligned}
P_{f} & =P\left(\bigcup_{i=1}^{n}\left(M_{i} \leq 0\right)\right)=P\left(\bigcup_{i=1}^{n}\left(f_{i}(\bar{X}) \leq 0\right)\right)=P\left(\bigcup_{i=1}^{n}\left(g_{i}(\bar{Z}) \leq 0\right)\right) \\
& \approx P\left(\bigcup_{i=1}^{n}\left(\beta_{i}+\bar{u}_{i}^{T} \bar{Z} \leq 0\right)\right)=P\left(\bigcup_{i=1}^{n}\left(\bar{u}_{i}^{T} \bar{Z} \leq-\beta_{i}\right)\right) \\
& =1-P\left(\bigcap_{i=1}^{n}\left(\bar{u}_{i}^{T} \bar{Z}>-\beta_{i}\right)\right)=1-P\left(\bigcap_{i=1}^{n}\left(-\bar{u}_{i}^{T} \bar{Z}<\beta_{i}\right)\right) \\
& =1-\Phi_{n}(\bar{\beta} ; \bar{\rho})
\end{aligned}
$$

where $\bar{\beta}=\left(\beta_{1}, \ldots, \beta_{n}\right)$ is the reliability indices, $\bar{\rho}=\left[\rho_{i j}\right]$ is the correlation matrix, $\rho_{i j}=\bar{u}_{i}^{T} \bar{u}_{j}, \Phi_{n}$ is the n -dimensional standardized normal distribution function.

For a series system the estimate of the probability of failure, $P_{f}=1-\Phi_{n}(\bar{\beta} ; \bar{\rho})$, can be reduced to evaluate $\Phi_{n}$, but for $n \geq 3$ the calculation can only be treated in the approximate method.

Example 1. A structure consists of two bars loaded by a concentrated load P as shown. Assume that the resistance strength in bar 1 is $1 R$, and in bar 2 is $2 R$. Assume that $P$ and $R$ are independent normally distributed random variables, with:

$$
\begin{array}{ll}
\mu_{P}=10 K N & \mu_{R}=10 K N \\
\sigma_{P}=2 K N & \sigma_{R}=1 K N
\end{array}
$$

Calculate the probability of failure of the sturcture.


$$
\begin{aligned}
& \sum F_{y}=0 \\
& S_{1} \sin 45+S_{2} \sin 30-P=0 \\
& \sum F_{x}=0
\end{aligned} \begin{aligned}
& S_{1} \cos 45-S_{2} \cos 30=0
\end{aligned}
$$

By solving these simultaneous equations, one can get:

$$
S_{1}=0.897 P, \quad S_{2}=0.732 P
$$

Therefore, the safety margins can be given by:

$$
\begin{aligned}
& M_{1}=R_{1}-S_{1}=R-0.897 P \\
& M_{2}=R_{2}-S_{2}=2 R-0.732 P \\
& Z_{1}=\frac{R-\mu_{R}}{\sigma_{R}}=\frac{R-10}{1} R=Z_{1}+10 \\
& Z_{2}=\frac{P-\mu_{P}}{\sigma_{P}}=\frac{P-10}{2} P=2 Z_{2}+10 \\
& M_{1}=R-0.897 P=\left(Z_{1}+10\right)-0.897\left(2 Z_{2}+10\right)=Z_{1}-1.794 Z_{2}+1.03 \\
& M_{2}=2 R-0.732 P=2\left(Z_{1}+10\right)-0.732\left(2 Z_{2}+10\right) \\
& \quad=2 Z_{1}-1.464 Z_{2}+12.68 \\
& M_{1}=0.501+0.487 Z_{1}-0.873 Z_{2} \\
& M_{2}=5.12+0.807 Z_{1}-0.591 Z_{2}
\end{aligned}
$$

where $\beta_{1}=0.5$ and $\beta_{2}=5.12$, and the correlation coefficient is

$$
\rho=0.487 \times 0.807+0.873 \times 0.591=0.909
$$

Therefore, the probability of failure of the structure is

$$
P_{f}=1-\Phi_{2}\left(\beta_{1}, \beta_{2} ; \rho\right)=1-\Phi_{2}(0.5,5.12,0.91)
$$

### 7.2APPROXIMATE TECHNIQUES FOR SERIES SYSTEMS

It is very difficult to calculate the value of the multinormal distribution function $\Phi_{n}$, when n is greater than three; therefore, approximate techniques are needed, In this section two bounding methods are introduced.

First, the simple bounds method is suggested by Thoft-Christensen as follows:

$$
\max _{\mathrm{i}=1}^{\mathrm{n}} \Phi\left(-\beta_{i}\right) \leq P_{f} \leq 1-\prod_{i=1}^{n}\left(1-\Phi\left(-\beta_{i}\right)\right)
$$

When safety margins are normally distributed and $\rho \geq 0$, the simple bounds can be used, but when the gap between lower and upper bounds is big this method is rarely used. The lower bound is the exact value of $P_{f}$ when $\rho_{i j}=1$ for all i and j are totally dependent; The upper bound is the exact value of $P_{f}$ when $\rho_{i j}=0$ for all $i \neq j$ are totally independent.

Example 2. Consider the structure of example 1 , the probability of failure $P_{f}$ of the structure is given as: $P_{f}=1-\Phi_{2}\left(\beta_{1}, \beta_{2} ; \rho\right)=1-\Phi_{2}(0.5,5.12 ; 0.91)$. Calculate the probability of failure $P_{f}$ by using the simple bounds method.

$$
\begin{aligned}
& P_{f_{1}}=\Phi\left(-\beta_{1}\right)=\Phi(-0.5)=0.4801 \\
& P_{f_{2}}=\Phi\left(-\beta_{2}\right)=\Phi(-5.12)=1.536 \times 10^{-7}
\end{aligned}
$$

$$
\begin{aligned}
& \max \Phi\left(-\beta_{i}\right)=\Phi(-0.5)=0.4801 \\
& 1-\prod_{i=1}^{n}\left(1-\Phi\left(\beta_{i}\right)\right)=1-\left(1-\Phi\left(-\beta_{1}\right)\right)\left(1-\Phi\left(-\beta_{2}\right)\right) \\
& \quad=1-(1-0.4801)\left(1-1.536 \times 10^{-7}\right)=0.480100079
\end{aligned}
$$

Therefore, the bounds for the probability of failure $P_{f}$ are:
$0.4801 \leq P_{f} \leq 0.480100079$

Second, the Ditlevsen bounds is defined as follows:
upper bound: $P_{f} \leq \sum_{i=1}^{n} \Phi\left(-\beta_{i}\right)-\sum_{i=2, j<i}^{n} \max \Phi_{2}\left(-\beta_{i},-\beta_{j}, \rho\right)$
lower bound: $P_{f} \geq \Phi\left(-\beta_{1}\right)+\sum_{i=2}^{n} \max \left[\Phi\left(-\beta_{i}\right)-\sum_{j=1}^{i-1} \Phi_{2}\left(-\beta_{i},-\beta_{j} ; \rho\right), 0\right]$

Note that ordering is important, where $P\left(-\beta_{1}\right) \geq P\left(-\beta_{2}\right) \geq \ldots \geq P\left(-\beta_{n}\right)$

The gap between the lower bound and upper bound of the Ditlevsen bounds is usually much smaller than the gap between the simple bounds.

Example 3. Consider the structure of example 1 again, the probability of failure $P_{f}$ is given. Now use the Ditlevsen bounds to calculate $P_{f}$ value.

$$
\begin{aligned}
& P_{f}=1-\Phi_{2}\left(\beta_{1}, \beta_{2} ; \rho\right)=1-\Phi_{2}(0.5,5.12 ; 0.91) \\
& P_{f_{1}}=\Phi\left(-\beta_{1}\right)=\Phi(-0.5)=0.4801 \\
& P_{f_{2}}=\Phi\left(-\beta_{2}\right)=\Phi(-5.12)=1.536 \times 10^{-7} \\
& \text { Upper bound: } P_{f} \leq \Phi(-0.5)+\Phi(-5.12)-\Phi_{2}(-5.12,-0.5 ; 0.91) \\
& \quad=0.4801+1.536 \times 10^{-7}-3.4029 \times 10^{-8}=0.480100119 \\
& \text { lower bound: } P_{f} \geq \Phi(-0.5)+\max \left[\Phi(-5.12)-\Phi_{2}(-5.12,-0.5 ; 0.91), 0\right] \\
& \quad=0.4801+1.536 \times 10^{-7}-3.4029 \times 10^{-8}=0.480100119 \\
& 0.480100119 \leq P_{f} \leq 0.480100119
\end{aligned}
$$

### 7.3PROBABILITY OF FAILURE OF PARALLEL SYSTEMS

It has been mentioned several time that the reliability of a structural system is modelled by a series system of parallel systems; Each parallel system represents a failure mode. Then next step is to calculate the probability of failure for each parallel system and the correlation between the parallel systems, and then final step is to calculate the probability of failure of the series system of parallel systems by the methods suggested in previous section.

Consider a simple parallel system( failure mode ) with only two failure components and the safety margins are given by $M_{1}=f_{1}\left(X_{1}, X_{2}\right)$ and $M_{2}=f_{2}\left(X_{1}, X_{2}\right)$, where
$X_{1}$ and $X_{2}$ are independent standard normally distributed random variables. If failure functions $F_{1}=\left(M_{1} \leq 0\right), F_{2}=\left(M_{2} \leq 0\right)$, then the probability of failure $P_{f}$ of the parallel system can be given by:
$P_{f}=P\left(F_{1} \cap F_{2}\right)$

$M_{1}=\beta_{1}+u_{1} X_{1}+u_{2} X_{2}=\beta_{1}+\bar{u}^{T} \bar{X}$
$M_{2}=\beta_{2}+v_{1} X_{1}+v_{2} X_{2}=\beta_{2}+\bar{v}^{T} \bar{X}$
$P_{f} \approx P\left(\left(M_{1} \leq 0\right) \cap\left(M_{2} \leq 0\right)\right)=P\left(\left(\beta_{1}+\bar{u}^{T} \bar{X} \leq 0\right) \cap\left(\beta_{2}+\bar{v}^{T} \bar{X} \leq 0\right)\right)$
$=P\left(\left(\bar{u}^{T} \bar{X} \leq-\beta_{1}\right) \cap\left(\bar{v}^{T} \bar{X} \leq-\beta_{2}\right)\right)=\Phi_{2}\left(-\beta_{1},-\beta_{2} ; \rho\right)$
where $\rho$ the correlation coefficient is given by:
$\rho=\sum_{i} u_{i} b_{i}=\bar{u}^{T} \bar{v}=u_{1} v_{1}+u_{2} v_{2}$
$\Phi_{2}$ is the bivariate normal distribution function.

Therefore, the reliability index $\beta$ for the parallel system can be obtained by:

$$
\beta=-\left(\Phi^{-1}\left(P_{f}\right) \approx-\Phi^{-1}\left(-\beta_{1},-\beta_{2} ; \rho\right)\right)
$$

The formula derived above can be generalized to a general form where the parallel system has n failure components and where the number of basic varibales is m . Let the safety margin for component i be given by:
$M_{i}=f_{i}(\bar{X}), i=1,2, \ldots, n$
where $\bar{X}=\left(X_{1}, \ldots, X_{m}\right)$ are basic variables and where $f_{i}$ are non-linear functions.


The probability of failure $P_{f_{i}}$ of component i can be derived as before (see section 7.1) so that

$$
P_{f_{i}}=P\left(M_{i} \leq 0\right)=P\left(f_{i}(\bar{X}) \leq 0\right)=P\left(g_{i}(\bar{Z}) \leq 0\right)
$$

where the basic variables $\bar{X}=\left(X_{1}, \ldots, X_{m}\right)$ are transformed into independent standard normal variables $\bar{Z}=\left(Z_{1}, \ldots, Z_{m}\right)$.

The approximation of $P_{f_{i}}$ can be estimated by linearizing $g_{i}$ in the reliability index point $\beta_{i}$

$$
P_{f_{i}}=P\left(g_{i}(\bar{Z}) \leq 0\right) \approx P\left(\beta_{i}+\bar{u}_{i}^{T} \bar{Z} \leq 0\right)=P\left(\bar{u}_{i}^{T} \bar{Z} \leq-\beta_{i}\right)=\Phi\left(-\beta_{i}\right)
$$

where $\bar{u}_{i}$ is the unit normal vector, $\beta_{i}$ is the reliability index, and $\Phi$ is the standard normal distribution function.

Therefore, an approximation of the probability of failure $P_{f}$ for the general parallel system can then be estimated as follows:

$$
\begin{aligned}
P_{f} & =P\left(\bigcap_{i=1}^{n}\left(M_{i} \leq 0\right)\right)=P\left(\bigcap_{i=1}^{n}\left(f_{i}(\bar{X}) \leq 0\right)\right)=P\left(\bigcap_{i=1}^{n}\left(g_{i}(\bar{Z}) \leq 0\right)\right) \\
& \approx P\left(\bigcap_{i=1}^{n}\left(\beta_{i}+\bar{u}_{i}^{T} \bar{Z} \leq 0\right)\right)=P\left(\bigcap_{i=1}^{n}\left(\bar{u}_{i}^{T} \bar{Z} \leq-\beta_{i}\right)\right)=\Phi_{n}(-\bar{\beta} ; \bar{\rho})
\end{aligned}
$$

where $\bar{\beta}=\left(\beta_{1}, \ldots, \beta_{n}\right)$ and $\bar{\rho}=\left[\rho_{i j}\right]$ is the correlation matrix for the linearized safety margins, i.e. $\rho_{i j}=\sum_{i=j=1}^{m} \bar{u}_{i} \bar{u}_{j}=\bar{u}_{i} \bar{u}_{j} . \Phi_{n}$ is n-dimensional standardized normal distribution function.

From the formula $P_{f}=\Phi_{n}(-\bar{\beta} ; \bar{\rho})$, the estimation of the probability of failure of a parallel system with linear and normally distributed safety margins is reduced to estimate $\Phi_{n}$. However, as mentioned before, estimation of $\Phi_{n}$ for $n$ greater than three can only be treated in an approximate approach.

### 7.4APPROXIMATE TECHNIQUES FOR PARALLEL SYSTEMS

Since it is difficult to calculate the multinormal distribution function $\Phi_{n}$ directly, approximate methods must be considered.

The simple bounds is suggested by Thoft-Christensen as follows:
$\prod_{i=1}^{n} \Phi\left(-\beta_{i}\right) \leq P_{f} \leq \min _{\mathrm{i}=1}^{\mathrm{n}} \Phi\left(-\beta_{i}\right)$

The lower bound is the exact value of $P_{f}$ when $\rho_{i j}=0(i \neq j)$ are totally independent;
The upper bound is the exact value of $P_{f}$ when $\rho_{i j}=1$ (for all $i$ and $j$ ) are totally dependent.

The modified simple bounds is introduced by Murotsu as follows:

$$
\prod_{i=1}^{n} \Phi\left(-\beta_{i}\right) \leq P_{f} \leq \min _{i, j=1}^{n} \Phi_{2}\left(-\beta_{i},-\beta_{j} ; \rho_{i j}\right)
$$

The Hohenbichler approximation:

$$
\Phi_{n}(\bar{\beta} ; \bar{\rho}) \approx \Phi\left(\beta_{1}\right) \Phi_{n-1}\left(\bar{\beta}_{(2)}^{e} ; \bar{\rho}_{(2)}\right)
$$

where the equivalent reliability index $\bar{\beta}_{i}^{e}$ is definde by:
$\beta_{i}^{e}=\left.\beta_{i}^{e}(\bar{\varepsilon})\right|_{\bar{\varepsilon}=0}=-\left.\Phi^{-1}\left(P\left(f_{i}(\bar{Z}+\bar{\varepsilon}) \leq 0\right)\right)\right|_{\bar{\varepsilon}=\overline{0}}$,where
$\bar{Z}=\left(Z_{1}, \ldots, Z_{n}\right)$ are standard normal independent variables, and the corresponding $\bar{u}_{i}^{e}$ unit vector is definde by:

$$
u_{i j}^{e}=\frac{\left.\frac{\partial}{\partial \varepsilon_{j}} \beta_{i}^{e}\right|_{\bar{\varepsilon}=\overline{0}}}{\sqrt{\sum_{l=1}^{n}\left(\left.\frac{\partial}{\partial \varepsilon_{l}} \beta_{i}^{e}\right|_{\bar{\varepsilon}=\overline{0}}\right)}} j=1,2, \ldots, n
$$

where $\beta_{(2) i}^{e}=-\beta_{i}^{e}, i=1, \ldots, n$ and $\rho_{(2) k l}=\bar{u}_{k}^{e^{T}} \bar{u}_{l}^{e}$, where
$\bar{u}_{k}^{e^{T}}=\left(u_{k 1}^{e}, \ldots, u_{k n}^{e}\right), k=2, \ldots, n$

Therefore, the calculation of $\Phi_{n}$ has been reduced to calculation of $\Phi_{n-1}$. By repeating the same procedure, it gives the following approximation:
$\Phi_{n}(\bar{\beta} ; \bar{\rho})=\Phi\left(\beta_{1}\right) \Phi\left(\beta_{2(2)}^{e}\right) \ldots \Phi\left(\beta_{(n) n}^{e}\right)$

When a parallel system (failure mode) consists of only two failure components the bounds for $\Phi_{2}\left(-\beta_{1},-\beta_{2} ; \rho\right)$ have been derived by Thoft-Christensen :
for $\rho>0 \quad \max \left(P_{1}, P_{2}\right) \leq \Phi_{2}\left(-\beta_{1},-\beta_{2}, \rho\right) \leq P_{1}+P_{2}$
for $\rho \leq 0 \quad 0 \leq \Phi_{2}\left(-\beta_{1}-\beta_{2} ; \rho\right) \leq \min \left(P_{1}, P_{2}\right)$

$$
\begin{aligned}
& \text { where } P_{1}=\Phi\left(-\beta_{2}\right) \Phi\left(-\frac{\beta_{1}-\rho \beta_{2}}{\sqrt{1-\rho^{2}}}\right) \\
& P_{2}=\Phi\left(-\beta_{1}\right) \Phi\left(-\frac{\beta_{2}-\rho \beta_{1}}{\sqrt{1-\rho^{2}}}\right)
\end{aligned}
$$

### 7.5EQUIVALENT LINEAR SAFETY MARGIN FOR PARALLEL SYSTEMS

From the previous section the probability of failure $P_{f}$ of the parallel system can be represented by: $P_{f}=\Phi_{n}(-\bar{\beta} ; \bar{\rho})$
where $\bar{\beta}=\left(\beta_{1}, \ldots, \beta_{n}\right)$ are the reliability indices of the failure components, and $\bar{\rho}$ is the correlation matrix.

When the reliability of a structural system is modelled by a series system of parallel systems, the reliability of the structure can be estimated by the following steps:
(1) calculate the probability of failure for each parallel system.
(2) calculate the correlationship between the parallel systems.
calculate the probability of failure of the series system.

Consider a parallel system (failure mode) with n components and the safety margin for element $\mathrm{i}, \mathrm{i}=1, \ldots, \mathrm{n}$ is linear as follows:
$M_{i}=\beta_{i}+u_{i 1} Z_{1}+\ldots+u_{i m} Z_{m}=\beta_{i}+\sum_{j=1}^{m} u_{i j} Z_{j}$
where the basic variables $Z_{i}, i=1, \ldots, m$ are independent standard normal variables, $\bar{u}_{i}=\left(u_{i 1}, \ldots, u_{i m}\right)$ is a unit normal vector, and where $\beta_{i}$ is the reliability index.

Therefore, the reliability index $\beta$ for the parallel system can be obtained by:
$\beta=-\Phi^{-1}\left(\Phi_{n}(-\bar{\beta} ; \bar{\rho})\right)$

The reliability index $\beta^{e}$ of the equivalent linear safety margin $M^{e}$ is equal to the reliability index $\beta$ of the parallel system so that the equivalent linear safety margin $M^{e}$ has the same sensitivity as the parallel system when the basic variables change.

Let the basic variables $\bar{Z}=\left(Z_{1}, \ldots, Z_{m}\right)$ increase by a small amount $\bar{\varepsilon}=\left(\varepsilon_{1}, \ldots, \varepsilon_{m}\right)$. The corresponding reliability index $\beta(\bar{\varepsilon})$ of the parallel system becomes:

$$
\begin{aligned}
& \left.\beta(\bar{\varepsilon})=-\Phi\left(P\left(\bigcap_{i=1}^{n}\left(\sum_{j=1}^{m} \beta_{i}+u_{i j}\left(Z_{j}+\varepsilon_{j}\right) \leq 0\right)\right)\right)\right) \\
& \quad=-\Phi\left(P\left(\bigcap_{i=1}^{n}\left(\sum_{j=1}^{m} u_{i j} Z_{j} \leq-\beta_{i}-u_{i j} \varepsilon_{j}\right)\right)\right) \\
& \quad=-\Phi^{-1}\left(\Phi_{n}(-\bar{\beta}-\bar{u} \bar{\varepsilon} ; \bar{\rho})\right)
\end{aligned}
$$

The equivalent linear safety margin $M^{e}$ is defined by:
$M^{e}=\beta^{e}+u_{1}^{e} Z_{1}+\ldots+u_{m}^{e} Z_{m}=\beta^{e}+\sum_{j=1}^{m} u_{j}^{e} Z_{j}$
where $\beta^{e}=\beta$. By the same increase $\bar{\varepsilon}$ in the basic variables $Z_{i}, i=1, \ldots, m$ the reliability index $\beta^{e}(\bar{\varepsilon})$ becomes:

$$
\beta^{e}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi\left(-\beta^{e}-\bar{u}^{e^{T}} \bar{\varepsilon}\right)\right)=\beta^{e}+\bar{u}^{-} \bar{\varepsilon}=\beta^{e}+u_{1}^{e} \varepsilon_{1}+\ldots+u_{1}^{e} \varepsilon_{m}
$$

Let $\beta(\overline{0})=\beta^{e}(\overline{0})$, one can get:
$u_{i}^{e}=\frac{\left.\frac{\partial \beta}{\partial \varepsilon_{i}}\right|_{\bar{\varepsilon}=\overline{0}}}{\left.\sqrt{\sum_{j=1}^{n}\left(\left.\frac{\partial \beta}{\partial \varepsilon_{j}}\right|_{\bar{\varepsilon}=\overline{0}}\right.}\right)^{2}}, i=1, \ldots, m$

Example 4. Assume that a parallel system (failure mode) consists of two failure components and the safety margins of the failure coimponents are given by:

$$
\left.M_{1}=3.0-0.3 Z_{1}+0.954 Z_{2}=3.5-0.866 Z_{1}+0.5 Z_{2}-\begin{array}{c}
M_{1} \\
M_{2}
\end{array}\right] \Rightarrow M^{e}
$$

where $Z_{1}$ and $Z_{2}$ are independent standard normal variables.

The reliability index $\beta$ of the parallel system is :

$$
\begin{aligned}
& \Phi(-\beta)=\Phi_{2}(-3.0,-3.5 ; 0.74)=0.00008491 ; \beta=3.76 \\
& \beta=-\Phi^{-1}(-3.0,3.5 ; 0.74)=3.76 \\
& \text { let } \varepsilon_{i}=0.1, i=1,2 . \text { for } \bar{\varepsilon}=(0.1,0) \text { one gets: } \\
& -\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{l}
-3.0 \\
-3.5
\end{array}\right]-\left[\begin{array}{cc}
-0.3 & 0.954 \\
-0.866 & 0.5
\end{array}\right]\left[\begin{array}{c}
0.1 \\
0
\end{array}\right]=\left[\begin{array}{l}
-2.97 \\
-3.14
\end{array}\right] \\
& \beta(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-2.97,-3.14 ; 0.74)\right)=3.53 \\
& \text { for } \bar{\varepsilon}=(0,0.1) \\
& \bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{l}
-3.0 \\
-3.5
\end{array}\right]-\left[\begin{array}{cc}
-0.3 & 0.954 \\
0.866 & 0.5
\end{array}\right]\left[\begin{array}{c}
0 \\
0.1
\end{array}\right]=\left[\begin{array}{l}
-3.1 \\
-3.55
\end{array}\right] \\
& \beta(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi \Phi_{2}(-3.1,-3.55 ; 0.74)\right)=3.98
\end{aligned}
$$

Therefore,

$$
\left.\frac{\partial \beta}{\partial \varepsilon_{1}}\right|_{\bar{\varepsilon}=\overline{0}} \approx \frac{\beta(\bar{\varepsilon})-\beta}{\varepsilon_{1}}=\frac{3.53-3.76}{0.1}=-2.3
$$

$$
\left.\frac{\partial \beta}{\partial \varepsilon_{2}}\right|_{\bar{\varepsilon}=\overline{0}}=\frac{3.98-3.76}{0.1}=2.2
$$

By normalizing

$$
\bar{u}^{e}=\left(u_{1}^{e}, u_{2}^{e}\right)=\left(\frac{-2.3}{\sqrt{(-2.3)^{2}+2.2^{2}}}, \frac{2.2}{\sqrt{(-2.3)^{2}+2.2^{2}}}\right)=(-0.7226,0.6912)
$$

Then the equivalent safety margin is given by:

$$
M^{e}=\beta^{e}+u_{1}^{e} Z_{1}+u_{2}^{e} Z_{2}=3.76-0.7226 Z_{1}+0.6912 Z_{2}
$$

# CHAPTER 8 <br> GENERATION OF SAFETY MARGINS BY ANSYS 

### 8.1INTRODUCTION

A real structure usually has many different modes of failure, In order to estimate the structural reliability, these failure modes and their corresponding safety margins must be given. For a simple structure the safety margins can be built up by hand calculation. In the conventional analysis, the structural safety margins are built up by using the principle of virtual work, but in practice, for a complex structure with large redundancy it is difficult to derive the safety margins by using the principle of virtual work. However, in this chapter, we show how to use ANSYS (a finite element software produced by Swanson Analysis Systems, Inc.) to derive the failure modes and their corresponding safety margins in detail.

### 8.2THE THEORY OF GENERATION OF SAFETY MARGINS

Consider a structure with n bars. A bar will fail if the internal force exceeds the strength of the bar. The safety margin is determined by the difference between the strength of material and the internal force: $M_{i}=R_{i}-S_{i}$
where $M_{i}$ is the safety margin of the $i^{t h}$ bar, $R_{i}$ is the strength capacity of the $i^{t h}$ bar, and $S_{i}$ is the internal force of the $i^{t h}$ bar.

The strength capacity $R_{i}$ is given by specifying the material, and the internal force $S_{i}$ can be evaluated by ANSYS finite element software.

Let $\bar{f}_{i}$ and $\bar{\delta}_{i}$ represent the nodal force vector and displacement vector of the $i^{\text {th }}$ bar in the local coordinate system as shown below:


The stiffness equation of bar $i$ is given by:
$\bar{f}_{i}=\bar{k}_{i} \bar{\delta}_{i}$
where $\bar{f}_{i}=\left(F_{x_{i}}^{R}, F_{y_{i}}^{R}, F_{z_{i}}^{R}, F_{x_{i}}^{L}, F_{y_{i}}^{L}, F_{z_{i}}^{L}\right), \bar{\delta}_{i}=\left(l_{x_{i}}^{R}, l_{y_{i}}^{R}, l_{z_{i}}^{R}, l_{x_{i}}^{L}, l_{y_{i}}^{L}, l_{z_{i}}^{L}\right)$

Since $\sigma=E \varepsilon, \frac{F}{A}=E \frac{\Delta l}{l}, F=\frac{A E}{l} \Delta l=\frac{A E}{l} \delta=k \delta$,
nodal forces: $F_{x_{i}}^{L}=\frac{A_{i} E_{i}}{l_{i}}\left(\delta^{L}{ }_{x_{i}}-\delta^{R}{ }_{y_{i}}\right), F_{x_{i}}^{R}=\frac{A_{i} E_{i}}{l_{i}}\left(\delta^{R}{ }_{x_{i}}-\delta_{y_{i}}^{L}\right)$
$\bar{f}_{i}=\bar{k}_{i} \bar{\delta}_{i}$ can be written as the matrix form:
$\left[\begin{array}{r}F_{x_{i}}^{L} \\ F_{i}^{L} \\ y_{i} \\ F_{z_{i}}^{L} \\ F_{x_{i}}^{R} \\ F_{i}^{R} \\ y_{i} \\ F_{2}^{R} \\ z_{i}\end{array}\right]=\frac{A_{i} E_{i}}{l_{i}}\left[\begin{array}{cccccccc}1 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0\end{array}\right]\left[\begin{array}{c}l_{x_{i}}^{L} \\ l_{2}^{L} \\ y_{i} \\ l_{2} \\ z_{i} \\ R \\ l_{x_{i}} \\ l_{y_{i}}^{R} \\ l_{2}^{R} \\ z_{i}\end{array}\right]$
where $A_{i}$ is the cross area, $E_{i}$ is the Young's modulus, $l_{i}$ is the length of bar $i$.

Therefore, the stiffness matrix of bar $i$ is given by:

$$
\bar{k}_{i}=\frac{A_{i} E_{i}}{l_{i}}\left[\begin{array}{cccccc}
1 & 0 & 0 & -1 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 \\
-1 & 0 & 0 & 1 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0
\end{array}\right]
$$

The displacement and nodal force vectors can be transformed into the global coordinate system by the transformation matrix $\bar{T}_{i}$.
$\bar{\delta}_{i}=\bar{T}_{i} \bar{d}_{i} ; \bar{d}_{i}=\bar{T}_{i}^{-1} \bar{\delta}_{i}$
$\bar{f}_{i}=\bar{T}_{i} \bar{F}_{i} ; \bar{F}_{i}=\bar{T}_{i}^{1} \bar{f}_{i}$
where $\bar{d}_{i}$ and $\bar{F}_{i}$ are the displacement and nodal force vectors of bar i in the global coordinate system.

Therefore, the stiffness equation of bar i in the global coordinate system can be written as:
$\bar{F}_{i}=\bar{K}_{i} \bar{d}_{i}$
$\bar{F}_{i}=\bar{T}_{i}^{-1} \bar{f}_{i}=\bar{T}_{i}^{-1} \bar{k}_{i} \bar{\delta}_{i}=\bar{T}_{i}^{-1} \bar{k}_{i} \bar{T}_{i} \bar{d}_{i}=\bar{K}_{i} \bar{d}_{i}$
where $\bar{K}_{i}=\bar{T}_{i}^{-1} \bar{k}_{i} \bar{T}_{i}=\bar{T}_{i}^{T} \bar{k}_{i} \bar{T}_{i}$

In the similar manner the stiffness equations of other bars can be formed, and then the global nodal displacement vector $\bar{d}$ is formed by arranging the individual displacement vectors $\bar{d}_{i}$, and the global nodal force vector $\bar{F}$ is also formed by the individual nodal vectors $\bar{f}_{i}$, Furthermore, the whole structural stiffness matrix $\bar{K}$ is constructed by superposing the individual stiffness matrices.

Therefore, the total structure stiffness equation can be given by $\bar{F}=\bar{K} \bar{d}$

The nodal force $\bar{f}_{i}$ in the local coordinate system is related to $\bar{F}_{i}$ in the global coordinate system; therefore, the nodal force $\bar{f}_{i}$ can be solved as follows:
$\bar{f}_{i}=\bar{T}_{i} \bar{F}_{i}=\bar{T}_{i} \bar{K}_{i} \bar{d}_{i}=\bar{T}_{i}\left(\widehat{T}_{i}^{1} \bar{k}_{i} \bar{T}_{i}\right) \bar{K}_{i}^{-1} \bar{F}=\left(\bar{k}_{i} \bar{T}_{i} \bar{K}_{i}^{1}\right) \bar{F}=\bar{A}_{i} \bar{F}$
where $\bar{A}_{i}=\bar{k}_{i} \bar{T}_{i} \bar{K}_{i}^{-1}$, and $\bar{K}_{i}^{1}$ is a submatrix of $\bar{K}^{-1}$ corresponding to the $i^{\text {th }}$ bar.

For a truss structure the local internal force is equal to the local axial force
$S_{i}=F_{x_{i}}^{R}=-F_{x_{i}}^{L}$, and it can be written as: $S_{i}=\sum_{j=1}^{n} a_{i j} F_{j}$
where $a_{i j}$ is the element of matrix $\bar{A}_{i}$ referred to $S_{i}$ and $F_{j}$.

Therefore, the safety margin of the $i^{\text {th }}$ bar can be defined by

$$
M_{i}=R_{i}-S_{i}=R_{i}-\sum_{j=1}^{n} a_{i j} F_{j}
$$

When the bar fails in tension or compression, the yield stress is taken into account, and when the bar is instable in compression, the bucking stress is considered.

For a statically determinate structure, the structure will fail, if any bar of the structure fails. For a statically indeterminate structure, the structure will not necessarily fail if any bar of the structure fails, and the failure will occure only after the structure becomes a mechanism. Failure modes will be produced by the following method. When any one bar fails, the internal forces will be redistributed among the survival bars and a bar next to fail is found. After any bar failed, the residual strength $R_{i}$ is applied as an artificial force at the corresponding nodes, and its individual local stiffness matrix is set to zero. Repeating the same procedure, structural failure occurs when the failed bars reach some specified number q. A mechanism will be formed if the determinant of the total structure stiffness matrix
$\bar{K}^{(n-q)}$ becomes singular. That is
$\left|\bar{K}^{(n-q)}\right|=0$
where $n-q$ is the number of surviving bars.

The safety margins of the surviving bars after some bars failed can be defined as follows:
$S_{i}^{n-q}=\sum_{j=1}^{n} a_{i j}^{(n-q)} F_{j}^{(n-q)}=\sum_{j=1}^{n} a_{i j}^{(n-q)} F_{j}-b_{i r_{1}}^{(n-q)} R_{r_{1}}-$
$b_{i r_{2}}^{(n-q)} R_{r_{2}}-\ldots-b_{i r_{q}}^{(n-q)} R_{r_{q}}$
where $b_{i j}^{(n-q)}$ are the coefficients of influence and where suffix $\left(r_{1}, r_{2}, \ldots, r_{q}\right)$ denote the failed bars. Therefore, the safety margins are defined by:
$M_{i}^{n-q} \equiv R_{i}-S_{i}^{n-q}$, where $i=(1,2, \ldots, n-q-1)$.

Therefore, a structural failure criterion for a statically indeterminate(redundant) truss can be defined as:

$$
M_{i}^{n-q} \leq 0
$$

### 8.3GENERATION OF SAFETY MARGINS <br> USING ANSYS

Usually each bar can fail in two different forms, namely in tension or in compression. Let $\mathrm{R}_{i}{ }^{+}$and $\mathrm{R}_{i}{ }^{-}$represent the strength capacity in tension and in compression for bar i and let
$S_{i}$ represent the load effect of bar $i$. Then the following two safety margins are described:
$M_{i}{ }^{+}=R_{i}{ }^{+}-S_{i}$ tension load effect
$M_{i}^{-}=R_{i}^{-}+S_{i}$ compression load effect

Therefore, the corresponding safety margin $M_{i}$ is determined by:
$M_{i}=\min \left(R_{i}{ }^{+}-S_{i}, R_{i}^{-}+S_{i}\right)$

Example 1. Consider a statically determinate truss structure as shown below. Assume that the strength capacities for compression and tension are same $R_{i}{ }^{+}=R_{i}^{-}$. Calculate the safety margins of the total structure.

The ANSYS PROGRAMS and the corresponding results are listed in the appendixes A, A 1 , and A2.

figure a
$b+r=2 j-e \Rightarrow 7+3=2 \times 5-0$ (statically determinate)

The external loads in figure a are the linear combinations of individual external loads as shown in figure al and in figure a2.

figure a2

The load effects of figure al are as follows:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 5000 | tension |
| 2 | -5000 | compression |
| 3 | 5000 | tension |
| 4 | -5000 | compression |
| 5 | -5000 | compression |
| 6 | 7500 | tension |
| 7 | 2500 | tension |

Therefore, for each element the safety margins of figure a1 are given by:

$$
\begin{aligned}
& M_{1}=R_{1}^{+}-S_{1}(\text { tension })=R_{1}-5000=R_{1}-0.5 P_{1} \\
& M_{2}=R_{2}^{-}-S_{1}(\text { compression })=R_{2}-5000=R_{2}-0.5 P_{1} \\
& M_{3}=R_{3}^{+}-S_{3}(\text { tension })=R_{3}-5000=R_{3}-0.5 P_{1} \\
& M_{4}=R_{4}^{-}+S_{4}(\text { compression })=R_{4}-5000=R_{4}-0.5 P_{1} \\
& M_{5}=R_{5}^{-}+S_{5}(\text { compression })=R_{5}-5000=R_{5}-0.5 P_{1} \\
& M_{6}=R_{6}^{+}-S_{6}(\text { tension })=R_{6}-7500=R_{6}-0.75 P_{1} \\
& M_{7}=R_{7}^{+}-S_{7}(\text { tension })=R_{7}-2500=R_{7}-0.25 P_{1}
\end{aligned}
$$

The load effects of figure 22 are as follows:

ELEMENT

| 1 | -8660.3 | compression |
| :--- | :--- | :--- |
| 2 | -2886.8 | compression |
| 3 | 2886.8 | tension |
| 4 | -2886.8 | compression |
| 5 | -2886.8 | compression |
| 6 | 4330.1 | tension |
| 7 | 1443.4 | tension |

Therefore, for each element the safety margins of figure a 2 are given by:

$$
\begin{aligned}
& M_{1}=R_{1}^{-}+S_{1}(\text { compression })=R_{1}-8660.3=R_{1}-0.866 P_{2} \\
& M_{2}=R_{2}^{-}+S_{2}(\text { compression })=R_{2}-2886.8=R_{2}-0.289 P_{2} \\
& M_{3}=R_{3}^{+}-S_{3}(\text { tension })=R_{3}-2886.8=R_{3}-0.289 P_{2} \\
& M_{4}=R_{4}^{-}+S_{4}(\text { compression })=R_{4}-2886.8=R_{4}-0.289 P_{2} \\
& M_{5}=R_{5}^{-}+S_{5}(\text { compression })=R_{5}-2886.8=R_{5}-0.289 P_{2} \\
& M_{6}=R_{6}^{+}-S_{6}(\text { tension })=R_{6}-4330.1=R_{6}-0.433 P_{2} \\
& M_{7}=R_{7}^{+}-S_{7}(\text { tension })=R_{7}-1443.4=R_{7}-0.144 P_{2}
\end{aligned}
$$

The load effects of figure a are as follows:

| 1 | -3660.3 | compression |
| :--- | :--- | :--- |
| 2 | -7886.8 | compression |
| 3 | 7886.8 | tension |
| 4 | -7886.8 | compression |
| 5 | -7886.8 | compression |
| 6 | 11830 | tension |
| 7 | 3943.4 | tension |

Therefore, the safety margins of the total sructure are given by the linear combinations of figure a1 and a2:

$$
\begin{aligned}
& M_{1}=R_{1}^{-}+S_{1}(\text { compression })=R_{1}-3660.3=R_{1}+0.5 P_{1}-0.866 P_{2} \\
& M_{2}=R_{2}^{-}+S_{2}(\text { compression })=R_{2}-7886.8=R_{2}-0.5 P_{1}-0.289 P_{2} \\
& M_{3}=R_{3}^{+}-S_{3}(\text { tension })=R_{3}-7886.8=R_{3}-0.5 P_{1}-0.289 P_{2} \\
& M_{4}=R_{4}^{-}+S_{4}(\text { compression })=R_{4}-7886.8=R_{4}-0.5 P_{1}-0.289 P_{2} \\
& M_{5}=R_{5}^{-}+S_{5}(\text { compression })=R_{5}-7886.8=R_{5}-0.5 P_{1}-0.289 P_{2} \\
& M_{6}=R_{6}^{+}-S_{6}(\text { tension })=R_{6}-11830=R_{6}-0.75 P_{1}-0.433 P_{2} \\
& M_{7}=R_{7}^{+}-S_{7}(\text { tension })=R_{7}-3943.4=R_{7}-0.25 P_{1}-0.144 P_{2}
\end{aligned}
$$

For a statically determinate structure, the failure modes can be plotted in a series system.


Example 2. Consider a statically determinate truss structure as shown below. Assume that the strength capacities for compression and tension are same and then calculate the safety margins of the total structure.

(Figure b)

The ANSYS PROGRAM and the corresponding results are listed in the appendixes $\mathrm{B}, \mathrm{B} 1, \mathrm{~B} 2$, and B 3 .

The external loads in figure $b$ are the linear combinations of individual external loads as shown in figure $\mathrm{b} 1, \mathrm{~b} 2$, and b 3 .

(Figure b1)

The load effects of figure b1 are as follows:

|  | ELEMENT | FORCE |
| :---: | :---: | :---: |
| 1 | -9185.6 | compression |
| 2 | -3029.1 | compression |
| 3 | 5303.3 | tension |
| 4 | 10000 | tension |
| 5 | -4185.6 | compression |
| 6 | 1835 | tension |
| 7 | -3061.9 | compression |
| 8 | -3029.1 | compression |
| 9 | 1767.8 | tension |
| 10 | 0 |  |
| 11 | 1938.1 | tension |
| 12 | 5303.3 | tension |
| 13 | 1767.8 | tension |

Therefore, for each element the safety margins of figure b1 are given by:

$$
\begin{aligned}
& M_{1}=R_{1}^{-}+S_{1}(\text { compression })=R_{1}-9185.6=R_{1}-0.9186 F_{1} \\
& M_{2}=R_{2}^{-}+S_{2}(\text { compression })=R_{2}-3029.1=R_{2}-0.3029 F_{1} \\
& M_{3}=R_{3}^{+}-S_{3}(\text { tension })=R_{3}-5303.3=R_{3}-0.5303 F_{1} \\
& M_{4}=R_{4}^{+}-S_{4}(\text { tension })=R_{4}-10000=R_{4}-F_{1} \\
& M_{5}=R_{5}^{-}+S_{5}(\text { compression })=R_{5}-4185.6=R_{5}-0.4186 F_{1} \\
& M_{6}=R_{6}^{+}-S_{6}(\text { tension })=R_{6}-1835=R_{6}-0.1835 F_{1} \\
& M_{7}=R_{7}^{-}+S_{7}(\text { compression })=R_{7}-3061.9=R_{7}-0.3062 F_{1} \\
& M_{8}=R_{8}^{-}+S_{8}(\text { compression })=R_{8}-3029.1=R_{8}-0.3029 F_{1} \\
& M_{9}=R_{9}{ }^{+}-S_{9}(\text { tension })=R_{9}-1767.8=R_{9}-0.1768 F_{1} \\
& M_{10}=R_{10}-S_{10}=R_{10}-0=R_{10} \\
& M_{11}=R_{11}^{+}-S_{11}(\text { tension })=R_{11}-1938.1=R_{11}-0.1938 F_{1} \\
& M_{12}=R_{12}^{+}-S_{12}(\text { tension })=R_{12}-5303.3=R_{12}-0.5303 F_{1} \\
& M_{13}=R_{13}^{+}-S_{13}(\text { tension })=R_{13}-1767.8=R_{13}-0.1768 F_{1}
\end{aligned}
$$


(Figure b2)

The load effects of figure b2 are as follows:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | -6123.7 | compression |
| 2 | -6058.1 | compression |
| 3 | 3535.5 | tension |
| 4 | 0 |  |
| 5 | 3876.3 | tension |
| 6 | 3670 | tension |
| 7 | -6123.7 | compression |
| 8 | -6058.1 | compression |
| 9 | 3535.5 | tension |
| 10 | 0 |  |

11

12

13
3876.3
3535.3
3535.3
tension
tesnion
tension

Therefore, for each element the safety margins of figure b2 are given by:

$$
M_{1}=R_{1}^{-}+S_{1}(\text { compression })=R_{1}-6123.7=R_{1}-0.6124 F_{2}
$$

$$
M_{2}=R_{2}^{-}+S_{2}(\text { compression })=R_{2}-6058.1=R_{2}-0.6058 F_{2}
$$

$$
M_{3}=R_{3}^{+}-S_{3}(\text { tesnion })=R_{3}-3535.5=R_{3}-0.3536 F_{2}
$$

$$
M_{4}=R_{4}-S_{4}=R_{4}-0=R_{4}
$$

$$
M_{5}=R_{5}{ }^{+}-S_{5}(\text { tesnion })=R_{5}-3876.3=R_{5}-0.3876 F_{2}
$$

$$
M_{6}=R_{6}^{+}-S_{6}(\text { tesnion })=R_{6}-3670=R_{6}-0.3670 F_{2}
$$

$$
M_{7}=R_{7}^{-}+S_{7}(\text { compression })=R_{7}-6123.7=R_{7}-0.6124 F_{2}
$$

$$
M_{8}=R_{8}^{-}+S_{8}(\text { compression })=R_{8}-6058.1=R_{8}-0.6058 F_{2}
$$

$$
M_{9}=R_{9}^{+}-S_{9}(\text { tesnion })=R_{9}-3535.5=R_{9}-0.3536 F_{2}
$$

$$
M_{10}=R_{10}-S_{10}=R_{10}-0=R_{10}
$$

$$
M_{11}=R_{11}^{+}-S_{11}(\text { tesnion })=R_{11}-3876.3=R_{11}-0.3876 F_{2}
$$

$$
M_{12}=R_{12}^{+}-S_{12}(\text { tesnion })=R_{12}-3535.5=R_{12}-0.3536 F_{2}
$$

$$
M_{13}=R_{13}^{+}-S_{13}(\text { tesnion })=R_{13}-3535.5=R_{13}-0.3536 F_{2}
$$


(Figure b3)

The load effects of figure b3 are as follows:

ELEMENT FORCE

| 1 | -3061.9 | compression |
| :--- | :--- | :--- |
| 2 | -3029.1 | compression |
| 3 | 1767.8 | tension |
| 4 | 0 |  |
| 5 | 1938.1 | tension |
| 6 | 1835 | tension |
| 7 | -9185.6 | compression |
| 8 | -3029.1 | compression |
| 9 | 5303.3 | tension |
| 10 | 10000 | tension |

11

12

13
$-4185.6$
1767.8
5303.3
compression
tension
tension

Therefore, for each element the safety margins of figure b3 are given by:

$$
\begin{aligned}
& M_{1}=R_{1}^{-}+S_{1}(\text { compression })=R_{1}-3061.9=R_{1}-0.3062 F_{3} \\
& M_{2}=R_{2}^{-}+S_{2}(\text { compression })=R_{2}-3029.1=R_{2}-0.3029 F_{3} \\
& M_{3}=R_{3}^{+}-S_{3}(\text { tension })=R_{3}-1767.8=R_{3}-0.1768 F_{3} \\
& M_{4}=R_{4}-S_{4}=R_{4}-0=R_{4} \\
& M_{5}=R_{5}^{+}-S_{5}(\text { tension })=R_{5}-1938.1=R_{5}-0.1938 F_{3} \\
& M_{6}=R_{6}^{+}-S_{6}(\text { tension })=R_{6}-1835=R_{6}-0.1835 F_{3} \\
& M_{7}=R_{7}^{-}+S_{7}(\text { compression })=R_{7}-9185.6=R_{7}-0.9186 F_{3} \\
& M_{8}=R_{8}^{-}+S_{8}(\text { compression })=R_{8}-3029.1=R_{8}-0.3029 F_{3} \\
& M_{9}=R_{9}^{+}-S_{9}(\text { tension })=R_{9}-5303.3=R_{9}-0.5303 F_{3} \\
& M_{10}=R_{10}^{+}-S_{10}(\text { tension })=R_{10}-10000=R_{10}-F_{3} \\
& M_{11}=R_{11}^{-}+S_{11}(\text { compression })=R_{11}-4185.6=R_{11}-0.4186 F_{3} \\
& M_{12}=R_{12}^{+}-S_{12}(\text { tension })=R_{12}-1767.8=R_{12}-0.1768 F_{3}
\end{aligned}
$$

$$
M_{13}=R_{13}{ }^{+}-S_{13}(\text { tension })=R_{13}-5303.3=R_{13}-0.5303 F_{3}
$$


(Figure b)

The load effects of figure $b$ are as follows:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | -18371 | compression |
| 2 | -12116 | compression |
| 3 | 10607 | tension |
| 4 | 10000 | tension |
| 5 | 1628.9 | tension |
| 6 | 7340.1 | tension |
| 7 | -18371 | compression |
| 7 | -12116 | compression |
| 8 | 10607 | tension |

tension
tension

## tension

tension

Therefore, the safety margins of the total structure are given by the linear combinations of figure $\mathrm{b} 1, \mathrm{~b} 2$, and b 3 :

$$
\begin{aligned}
& M_{1}=R_{1}^{-}+S_{1}(c)=R_{1}-18371=R_{1}-0.9186 F_{1}-0.6124 F_{2}-0.3062 F_{3} \\
& M_{2}=R_{2}^{-}+S_{2}(c)=R_{2}-12116=R_{2}-0.3029 F_{1}-0.6058 F_{2}-0.3029 F_{3} \\
& M_{3}=R_{3}{ }^{+}-S_{3}(t)=R_{3}-10607=R_{3}-0.53 F_{1}-0.3536 F_{2}-0.1768 F_{3} \\
& M_{4}={R_{4}}^{+}-S_{4}(t)=R_{4}-10000=R_{4}-F_{1} \\
& M_{5}=R_{5}^{+}-S_{5}(t)=R_{5}-1628.9=R_{5}+0.42 F_{1}-0.3876 F_{2}-0.1938 F_{3} \\
& M_{6}=R_{6}^{+}-S_{6}(t)=R_{6}-7340.1=R_{6}-0.184 F_{1}-0.367 F_{2}-0.184 F_{3} \\
& M_{7}=R_{7}^{-}+S_{7}(c)=R_{7}-18371=R_{7}-0.3062 F_{1}-0.6124 F_{2}-0.9186 F_{3} \\
& M_{8}=R_{8}^{-}+S_{8}(c)=R_{8}-12116=R_{8}-0.3029 F_{1}-0.6058 F_{2}-0.3029 F_{3} \\
& M_{9}=R_{9}{ }^{+}-S_{9}(t)=R_{9}-10607=R_{9}-0.1768 F_{1}-0.3536 F_{2}-0.53 F_{3} \\
& M_{10}=R_{10}^{+}-S_{10}(t)=R_{10}-10000=R_{10}-F_{3} \\
& M_{11}=R_{11}^{+}-S_{11}(t)=R_{11}-1628.9=R_{11}-0.194 F_{1}-0.39 F_{2}+0.42 F_{3} \\
& M_{13}=R_{13}^{+}-S_{13}(t)=R_{13}-10607=R_{13}-0.53 F_{1}-0.35 F_{2}-0.18 F_{3}
\end{aligned}
$$

For a statically determinate structure, the failure modes can be plotted in a series system:


Example 3. Consider a redundant truss sturcture as shown below. Assume that the strength capacities for compression and tension are same $R_{i}{ }^{+}=R_{i}^{-}=60000$ and then calculate the safety margins of the total structure.

$b+r>2 j-e \quad 6+3>2 \times 4-0 \quad 9>8$ (one redundancy).

The ANSYS PROGRAM and the corresponding results are listed in the appendixes $\mathrm{C}, \mathrm{C} 1, \mathrm{C} 2, \mathrm{C} 3, \mathrm{C} 4, \mathrm{C} 5, \mathrm{C} 6, \mathrm{D}, \mathrm{D} 1, \mathrm{D} 2, \mathrm{D} 3, \mathrm{D} 4, \mathrm{D} 5, \mathrm{E}, \mathrm{E} 1, \mathrm{E} 2, \mathrm{E} 3, \mathrm{E} 4$, and E 5 . The force distributions are listed below:

## ELEMENT AND FORCE

| CASE | LOAD | APP. | 1 | 2 | 3 | 4 | 5 | 6 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | L | C | 40000 | 40000 | 56569 | -56569 | -40000 | -40000 |
| 2 | L | D | FAIL | 0 | 113140 | 0 | -80000 | -80000 |
| 3 | R1 | E | FAIL | 60000 | -84853 | -84853 | 60000 | 60000 |
| 4 | L,R1 | C1 | FAIL | 60000 | 28284 | -84853 | -20000 | -20000 |
| 5 | L | D1 | 0 | FAIL | 113140 | 0 | -80000 | -80000 |
| 6 | R2 | E1 | 60000 | FAIL | -84853 | -84853 | 60000 | 60000 |
| 7 | L,R2 | C2 | 60000 | FAIL | 28284 | -84853 | -20000 | -20000 |
| 8 | L | D2 | 80000 | 80000 | FAIL | -113140 | 0 | 0 |
| 9 | R3 | E2 | -42426 | -42426 | FAIL | 60000 | -42426 | -42426 |
| 10 | L,R3 | C3 | 37574 | 37574 | FAIL | -53137 | -42426 | -42426 |
| 11 | L | D3 | 0 | 0 | 113140 | FAIL | -80000 | -80000 |
| 12 | R4 | E3 | 42426 | 42426 | -60000 | FAIL | 42426 | 42426 |
| 13 | L,R4 | C4 | 42426 | 42426 | 53137 | FAIL | -37574 | -37574 |
| 14 | L | D4 | 80000 | 80000 | 0 | -113140 | FAIL | 0 |
| 15 | R5 | E4 | -60000 | -60000 | 84853 | 84853 | FAIL | -60000 |
| 16 | L,R5 | C5 | 20000 | 20000 | 84853 | -28284 | FAIL | -60000 |
| 17 | L | D5 | 80000 | 80000 | 0 | -113140 | 0 | FAIL |
| 18 | R6 | E5 | -60000 | -60000 | 84853 | 84853 | -60000 | FAIL |
| 19 | L,R6 | C6 | 20000 | 20000 | 84853 | -28284 | -60000 | FAIL |

From the above table and appendix $C$, one can refer to the force distributions. Therefore, the safety margins of the individual bars are given by:

$$
\begin{aligned}
& M_{1}=R_{1}^{+}-S_{1}(\text { tension })=R_{1}-40000=R_{1}-0.5 L \\
& M_{2}=R_{2}^{+}-S_{1}(\text { tension })=R_{2}-40000=R_{2}-0.5 L \\
& M_{3}=R_{3}^{+}+S_{3}(\text { tension })=R_{3}-56569=R_{3}-0.7071 L \\
& M_{4}=R_{4}^{-}+S_{4}(\text { compression })=R_{4}-56569=R_{4}-0.7071 L \\
& M_{5}=R_{5}^{-}+S_{5}(\text { compression })=R_{5}-40000=R_{5}-0.5 L \\
& M_{6}=R_{6}^{-}+S_{6}(\text { compression })=R_{6}-40000=R_{6}-0.5 L
\end{aligned}
$$

When member one fails in tension, the safety margins of the other members are calculated below.

From the above table and appendix D , one can refer to the force distributions. Therefore, the safety margins of the individual bars are given by:


The corresponding safety margins can be written as:
$M_{2(1)}=R_{2}$
$M_{3(1)}=R_{3}{ }^{+}-S_{3}($ tension $)=R_{3}-113140=R_{3}-1.4142 L$

$$
\begin{aligned}
& M_{4(1)}=R_{4} \\
& M_{5(1)}=R_{5}^{-}+S_{5}(\text { compression })=R_{5}-80000=R_{5}-L \\
& M_{6(1)}=R_{6}^{-}+S_{6}(\text { compression })=R_{6}-80000=R_{6}-L
\end{aligned}
$$

From the above table and appendix E, one can refer to the force distributions. Therefore, the safety margins of the individual bars are given by:

$M_{2(1)}=R_{2}{ }^{+}-S_{2}($ tension $)=R_{2}-60000=R_{2}-R_{1}$
$M_{3(1)}=R_{3}^{-}+S_{3}($ compression $)=R_{3}-84853=R_{3}-1.4142 R_{1}$
$M_{4(1)}=R_{4}^{-}+S_{4}($ compression $)=R_{4}-84853=R_{4}-1.4142 R_{1}$
$M_{5(1)}=R_{5}{ }^{+}-S_{5}($ tension $)=R_{5}-60000=R_{5}-R_{1}$
$M_{6(1)}=R_{6}{ }^{+}-S_{6}($ tension $)=R_{6}-60000=R_{6}-R_{1}$

From the above table and appendix C 1 , one can refer to the force distributions.


Therefore, when member one fails in tension, the safety margins of the other members are as follows:

$$
\begin{aligned}
& M_{2(1)}=R_{2}^{+}-S_{2}(\text { tension })=R_{2}-60000=R_{2}-R_{1} \\
& M_{3(1)}=R_{3}^{+}-S_{3}(\text { tension })=R_{3}-28284=R_{3}+1.4142 R_{1}-1.4142 L \\
& M_{4(1)}=R_{4}^{-}+S_{4}(\text { compression })=R_{4}-84853=R_{4}-1.4142 R_{1} \\
& M_{5(1)}=R_{5}^{-}+S_{5}(\text { compression })=R_{5}-20000=R_{5}+R_{1}-L \\
& M_{6(1)}=R_{6}^{-}+S_{6}(\text { compression })=R_{6}-20000=R_{6}+R_{1}-L
\end{aligned}
$$

If any more member fails, the stiffness mateix will become singular; therefore, when member one failed, the failure modes of the structure can be plotted in a series system as shown:


The corresponding safety margins are as follows:

$$
\begin{aligned}
& M_{1}=R_{1}-0.5 L \\
& M_{2(1)}=R_{2}-R_{1} \\
& M_{3(1)}=R_{3}+1.4142 R_{1}-1.4142 L \\
& M_{4(1)}=R_{4}-1.4142 R_{1} \\
& M_{5(1)}=R_{5}+R_{1}-L \\
& M_{6(1)}=R_{6}+R_{1}-L
\end{aligned}
$$

When member two fails in tension, the safety margins of the other members are calculated below:

From the above table and appendix D1, one can refer to the force distributions. Therefore, the safety margins of the individual bars are given by:

$M_{1(2)}=R_{1}$
$M_{3(2)}=R_{3}{ }^{+}-S_{3}($ tension $)=R_{3}-113140=R_{3}-1.4142 L$

$$
\begin{aligned}
& M_{4(2)}=R_{4} \\
& M_{5(2)}=R_{5}^{-}+S_{5}(\text { compression })=R_{5}-80000=R_{5}-L \\
& M_{6(2)}=R_{6}^{-}+S_{6}(\text { compression })=R_{6}-80000=R_{6}-L
\end{aligned}
$$

From the above table and appendix E1, one can refer to the force distributions. Therefore, the safety margins of the individual bars are given by:


$$
\begin{aligned}
& M_{3(2)}=R_{3}^{-}+S_{3}(\text { compression })=R_{3}-84853=R_{3}-1.4142 R_{2} \\
& M_{4(2)}=R_{4}^{-}+S_{4}(\text { compression })=R_{4}-84853=R_{4}-1.4142 R_{2} \\
& M_{5(2)}=R_{5}{ }^{+}-S_{5}(\text { tension })=R_{5}-60000=R_{5}-R_{2} \\
& M_{6(2)}=R_{6}{ }^{+}-S_{6}(\text { tension })=R_{6}-60000=R_{6}-R_{2}
\end{aligned}
$$

From the above table and appendix C2, one can refer to the force distributions. Therefore, the safety margins of the individual bars are given by:

$$
\begin{aligned}
& \text { L= } \\
& M_{1(2)}=R_{1}^{+}-S_{1}(t)=R_{1}-600000=R_{1}-R_{2} \\
& M_{3(2)}=R_{2}+-S_{2}(t)=R_{3}-28284=R_{3}+1.4142 R_{2}-1.4142 L \\
& M_{5(2)}=R_{5}^{-}+S_{5}(c)=R_{4}-84853=R_{4}-1.4142 R_{2} \\
& M_{6(2)}=R_{6}^{-}+S_{6}(c)=R_{6}-20000=R_{5}+R_{2}-L
\end{aligned}
$$

If any more member fails, the stiffness matrix will become singular; therefore, when member two failed, the failure modes of the structure can be plotted in a series system as follows:


The corresponding safety margins are as follows:
$M_{2}=R_{2}-0.5 L$
$M_{1(2)}=R_{1}-R_{2}$
$M_{3(2)}=R_{3}+1.4142 R_{2}-1.4142 L$
$M_{4(2)}=R_{4}-1.4142 R_{2}$
$M_{5(2)}=R_{5}+R_{2}-L$
$M_{6(2)}=R_{6}+R_{2}-L$

When member three fails in tension, the safety margins of the other members are calculated below:

From the above table and appendix D2, one can refer to the force distributions. Therefore, the safety margins of the individual bars are given by:


$$
\begin{aligned}
& M_{1(3)}=R_{1}^{+}-S_{1}(\text { tension })=R_{1}-80000=R_{1}-L \\
& M_{2(3)}=R_{2}^{+}-S_{2}(\text { tension })=R_{2}-80000=R_{2}-L \\
& M_{4(3)}=R_{4}^{-}+S_{4}(\text { compression })=R_{4}-113140=R_{4}-1.4142 L
\end{aligned}
$$

$$
\begin{aligned}
M_{5(3)} & =R_{5} \\
M_{6(3)} & =R_{6}
\end{aligned}
$$

From the above table and appendix E2, one can refer to the force distributions. Therefore, the safety margins of the individual bars are given by:

$M_{1(3)}=R_{1}^{-}+S_{1}($ compression $)=R_{1}-42426=R_{1}-0.7071 R_{3}$
$M_{2(3)}=R_{2}^{-}+S_{2}($ compression $)=R_{2}-42426=R_{2}-0.7071 R_{3}$
$M_{4(3)}=R_{4}{ }^{+}-S_{4}($ tension $)=R_{4}-60000=R_{4}-R_{3}$
$M_{5(3)}=R_{5}^{-}+S_{5}($ compression $)=R_{5}-42426=R_{5}-0.7071 R_{3}$
$M_{6(3)}=R_{6}^{-}+S_{6}($ compression $)=R_{6}-42426=R_{6}-0.7071 R_{3}$

From the above table and appendix C 3 , one can refer to the force distributions. Therefore, the safety margins of the individual bars are given by:


$$
\begin{aligned}
& M_{1(3)}=R_{1}^{+}-S_{1}(\text { tension })=R_{1}-37574=R_{1}+0.7071 R_{3}-L \\
& M_{2(3)}=R_{2}^{+}-S_{2}(\text { tension })=R_{2}-37574=R_{2}+0.7071 R_{3}-L
\end{aligned}
$$

$$
M_{4(3)}=R_{4}^{-}+S_{4}(\text { compression })=R_{4}-53137=R_{4}+R_{3}-1.4142 L
$$

$$
M_{5(3)}=R_{5}^{-}+S_{5}(\text { compression })=R_{5}-42426=R_{5}-0.7071 R_{3}
$$

$$
M_{6(3)}=R_{6}^{-}+S_{6}(\text { compression })=R_{6}-42426=R_{6}-0.7071 R_{3}
$$

If any more member fails, the stiffness matrix will become singular; therefore, when member three failed, the failure modes of the structure can be plotted in a series system as follows:


The corresponding safety margins are as follows:
$M_{3}=R_{3}-0.7071 L$
$M_{1(3)}=R_{1}+0.7071 R_{3}-L$
$M_{2(3)}=R_{2}+0.7071 R_{3}-L$
$M_{4(3)}=R_{4}+R_{3}-1.4142 L$
$M_{5(3)}=R_{5}-0.7071 R_{3}$
$M_{6(3)}=R_{6}-0.7071 R_{3}$

When member four fails in compression, the safety margins of the other members are calculated below:


From the above table and appendix D3, one can refer to the force distributions. Therefore, the safety margins of the individual bars are given by:
$M_{1(4)}=R_{1}$
$M_{2(4)}=R_{2}$
$M_{3(4)}=R_{3}{ }^{+}-S_{3}($ tension $)=R_{3}-113140=R_{3}-1.4142 L$
$M_{5(4)}=R_{5}^{-}+S_{5}($ compression $)=R_{5}-80000=R_{5}-L$
$M_{6(4)}=R_{6}^{-}+S_{6}($ compression $)=R_{6}-80000=R_{6}-L$
From the above table and appendix E3, one can refer to the force distributions. Therefore, the safety margins of the individual bars are given by:


$$
\begin{aligned}
& M_{1(4)}=R_{1}{ }^{+}-S_{1}(\text { tension })=R_{1}-42426=R_{1}-0.7071 R_{4} \\
& M_{2(4)}=R_{2}^{+}-S_{2}(\text { tension })=R_{2}-42426=R_{2}-0.7071 R_{4} \\
& M_{3(4)}=R_{3}^{-}+S_{3}(\text { compression })=R_{3}-60000=R_{3}-R_{4} \\
& M_{5(4)}=R_{5}{ }^{+}-S_{5}(\text { tension })=R_{5}-42426=R_{5}-0.7071 R_{4} \\
& M_{6(4)}=R_{6}{ }^{+}-S_{6}(\text { tension })=R_{6}-42426=R_{6}-0.7071 R_{4}
\end{aligned}
$$

From the above table and appendix C 4 , one can refer to the force distributions. Therefore, the safety margins of the individual bars are given by:


$$
\begin{aligned}
& M_{1(4)}=R_{1}^{+}-S_{1}(t)=R_{1}-42426=R_{1}-0.7071 R_{4} \\
& M_{2(4)}=R_{2}^{+}-S_{2}(t)=R_{2}-42426=R_{2}-0.7071 R_{4} \\
& M_{3(4)}=R_{3}^{+}-S_{3}(t)=R_{3}-53137=R_{3}+R_{4}-1.4142 L \\
& M_{5(4)}=R_{5}^{-}+S_{5}(c)=R_{5}-37574=R_{5}+0.7071 R_{4}-L \\
& M_{6(4)}=R_{6}^{-}+S_{6}(c)=R_{6}-37574=R_{6}+0.7071 R_{4}-L
\end{aligned}
$$

If any more member fails, the stiffness matrix will become singular; therefore, when member four failed, the failure modes of the structure can be plotted in a series system as shown:


The corresponding safety margins are as follows:

$$
\begin{aligned}
& M_{4}=R_{4}-0.7071 L \\
& M_{1(4)}=R_{1}-0.7071 R_{4} \\
& M_{2(4)}=R_{2}-0.7071 R_{4} \\
& M_{3(4)}=R_{3}+R_{4}-1.4142 L \\
& M_{5(4)}=R_{5}+0.7071 R_{4}-L \\
& M_{6(4)}=R_{6}+0.7071 R_{4}-L
\end{aligned}
$$

When member five fails in compression, the safety margins of the other members are calculated below:


From the above table and appendix D4, one can refer to the force distributions. Therefore, the safety margins of the individual bars are given by:
$M_{1(5)}=R_{1}{ }^{+}-S_{1}($ tension $)=R_{1}-L$
$M_{2(5)}=R_{2}{ }^{+}-S_{2}($ tension $)=R_{2}-L$
$M_{3(5)}=R_{3}$
$M_{4(5)}=R_{4}^{-}+S_{4}($ compression $)=R_{4}-113140=R_{4}-1.4142 L$
$M_{6(5)}=R_{6}$
From the above table and appendix E4, one can refer to the force distributions. Therefore,
the safety margins of the individual bars are given by:


$$
\begin{aligned}
& M_{1(5)}=R_{1}^{-}+S_{1}(\text { compression })=R_{1}-60000=R_{1}-R_{5} \\
& M_{2(5)}=R_{2}^{-}+S_{2}(\text { compression })=R_{2}-60000=R_{2}-R_{5} \\
& M_{3(5)}=R_{3}^{+}-S_{3}(\text { tension })=R_{3}-84853=R_{3}-1.4142 R_{5} \\
& M_{4(5)}=R_{4}^{+}-S_{4}(\text { tension })=R_{4}-84853=R_{4}-1.4142 R_{5} \\
& M_{6(5)}=R_{6}^{-}+S_{6}(\text { compression })=R_{6}-60000=R_{6}-R_{5}
\end{aligned}
$$

From the above table and appendix C5, one can refer to the force distributions. Therefore, the safety margins of the individual bars are given by:

$M_{1(5)}=R_{1}{ }^{+}-S_{1}(t)=R_{1}-20000=R_{1}+R_{5}-L$

$$
\begin{aligned}
& M_{2(5)}=R_{2}^{+}-S_{2}(t)=R_{2}-20000=R_{2}+R_{5}-L \\
& M_{3(5)}=R_{3}^{+}-S_{3}(t)=R_{3}-84853=R_{3}-1.4142 R_{5} \\
& M_{4(5)}=R_{4}^{-}+S_{4}(c)=R_{4}-28284=R_{4}+1.4142 R_{5}-1.4142 L \\
& M_{6(5)}=R_{6}^{-}+S_{6}(c)=R_{6}-60000=R_{6}-R_{5}
\end{aligned}
$$

If any more member fails, the stiffness matrix will become singular; therefore, when member five failed, the failure modes of the structure can be ploted in a series as shown:


The corresponding safety margins are as follows:

$$
\begin{aligned}
& M_{5}=R_{5}-0.5 L ; M_{1(5)}=R_{1}+R_{5}-L \\
& M_{2(5)}=R_{2}+R_{5}-L \\
& M_{3(5)}=R_{3}-1.4142 R_{5} \\
& M_{4(5)}=R_{4}+1.4142 R_{5}-1.4142 L \\
& M_{6(5)}=R_{6}-R_{5}
\end{aligned}
$$

When member six fails in compression, the safety margins of the other members are calculated below:


From the above table and appendix D5, one can refer to the force distributions. Therefore, the safety margins of the individual bars are given by:
$M_{1(6)}=R_{1}{ }^{+}-S_{1}($ tension $)=R_{1}-80000=R_{1}-L$
$M_{2(6)}=R_{2}{ }^{+}-S_{2}($ tension $)=R_{2}-80000=R_{2}-L$
$M_{3(6)}=R_{3}$
$M_{4(6)}=R_{4}^{-}+S_{4}($ compression $)=R_{4}-113140=R_{4}-1.4142 L$
$M_{5(6)}=R_{5}$

From the above table and appendix E5, one can refer to the force distributions. Therefore, the safety margins of the individual bars are given by:


$$
\begin{aligned}
& M_{1(6)}=R_{1}^{-}+S_{1}(\text { compression })=R_{1}-60000=R_{1}-R_{6} \\
& M_{2(6)}=R_{2}^{-}+S_{2}(\text { compression })=R_{2}-60000=R_{2}-R_{6} \\
& M_{3(6)}=R_{3}^{+}-S_{3}(\text { tension })=R_{3}-84853=R_{3}-1.4142 R_{6} \\
& M_{4(6)}=R_{4}^{+}-S_{4}(\text { tension })=R_{4}-84853=R_{4}-1.4142 R_{6} \\
& M_{5(6)}=R_{5}^{-}+S_{5}(\text { compression })=R_{5}-60000=R_{5}-R_{6}
\end{aligned}
$$

From the above table and appendix C6, one can refer to the force distributions. Therefore, the safety margins of the individual bars are given by:


$$
\begin{aligned}
& M_{1(6)}=R_{1}^{+}-S_{1}(t)=R_{1}-20000=R_{1}+R_{6}-L \\
& M_{2(6)}=R_{2}^{+}-S_{2}(t)=R_{2}-20000=R_{2}+R_{6}-L \\
& M_{3(6)}=R_{3}^{+}-S_{3}(t)=R_{3}-84853=R_{3}-1.4142 R_{6} \\
& M_{4(6)}=R_{4}^{-}+S_{4}(c)=R_{4}-28284=R_{4}+1.4142 R_{6}-1.4142 L \\
& M_{5(6)}=R_{5}^{-}+S_{5}(c)=R_{5}-60000=R_{5}-R_{6}
\end{aligned}
$$

If any more member fails, the stiffness matrix will become singular; therefore, when member six failed, the failure modes of the structure can be plotted in a series system as shown:


The corresponding safety margins are as follows:
$M_{6}=R_{6}-0.5 L$
$M_{1(6)}=R_{1}+R_{6}-L$
$M_{2(6)}=R_{2}+R_{6}-L$
$M_{3(6)}=R_{3}-1.4142 R_{6}$
$M_{4(6)}=R_{4}+1.4142 R_{6}-1.4142 L$
$M_{5(6)}=R_{5}-R_{6}$

If one considers the probability of failure of the whole structure, there are thirty different possibilities (failure modes) which can cause the structure failure as shown below:



## CHAPTER 9

## STRUCTURAL RELIABILITY ANALYSIS

 USING ANSYS
### 9.1 INTRODUCTION

For some structures the reliabilities of structures are calculated on the basis of failure of single components, where the probability of failure of any component and the correlation among failed components are taken into account. Then combine all the failure components to make up the series system. The modelling of this type is called system reliability at level 1. The evaluation of the structural reliability can be obtained with satisfactory accuracy by only including failure components with high probabilities of failure. Such significant failure components can be selected by choosing those failure components with $P_{f}$ values in an interval $\left[P_{f m a x}, P_{f m a x}-\Delta P_{f}\right]$, where $\Delta P_{f}$ must be chosen properly.

For some structures the reliabilities of the structures are calculated on the basis of failure of two failure components, where the probability of failure of any pair of failure components and the correlation among failure pairs are taken into account, and then all the failure pairs are combined to make up the series system. The modelling of this type is called system reliability at level 2 . The evaluation of the structural reliability can be obtained with satisfactory accuracy by only including failure pairs with high probability of failure.

To obtain the so-called significant pairs of failure components, the structure is modified by assuming failure in the significant failure components and applying artificial loads which are the strength capacities of the failure components if the components are ductile.

No artificial loads are applied if the failure components are brittle. Then the modified structure is analysed elastically and new $P_{f}$ values are calculated for all surviving components. Surviving components with high $P_{f}$ values are then combined with the significant failure components so that the significant pairs of failure components can be determined. By continuing in the same procedure, system reliability at level $\mathrm{N}, \mathrm{N}=3,4,5 \ldots \ldots$..... can be defined.

The most frequently used modelling of system reliability is system reliability at the mechanism level. Usually the number of mechanisms (failure modes) is very large; therefore, only some reasonable number of significant mechanisms should be considered. The procedure described above can be continued until formations of mechanisms, but sometimes such a procedure will be very inconvenient due to many reanalyses needed for a highly redundant structure. Therefore, it is better to base the ANSYS reliability analysis on the fundamental mechanisms and on the linear combinations of fundamental mechanisms. (see the platic theory of structures for details).

### 9.2 TRANSFORMATIONS OF NON-NORMAL BASIC VARIABLES

In general basic variables can not be modelled by a normal distribution; In such a case the transformation from the non-normal distribution to a normal distribution is needed. If all basic variables are normally distributed, the evaluation of the structural reliability will be greatly simplified; The only information needed will then be the expected values, the standard deviations and the correlation coefficients.

Many different transformation methods have been suggested to overcome the problem. A very accurate method suggested by Rackwitz and Fiessler is discussed below: A non-normal variable is transformed into a normal variable so that at the design point the corresponding density functions and the distribution functions are same , i.e.:
$F_{X_{i}}\left(x^{\prime \prime}{ }_{i}\right)=\Phi\left(\frac{x_{i}^{\prime \prime}-\mu_{X_{i}}^{\prime}}{\sigma_{X_{i}}^{\prime}}\right)$
$f_{X_{i}}\left(x_{i}^{\prime \prime}\right)=\frac{1}{\sigma_{X_{i}}^{\prime}} \varphi\left(\frac{x_{i}^{\prime \prime}-\mu_{X_{i}}^{\prime}}{\sigma_{X_{i}}^{\prime}}\right)$.
where $\bar{x}^{\prime \prime}=\left(x_{1}{ }_{1}, \ldots, x^{\prime \prime}, \ldots, x_{n}^{\prime}\right)$ is the design point, $\mu_{X_{i}}^{\prime}$ and $\sigma_{X_{i}}^{\prime}$ are the mean value and standard deviation of the transformed normal distribution.

From equation (1), (2) the mean value and the standard deviation of the transformed normal distribution can be given by:

$$
\begin{aligned}
& \mu_{X_{i}}^{\prime}=x_{i}{ }_{i}-\Phi^{-1}\left(F_{X_{i}}\left(x_{i}^{\prime \prime}\right)\right) \sigma_{X_{i}}^{\prime} \\
& \sigma_{X_{i}}^{\prime}=\frac{\varphi\left(\Phi^{-1}\left(F_{X_{i}}\left(x_{i}^{\prime \prime}\right)\right)\right)}{f_{X_{i}}\left(x_{i}^{\prime \prime}\right)}
\end{aligned}
$$

where the design point $\bar{x}$ " can be obtained by iterative method.

A simpler way called the multiplication factor method suggested by the Thoft-Christensen to define the design point is as follows:

$$
s^{\prime \prime}=\mu_{S}+\alpha_{S} \sigma_{S}
$$

where $\mu_{S}$ and $\sigma_{S}$ are the orginal mean value and standard deviation of non- normal distribution, and where $\alpha_{S}$ is a positive multiplication factor, and it can be determined by experiment.

Therefore, at design point $s^{\prime \prime}$
$F_{S}\left(s^{\prime \prime}\right)=\Phi\left(\frac{s^{\prime \prime}-\mu_{S}^{\prime}}{\sigma_{S}^{\prime}}\right)$
$f_{S}\left(s^{\prime \prime}\right)=\frac{1}{\sigma_{S}^{\prime}} \varphi\left(\frac{s^{\prime \prime}-\mu_{S}^{\prime}}{\sigma_{S}^{\prime}}\right)$

Finally, the unknown equivalent mean value and standard deviation can be given by:
$\mu_{S}^{\prime}=s^{\prime \prime}-\Phi^{-1}\left(F_{S}\left(s^{\prime \prime}\right)\right) \sigma_{S}^{\prime}$
$\sigma_{S}^{\prime}=\frac{\varphi\left(\Phi^{-1}\left(F_{S}\left(s^{\prime \prime}\right)\right)\right)}{f_{S}\left(s^{\prime \prime}\right)}$

According to experience, in some cases one can use the original mean value $\mu_{S}$ and original standard deviation $\sigma_{S}$ of a non-normal distribution variable instead of the equivalent mean value $\mu_{S}^{\prime}$ and equivalent standard deviation $\sigma_{S}^{\prime}$ of the approximate normal distribution variable.

### 9.3ESTIMATE OF STRUCTURAL RELIABILITY

In this section it is assumed that all basic variables are normally distributed. The structure is considered at a fixed point in time so that only static situation is discussed and all elasticity coefficients are assumed deterministic.

Example 1. Consider again the structure of example 1 of chapter 8 . The expected values and standard deviations are listed below. Assume that the bars at the same level are perfectly correlated; otherwise, uncorrelated.


$$
\begin{aligned}
& \mu_{p_{1}}=10000, \mu_{p_{2}}=10000, \mu_{R}=60000 \\
& \sigma_{p_{1}}=1000, \sigma_{p_{1}}=1000, \sigma_{R}=6000
\end{aligned}
$$

The safety margins of the structure are given as follows:

$$
\begin{aligned}
& M_{1}=R_{1}+0.5 P_{1}-0.866 P_{2} \\
& M_{2}=R_{2}-0.5 P_{1}-0.289 P_{2} \\
& M_{3}=R_{3}-0.5 P_{1}-0.289 P_{2}
\end{aligned}
$$

$$
\begin{aligned}
& M_{4}=R_{4}-0.5 P_{1}-0.289 P_{2} \\
& M_{5}=R_{5}-0.5 P_{1}-0.289 P_{2} \\
& M_{6}=R_{6}-0.75 P_{1}-0.433 P_{2} \\
& M_{7}=R_{7}-0.25 P_{1}-0.144 P_{2}
\end{aligned}
$$

Due to the perfect correlated at the same level the safety margins can be reduced as follows:

$$
M_{1}=R_{1}+0.5 P_{1}-0.866 P_{2}
$$

$$
M_{2}=R_{2}-0.5 P_{1}-0.289 P_{2}
$$

$$
M_{3}=R_{1}-0.5 P_{1}-0.289 P_{2}
$$

$$
M_{4}=R_{6}-0.75 P_{1}-0.433 P_{2}
$$

$$
M_{5}=R_{6}-0.25 P_{1}-0.144 P_{2}
$$

The random variables are normalized by

$$
\begin{aligned}
& Z_{1}=\frac{P_{1}-\mu_{P_{1}}}{\sigma_{P_{1}}}, P_{1}=\sigma_{P_{1}} Z_{1}+\mu_{P_{1}}=1000 Z_{1}+10000 \\
& Z_{2}=\frac{P_{2}-\mu_{P_{2}}}{\sigma_{P_{2}}}, P_{2}=\sigma_{P_{2}} Z_{2}+\mu_{P_{2}}=1000 Z_{2}+10000
\end{aligned}
$$

$$
\begin{aligned}
& Z_{3}=\frac{R_{1}-\mu_{R}}{\sigma_{R}}, R_{1}=\sigma_{R} Z_{3}+\mu_{R}=6000 Z_{3}+60000 \\
& Z_{4}=\frac{R_{2}-\mu_{R}}{\sigma_{R}}, R_{2}=\sigma_{R} Z_{4}+\mu_{R}=6000 Z_{4}+60000 \\
& Z_{5}=\frac{R_{6}-\mu_{R}}{\sigma_{R}}, R_{6}=\sigma_{R} Z_{5}+\mu_{R}=6000 Z_{5}+60000
\end{aligned}
$$

By the substitutions, one can get:

$$
\begin{aligned}
& M_{1}=R_{1}+0.5 P_{1}-0.866 P_{2}=\left(6000 Z_{3}+60000\right)+0.5\left(1000 Z_{1}+10000\right) \\
& -0.866\left(1000 Z_{2}+10000\right)
\end{aligned}
$$

$$
M_{1}=56340+500 Z_{1}-866 Z_{2}+6000 Z_{3}
$$

$$
M_{1}=9.26+0.0822 Z_{1}-0.1424 Z_{2}+0.9864 Z_{3} \text { (after unification) }
$$

$$
\Phi(-9.26)=0.1098 \times 10^{-19}
$$

$$
M_{2}=R_{2}-0.5 P_{1}-0.289 P_{2}=\left(6000 Z_{4}+60000\right)-0.5\left(1000 Z_{1}+10000\right)
$$

$$
-0.289\left(1000 Z_{2}+10000\right)
$$

$$
M_{2}=52110-500 Z_{1}-289 Z_{2}+6000 Z_{4}
$$

$$
M_{2}=8.65-0.0829 Z_{1}-0.0479 Z_{2}+0.9954 Z_{4}
$$

$$
\Phi(-8.65)=0.2736 \times 10^{-17}
$$

$$
\begin{aligned}
& M_{3}=R_{1}-0.5 P_{1}-0.289 P_{2}=\left(6000 Z_{3}+60000\right)-0.5\left(1000 Z_{1}+10000\right) \\
& -0.289\left(1000 Z_{2}+10000\right) \\
& M_{3}=52110-500 Z_{1}-289 Z_{2}+6000 Z_{3} \\
& M_{3}=8.65-0.0829 Z_{1}-0.0479 Z_{2}+0.9954 Z_{3} \\
& \Phi(-8.65)=0.2736 \times 10^{-17} \\
& M_{4}=R_{6}-0.75 P_{1}-0.433 P_{2}=\left(6000 Z_{5}+60000\right)-0.75\left(1000 Z_{1}+10000\right) \\
& -0.433\left(1000 Z_{2}+10000\right) \\
& M_{4}=48170-750 Z_{1}-433 Z_{2}+6000 Z_{5} \\
& M_{4}=7.95-0.1237 Z_{1}-0.0714 Z_{2}+0.9897 Z_{5} \\
& \Phi(-7.95)=0.9823 \times 10^{-15} \\
& M_{5}=R_{6}-0.25 P_{1}-0.144 P_{2}=\left(6000 Z_{5}+60000\right)-0.25\left(1000 Z_{1}+10000\right) \\
& -0.144\left(1000 Z_{2}+10000\right) \\
& M_{5}=56060-250 Z_{1}-144 Z_{2}+6000 Z_{5} \\
& M_{5}=9.33-0.0416 Z_{1}-0.024 Z_{2}+0.9988 Z_{5} \\
& \Phi(-9.33)=0.553 \times 10^{-20}
\end{aligned}
$$

The coefficients of correlation are

$$
\begin{aligned}
& \rho_{12}=-0.0822 \times 0.0822+0.1424 \times 0.0479=0.00000658 \approx 0 \\
& \rho_{13}=-0.0822 \times 0.0829+0.1424 \times 0.0479+0.9864 \times 0.9954=0.9819 \\
& \rho_{14}=-0.0822 \times 0.1237+0.1424 \times 0.0714=-0.00000078 \approx 0 \\
& \rho_{15}=-0.0822 \times 0.0416+0.1424 \times 0.024=-0.00000192 \approx 0 \\
& \rho_{23}=0.0829 \times 0.0829+0.0479 \times 0.0479=0.0092 \\
& \rho_{24}=0.0829 \times 0.1237+0.0479 \times 0.0714=0.0137 \\
& \rho_{25}=0.0829 \times 0.0416+0.0479 \times 0.024=0.0046 \\
& \rho_{34}=0.0829 \times 0.1237+0.0479 \times 0.0714=0.0137 \\
& \rho_{35}=0.0829 \times 0.0416+0.0479 \times 0.024=0.0046 \\
& \rho_{45}=0.1237 \times 0.0416+0.0714 \times 0.024+0.9897 \times 0.9988=0.9953 \\
& \Phi(-7.95)=0.9823 \times 10^{-15}>\Phi(-8.65)=0.2736 \times 10^{-17}= \\
& \Phi(-8.65)=0.2736 \times 10^{-17}>\Phi(-9.26)=0.1098 \times 10^{-19}> \\
& \Phi(-9.33)=0.553 \times 10^{-20} \\
& \Phi_{2}\left(-\beta_{2},-\beta_{1} ; \rho\right)=\Phi_{2}(-8.65,-7.95 ; 0.0137)=6.534 \times 10^{-33} \\
& \Phi_{2}\left(-\beta_{3},-\beta_{1} ; \rho\right)=\Phi \Phi_{2}(-8.65,-7.95 ; 0.0137)=6.534 \times 10^{-33}
\end{aligned}
$$

$$
\begin{aligned}
& \Phi_{2}\left(-\beta_{3},-\beta_{2} ; \rho\right)=\Phi_{2}(-8.65,-8.65 ; 0.092)=5.472 \times 10^{-18} \\
& \Phi_{2}\left(-\beta_{4},-\beta_{1} ; \rho\right)=\Phi_{2}(-9.26,-7.95 ; 0)=1.0786 \times 10^{-35} \\
& \Phi_{2}\left(-\beta_{4},-\beta_{2} ; \rho\right)=\Phi_{2}(-9.26,-8.65 ; 0)=3.004 \times 10^{-38} \\
& \Phi_{2}\left(-\beta_{4},-\beta_{3} ; \rho\right)=\Phi_{2}(-9.26,-8.65 ; 0.9819)=1.04 \times 10^{-20} \\
& \Phi_{2}\left(-\beta_{5},-\beta_{1} ; \rho\right)=\Phi_{2}(-9.33,-7.95 ; 0.9953)=5.311 \times 10^{-21} \\
& \Phi_{2}\left(-\beta_{5},-\beta_{2} ; \rho\right)=\Phi_{2}(-9.33,-8.65 ; 0.0046)=2.14 \times 10^{-38} \\
& \Phi_{2}\left(-\beta_{5},-\beta_{3} ; \rho\right)=\Phi_{2}(-9.33,-8.65 ; 0.0046)=2.14 \times 10^{-38} \\
& \Phi_{2}\left(-\beta_{5},-\beta_{4} ; \rho\right)=\Phi_{2}(-9.33,-9.26 ; 0)=6.0719 \times 10^{-41}
\end{aligned}
$$

By using the Ditlevsen bounds:
upper bound: $P_{f} \leq \sum_{i=1}^{n} \Phi\left(-\beta_{i}\right)-\sum_{i=2, j<i}^{n} \max \Phi_{2}\left(-\beta_{i},-\beta_{j} ; p\right)$
$P_{f} \leq 9.878 \times 10^{-16}-\max \left[\Phi_{2}\left(-\beta_{2},-\beta_{1} ; \rho\right)\right]$
$-\max \left[\Phi_{2}\left(-\beta_{3},-\beta_{2} ; \rho\right), \Phi_{2}\left(-\beta_{3},-\beta_{1} ; \rho\right)\right]$
$-\max \left[\Phi\left(-\beta_{4},-\beta_{1} ; \rho\right), \Phi\left(-\beta_{4},-\beta_{2} ; \rho\right), \Phi\left(-\beta_{4},-\beta_{3} ; \rho\right)\right]$
$-\max \left[\Phi\left(-\beta_{5},-\beta_{1} ; \rho\right), \Phi\left(-\beta_{5},-\beta_{2} ; \rho\right), \Phi\left(-\beta_{5},-\beta_{3} ; p\right), \Phi\left(-\beta_{5},-\beta_{4} ; \rho\right)\right]$

$$
\begin{aligned}
& =9.878 \times 10^{-16}-6.534 \times 10^{-33}-5.472 \times 10^{-18}-1.04 \times 10^{-20}-5.311 \times 10^{-21} \\
& =9.823 \times 10^{-16}
\end{aligned}
$$

lower bound: $P_{f} \geq \Phi\left(-\beta_{1}\right)+\sum_{i=2}^{n} \max \left[\Phi\left(-\beta_{i}\right)-\sum_{j=1}^{i-1} \Phi_{2}\left(-\beta_{i},-\beta_{j} ; \rho\right), 0\right]$

$$
P_{f} \geq 9.823 \times 10^{-16}+\max \left[\Phi\left(-\beta_{2}\right)-\Phi_{2}\left(-\beta_{2},-\beta_{1} ; \rho\right), 0\right]
$$

$$
+\max \left[\Phi\left(-\beta_{3}\right)-\Phi_{2}\left(-\beta_{3},-\beta_{1} ; \rho\right)-\Phi_{2}\left(-\beta_{3},-\beta_{2} ; \rho\right), 0\right]+
$$

$$
\max \left[\Phi\left(-\beta_{4}\right)-\Phi_{2}\left(-\beta_{4},-\beta_{1} ; \rho\right)-\Phi_{2}\left(-\beta_{4},-\beta_{2} ; \rho\right)-\Phi_{2}\left(-\beta_{4},-\beta_{3} ; \rho\right), 0\right]
$$

$$
+
$$

$$
\max \left[\Phi\left(-\beta_{5}\right)-\Phi_{2}\left(-\beta_{5},-\beta_{1} ; \rho\right)-\Phi_{2}\left(-\beta_{5},-\beta_{2} ; \rho\right)-\Phi_{2}\left(-\beta_{5},-\beta_{3} ; \rho\right)\right.
$$

$$
\left.-\Phi_{2}\left(-\beta_{5},-\beta_{4} ; \rho\right), 0\right]
$$

$$
P_{f} \geq 9.823 \times 10^{-16}+0.2736 \times 10^{-17}-6.534 \times 10^{-33}+0.2736 \times 10^{-17}
$$

$$
-6.534 \times 10^{-33}-5.472 \times 10^{-18}+0.1098 \times 10^{-19}-1.0786 \times 10^{-35}-3.004 \times 10^{-38}
$$

$$
-1.04 \times 10^{-20}+0.533 \times 10^{-20}-5.311 \times 10^{-21}-2.14 \times 10^{-38}-2.14 \times 10^{-38}
$$

$$
-6.0719 \times 10^{-41}=9.823 \times 10^{-16}
$$

Therefore, one can get the probability of failure and probability index of the structure as follows:

$$
P_{f}=9.823 \times 10^{-16} \text { and } \beta=-\Phi^{-1}\left(P_{f}\right)=-7.95
$$

From the result one can expect that the failure bar six is the only dominant failure mode.

$$
M_{6}=R_{6}-0.75 P_{1}-0.433 P_{2}
$$

When $\mu_{p_{1}}=30000, \mu_{p_{2}}=30000, \mu_{R}=60000, \sigma_{p_{1}}=3000, \sigma_{p_{1}}=3000$, $\sigma_{R}=6000$

The structure reliability can be evaluated as follows:

$$
\begin{aligned}
& Z_{1}=\frac{R-\mu_{R}}{\sigma_{R}}, R=\sigma_{R} Z_{1}+\mu_{R}=6000 Z_{1}+60000 \\
& Z_{2}=\frac{P_{1}-\mu_{P_{1}}}{\sigma_{P_{1}}}, P_{1}=\sigma_{P_{1}} Z_{2}+\mu_{P_{1}}=3000 Z_{2}+30000 \\
& Z_{3}=\frac{P_{2}-\mu_{P_{2}}}{\sigma_{P_{2}}}, P_{2}=\sigma_{P_{2}} Z_{3}+\mu_{P_{2}}=3000 Z_{3}+30000 \\
& M_{6}=R_{6}-0.75 P_{1}-0.433 P_{2}=\left(6000 Z_{1}+60000\right)-0.75\left(3000 Z_{2}+30000\right) \\
& -0.433\left(3000 Z_{3}+30000\right) \\
& M=24510+6000 Z_{1}-2250 Z_{2}-1299 Z_{3} \\
& M=3.75+0.9177 Z_{1}-0.3441 Z_{2}-0.1987 Z_{3} \text { (after unification) } \\
& P_{f}=\Phi(-3.75)=8.837 \times 10^{-5}
\end{aligned}
$$

$$
\begin{aligned}
& \text { when } \mu_{p_{1}}=50000, \mu_{p_{2}}=50000, \mu_{R}=60000, \sigma_{p_{1}}=5000, \sigma_{p_{2}}=5000 \\
& \sigma_{R}=6000
\end{aligned}
$$

The Structure reliability can be evaluated as follows:

$$
\begin{aligned}
& Z_{1}=\frac{R-\mu_{R}}{\sigma_{R}}, R=\sigma_{R} Z_{1}+\mu_{R}=6000 Z_{1}+60000 \\
& Z_{2}=\frac{P_{1}-\mu_{P_{1}}}{\sigma_{P_{1}}}, P_{1}=\sigma_{P_{1}} Z_{2}+\mu_{P_{1}}=5000 Z_{2}+50000 \\
& Z_{3}=\frac{P_{2}-\mu_{P_{2}}}{\sigma_{P_{2}}}, P_{2}=\sigma_{P_{2}} Z_{3}+\mu_{P_{2}}=5000 Z_{3}+50000 \\
& M=R-0.75 P_{1}-0.433 P_{2}=\left(6000 Z_{1}+60000\right)-0.75\left(5000 Z_{2}+50000\right) \\
& -0.433\left(5000 Z_{3}+50000\right) \\
& M=850+6000 Z_{1}-3750 Z_{2}-2165 Z_{3} \\
& M=0.11+0.8109 Z_{1}-0.5068 Z_{2}-0.2926 Z_{3} \\
& P_{f}=\Phi(-0.11)=0.4562
\end{aligned}
$$

$$
\begin{aligned}
& \text { when } \mu_{p_{1}}=20000, \mu_{p_{2}}=20000, \mu_{R}=60000, \sigma_{p_{1}}=2000, \sigma_{p_{2}}=2000 \\
& \sigma_{R}=6000
\end{aligned}
$$

The Structure reliability can be evaluated as follows:

$$
\begin{aligned}
& Z_{1}=\frac{R-\mu_{R}}{\sigma_{R}}, R=\sigma_{R} Z_{1}+\mu_{R}=6000 Z_{1}+60000 \\
& Z_{2}=\frac{P_{1}-\mu_{P_{1}}}{\sigma_{P_{1}}}, P_{1}=\sigma_{P_{1}} Z_{2}+\mu_{P_{1}}=2000 Z_{2}+20000 \\
& Z_{3}=\frac{P_{2}-\mu_{P_{2}}}{\sigma_{P_{2}}}, P_{2}=\sigma_{P_{2}} Z_{3}+\mu_{P_{2}}=2000 Z_{3}+20000 \\
& M=R-0.75 P_{1}-0.433 P_{2}=\left(6000 Z_{1}+60000\right)-0.75\left(2000 Z_{2}+20000\right) \\
& -0.433\left(2000 Z_{3}+20000\right) \\
& M=36340+6000 Z_{1}-1500 Z_{2}-866 Z_{3} \\
& M=5.82+0.9608 Z_{1}-0.2402 Z_{2}-0.1387 Z_{3} \\
& P_{f}=\Phi(-5.82)=2.951 \times 10^{-9}
\end{aligned}
$$

Example 2. Consider the structure of example 3 of chapter 8 . Calculate the reliability of the structure. The expected values and standard deviations are given below. Assume that:

$$
R_{i}^{+}=R_{i}^{-}=60000,(i=1,2, \ldots, 6) \text { are independent. }
$$

$$
\mu_{L}=80000, \mu_{R}=60000, \sigma_{L}=8000, \sigma_{R}=6000
$$



$$
Z_{i}=\frac{X_{i}-\mu_{X_{i}}}{\sigma_{X_{i}}}, X_{i}=\sigma_{X_{i}} Z_{i}+\mu_{X_{i}}
$$

$$
R_{i}=\sigma_{R_{i}} Z_{i}+\mu_{R_{i}}=6000 Z_{i}+60000, L=\sigma_{L} Z_{7}+\mu_{L}=8000 Z_{7}+80000
$$

The safety margins of the structure are given as:

$$
\begin{aligned}
& M_{1}=R_{1}-0.5 L=2.77+0.8321 Z_{1}-0.5547 Z_{7} \\
& M_{2(1)}=R_{2}-R_{1}=0-0.7071 Z_{1}+0.7071 Z_{7} \\
& M_{3(1)}=R_{3}+1.414 R_{1}-1.414 L=2.06+0.5523 Z_{1}+0.3906 Z_{3}-0.7365 Z_{7} \\
& M_{4(1)}=R_{4}-1.4142 R_{1}=-2.39-0.8165 Z_{1}+0.5774 Z_{4}
\end{aligned}
$$

$$
\begin{aligned}
& M_{5(1)}=R_{5}+R_{1}-L=3.43+0.5145 Z_{1}+0.5145 Z_{5}-0.686 Z_{7} \\
& M_{6(1)}=R_{6}+R_{1}-L=3.43+0.5145 Z_{1}+0.5145 Z_{6}-0.686 Z_{7} \\
& M_{2}=R_{2}-0.5 L=2.77+0.8321 Z_{2}-0.5547 Z_{7} \\
& M_{1(2)}=R_{1}-R_{2}=0-0.7071 Z_{1}+0.7071 Z_{2} \\
& M_{3(2)}=R_{3}+1.414 R_{2}-1.4142 L=2.06+0.5523 Z_{2}+0.3906 Z_{3}-0.7365 Z_{7} \\
& M_{4(2)}=R_{4}-1.4142 R_{2}=-2.39-0.8165 Z_{2}+0.5774 Z_{4} \\
& M_{5(2)}=R_{5}+R_{2}-L=3.43+0.5145 Z_{2}+0.5145 Z_{5}-0.686 Z_{7} \\
& M_{6(2)}=R_{6}+R_{2}-L=3.43+0.5145 Z_{2}+0.5145 Z_{6}-0.686 Z_{7}
\end{aligned}
$$

$$
\begin{aligned}
& M_{3}=R_{3}-0.7071 L=0.42+0.7276 Z_{3}-0.686 Z_{7} \\
& M_{1(3)}=R_{1}+0.7071 R_{3}-L=2.06+0.5523 Z_{1}+0.3906 Z_{3}-0.7365 Z_{7} \\
& M_{2(3)}=R_{2}+0.7071 R_{3}-L=2.06+0.5523 Z_{2}+0.3906 Z_{3}-0.7365 Z_{7} \\
& M_{4(3)}=R_{4}+R_{3}-1.4142 L=0.49+0.4243 Z_{3}+0.4243 Z_{4}-0.8 Z_{7} \\
& M_{5(3)}=R_{5}-0.7071 R_{3}=2.39-0.5773 Z_{3}+0.8165 Z_{5}
\end{aligned}
$$

$$
M_{6(3)}=R_{6}-0.7071 R_{3}=2.39-0.5773 Z_{3}+0.8165 Z_{6}
$$

$$
\begin{aligned}
& M_{4}=R_{4}-0.7071 L=0.42+0.7276 Z_{4}-0.686 Z_{7} \\
& M_{1(4)}=R_{1}-0.7071 R_{4}=2.39+0.8165 Z_{1}-0.5773 Z_{4} \\
& M_{2(4)}=R_{2}-0.7071 R_{4}=2.39+0.8165 Z_{2}-0.5773 Z_{4} \\
& M_{3(4)}=R_{3}+R_{4}-1.4142 L=0.49+0.4243 Z_{3}+0.4243 Z_{4}-0.8 Z_{7} \\
& M_{5(4)}=R_{5}+0.7071 R_{4}-L=2.06+0.3906 Z_{4}+0.5523 Z_{5}-0.7365 Z_{7} \\
& M_{6(4)}=R_{6}+0.7071 R_{4}-L=2.06+0.3906 Z_{4}+0.5523 Z_{6}-0.7365 Z_{7}
\end{aligned}
$$

$$
M_{5}=R_{5}-0.5 L=2.77+0.8321 Z_{5}-0.5547 Z_{7}
$$

$$
M_{1(5)}=R_{1}+R_{5}-L=3.43+0.5145 Z_{1}+0.5145 Z_{5}-0.686 Z_{7}
$$

$$
M_{2(5)}=R_{2}+R_{5}-L=3.43+0.5145 Z_{2}+0.5145 Z_{5}-0.686 Z_{7}
$$

$$
M_{3(5)}=R_{3}-1.4142 R_{5}=-2.39+0.5774 Z_{3}-0.8165 Z_{5}
$$

$$
M_{4(5)}=R_{4}+1.414 R_{5}-1.414 L=2.06+0.3906 Z_{4}+0.5523 Z_{5}-0.7365 Z_{7}
$$

$$
M_{6(5)}=R_{6}-R_{5}=0-0.7071 Z_{5}+0.7071 Z_{6}
$$

$$
\begin{aligned}
& M_{6}=R_{6}-0.5 L=2.77+0.8321 Z_{6}-0.5547 Z_{7} \\
& M_{1(6)}=R_{1}+R_{6}-L=3.43+0.5145 Z_{1}+0.5145 Z_{6}-0.686 Z_{7} \\
& M_{2(6)}=R_{2}+R_{6}-L=3.43+0.5145 Z_{2}+0.5145 Z_{6}-0.686 Z_{7} \\
& M_{3(6)}=R_{3}-1.4142 R_{6}=-2.39+0.5774 Z_{3}-0.8165 Z_{6} \\
& M_{4(6)}=R_{4}+1.414 R_{6}-1.414 L=2.06+0.3906 Z_{4}+0.5523 Z_{6}-0.7365 Z_{7} \\
& M_{5(6)}=R_{5}-R_{6}=0+0.7071 Z_{5}-0.7071 Z_{6}
\end{aligned}
$$

There are thirty different failure modes, and the corresponding probabilities of failure are calculated as follows:

$$
M_{1}=2.77+0.8321 Z_{1}-0.5547 Z_{7}
$$

$$
M_{2(1)}=0-0.7071 Z_{1}+0.7071 Z_{7}
$$

$$
\rho=-0.5884, \Phi_{2}(-2.77,0 ;-0.5884)=0.0000393003
$$



$$
M_{1}=2.77+0.8321 Z_{1}-0.5547 Z_{7}
$$

$$
M_{3(1)}=2.06+0.5523 Z_{1}+0.3906 Z_{3}-0.7365 Z_{7}
$$

$$
\rho=0.8681, \Phi_{2}(-2.77,-2.06 ; 0.8681)=0.00242703
$$



$$
\begin{aligned}
& M_{1}=2.77+0.8321 Z_{1}-0.5547 Z_{7} \\
& M_{4(1)}=-2.39-0.8165 Z_{1}+0.5774 Z_{4} \\
& \rho=-0.6794, \Phi_{2}(-2.77,2.39 ;-0.6794)=0.00184232 \\
& M_{1}=2.77+0.8321 Z_{1}-0.5547 Z_{7} \\
& M_{5(1)}=3.43+0.5145 Z_{1}+0.5145 Z_{5}-0.686 Z_{7} \\
& \rho=0.8086, \Phi_{2}(-2.77,-3.43 ; 0.8086)=0.00019021 \\
& M_{1}=2.77+0.8321 Z_{1}-0.5547 Z_{7} \\
& M_{6(1)}=3.43+0.5145 Z_{1}+0.5145 Z_{6}-0.686 Z_{7} \\
& \rho=0.8086, \Phi_{2}(-2.77,-3.43 ; 0.8086)=0.00019021 \\
& M_{2}=2.77+0.8321 Z_{2}-0.5547 Z_{7} \\
& M_{1(2)}=0+0.7071 Z_{1}-0.7071 Z_{2} \\
& \rho=-0.5884, \Phi_{2}(-2.77,0 ;-0.5884)=0.0000393003 \\
& M_{2}=2.77+0.8321 Z_{2}-0.5547 Z_{7} \\
& M_{3(2)}=2.06+0.5523 Z_{2}+0.3906 Z_{3}-0.7365 Z_{7} \\
& \rho=0.8681, \Phi_{2}(-2.77,-2.06 ; 0.8681)=0.00242703 \\
& M_{2}=2.77+0.8321 Z_{2}-0.5547 Z_{7} \\
& M_{4(2)}=-2.39-0.8165 Z_{2}+0.5774 Z_{4} \\
& \rho=-0.6794, \Phi_{2}(-2.77,2.39 ;-0.6794)=0.00184232
\end{aligned}
$$

$$
\begin{array}{lc}
M_{2}=2.77+0.8321 Z_{2}-0.5547 Z_{7} & \\
M_{5(2)}=3.43+0.5145 Z_{2}+0.5145 Z_{5}-0.686 Z_{7} & M_{2} \\
\rho=0.8086, \Phi_{2}(-2.77,-3.43 ; 0.8086)=0.00019021 \\
M_{2}=2.77+0.8321 Z_{2}-0.5547 Z_{7} & \\
M_{6(2)}=3.43+0.5145 Z_{2}+0.5145 Z_{6}-0.686 Z_{7} & \\
\rho=0.8086, \Phi_{2}(-2.77,-3.43 ; 0.8086)=0.00019021 & \\
M_{3}=0.42+0.7276 Z_{3}-0.686 Z_{7} & M_{6(2)} \\
M_{1(3)}=2.06+0.5523 Z_{1}+0.3906 Z_{3}-0.7365 Z_{7} & \\
\rho=0.7894, \Phi_{2}(-0.42,-2.06 ; 0.7894)=0.0194841 & M_{1(3)} \\
M_{3}=0.42+0.7276 Z_{3}-0.686 Z_{7} & \\
M_{2(3)}=2.06+0.5523 Z_{2}+0.3906 Z_{3}-0.7365 Z_{7} & \\
\rho=0.7894, \Phi_{2}(-0.42,-2.06 ; 0.7894)=0.0194841 & M_{2} \\
M_{3}=0.42+0.7276 Z_{3}-0.686 Z_{7} & \\
M_{4(3)}=0.49+0.4243 Z_{3}+0.4243 Z_{4}-0.8 Z_{7} & \\
\hline=0.8575, \Phi_{2}(-0.42,-0.49 ; 0.8575)=0.246666 & M_{4(3)} \\
\hline
\end{array}
$$

$$
\begin{aligned}
& M_{3}=0.42+0.7276 Z_{3}-0.686 Z_{7} \\
& M_{5(3)}=2.39-0.5773 Z_{3}+0.8165 Z_{5} \\
& \rho=-0.42, \Phi_{2}(-0.42,-2.39 ;-0.42)=0.000369715 \\
& M_{3}=0.42+0.7276 Z_{3}-0.686 Z_{7} \\
& M_{6(3)}=2.39-0.5773 Z_{3}+0.8165 Z_{6} \\
& \rho=-0.42, \Phi_{2}(-0.42,-2.39 ;-0.42)=0.000369715 \\
& M_{4}=0.42+0.7276 Z_{4}-0.686 Z_{7} \\
& M_{1(4)}=2.39+0.8165 Z_{1}-0.5773 Z_{4} \\
& \rho=-0.42, \Phi_{2}(-0.42,-2.39 ;-0.42)=0.000369715 \\
& M_{4}=0.42+0.7276 Z_{4}-0.686 Z_{7} \\
& M_{2(4)}=2.39+0.8165 Z_{2}-0.5773 Z_{4} \\
& \rho=-0.42, \Phi_{2}(-0.42,-2.39 ;-0.42)=0.000369715 \\
& M_{4}=0.42+0.7276 Z_{4}-0.686 Z_{7} \\
& M_{3(4)}=0.49+0.4243 Z_{3}+0.4243 Z_{4}-0.8 Z_{7} \\
& \rho=0.8575, \Phi_{2}(-0.42,-0.49 ; 0.8575)=0.246666 \\
& M_{4}=0.42+0.7276 Z_{4}-0.686 Z_{7} \\
& M_{5(4)}=2.06+0.3906 Z_{4}+0.5523 Z_{5}-0.7365 Z_{7} \\
& \rho=0.7894, \Phi_{2}(-0.42,-2.06 ; 0.7894)=0.0194841
\end{aligned}
$$

$$
\begin{array}{lc}
M_{4}=0.42+0.7276 Z_{4}-0.686 Z_{7} & \\
M_{6(4)}=2.06+0.3906 Z_{4}+0.5523 Z_{6}-0.7365 Z_{7} \\
\rho=0.7894, \Phi_{2}(-0.42,-2.06 ; 0.7894)=0.0194841 & M_{4} \\
M_{5}=2.77+0.8321 Z_{5}-0.5547 Z_{7} & \\
M_{1(5)}=3.43+0.5145 Z_{1}+0.5145 Z_{5}-0.686 Z_{7} & \\
\rho=0.8086, \Phi_{2}(-2.77,-3.43 ; 0.8086)=0.00019021 & \\
M_{5}=2.77+0.8321 Z_{5}-0.5547 Z_{7} & M_{1(5)} \\
M_{2(5)}=3.43+0.5145 Z_{2}+0.5145 Z_{5}-0.686 Z_{7} & \\
\rho=0.8086, \Phi_{2}(-2.77,-3.43 ; 0.8086)=0.00019021 \\
M_{5}=2.77+0.8321 Z_{5}-0.5547 Z_{7} & M_{2(5)} \\
M_{3(5)}=-2.39+0.5774 Z_{3}-0.8165 Z_{5} & \\
\rho=-0.6794, \Phi_{2}(-2.77,2.39 ;-0.6974)=0.00184232 \\
M_{5}=2.77+0.8321 Z_{5}-0.5547 Z_{7} & M_{3} \\
M_{4(5)}=2.06+0.3906 Z_{4}+0.5523 Z_{5}-0.7365 Z_{7} & \\
\rho=0.8681, \Phi_{2}(-2.77,-2.06 ; 0.8681)=0.00242703 & \\
\hline M_{5} & \\
\hline M_{5}=2.77+0.8321 Z_{5}-0.5547 Z_{7} & \\
\hline
\end{array}
$$

$$
\begin{array}{lc}
M_{6}=2.77+0.8321 Z_{6}-0.5547 Z_{7} & \\
M_{1(6)}=3.43+0.5145 Z_{1}+0.5145 Z_{6}-0.686 Z_{7} \\
\rho=0.8086, \Phi_{2}(-2.77,-3.43 ; 0.8086)=0.00019021 \\
M_{6}=2.77+0.8321 Z_{6}-0.5547 Z_{7} & M_{6} \\
M_{2(6)}=3.43+0.5145 Z_{2}+0.5145 Z_{6}-0.686 Z_{7} \\
\rho=0.8086, \Phi_{2}(-2.77,-3.43 ; 0.8086)=0.00019021 & \\
M_{6}=2.77+0.8321 Z_{6}-0.5547 Z_{7} & \\
M_{3(6)}=-2.39+0.5774 Z_{3}-0.8165 Z_{6} & \\
\rho=-0.6794, \Phi_{2}(-2.77,2.39 ;-0.6974)=0.00184232 \\
M_{6}=2.77+0.8321 Z_{6}-0.5547 Z_{7} & M_{3(6)} \\
M_{4(6)}=2.06+0.3906 Z_{4}+0.5523 Z_{6}-0.7365 Z_{7} & \\
\rho=0.8681, \Phi_{2}(-2.77,-2.06 ; 0.8681)=0.00242703 \\
M_{6}=2.77+0.8321 Z_{6}-0.5547 Z_{7} & M_{6} \\
M_{5(6)}=0+0.7071 Z_{5}-0.7071 Z_{6} & \\
\rho=-0.5884, \Phi_{2}(-2.77,0 ;-0.5884)=0.0000393003 & M_{5} \\
\hline
\end{array}
$$

To reduce the calculation efforts, the reliability assessment is performed for the failure modes with higher probability of failure.

$$
\begin{aligned}
& M_{3}=0.42+0.7276 Z_{3}-0.686 Z_{7} \\
& M_{4(3)}=0.49+0.4243 Z_{3}+0.4243 Z_{4}-0.8 Z_{7} \\
& \rho=0.8575, \Phi_{2}(-0.42,-0.49 ; 0.8575)=0.246666 \\
& M_{4}=0.42+0.7276 Z_{4}-0.686 Z_{7} \\
& M_{3(4)}=0.49+0.4243 Z_{3}+0.4243 Z_{4}-0.8 Z_{7} \\
& \rho=0.8575, \Phi_{2}(-0.42,-0.49 ; 0.8575)=0.246666
\end{aligned}
$$



The reliability is then modelled as a series system.

and the equivalent series system:


The equivalent safety margins are calculated as follows:
$M_{3}=0.42+0.7276 Z_{3}-0.686 Z_{7}$
$M_{4(3)}=0.49+0.4243 Z_{3}+0.4243 Z_{4}-0.8 Z_{7}$
$\rho=0.8575, P_{f}=\Phi_{2}(-0.42,-0.49 ; 0.8575)=0.246666$


$$
\begin{aligned}
& \beta_{f}=0.68 \\
& \bar{\varepsilon}_{1}=(0.1,0,0) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-0.42 \\
-0.49
\end{array}\right]-\left[\begin{array}{ccc}
0.7276 & 0 & -0.686 \\
0.4243 & 0.4243 & -0.8
\end{array}\right]\left[\begin{array}{c}
0.1 \\
0 \\
0
\end{array}\right]=\left[\begin{array}{c}
-0.49 \\
-0.53
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-0.49,-0.53 ; 0.8575)\right)=-\Phi^{-1}(0.229583)=0.74 \\
& \bar{\varepsilon}_{2}=(0,0.1,0) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{l}
-0.42 \\
-0.49
\end{array}\right]-\left[\begin{array}{ccc}
0.7276 & 0 & -0.686 \\
0.4243 & 0.4243 & -0.8
\end{array}\right]\left[\begin{array}{c}
0 \\
0.1 \\
0
\end{array}\right]=\left[\begin{array}{c}
-0.42 \\
-0.53
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-0.42,-0.53 ; 0.8575)\right)=-\Phi^{-1}(0.239473)=0.71 \\
& \bar{\varepsilon}_{3}=(0,0,0.1) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-0.42 \\
-0.49
\end{array}\right]-\left[\begin{array}{ccc}
0.7276 & 0 & -0.686 \\
0.4243 & 0.4243 & -0.8
\end{array}\right]\left[\begin{array}{l}
0 \\
0 \\
0.1
\end{array}\right]=\left[\begin{array}{l}
-0.35 \\
-0.41
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-0.35,-0.41 ; 0.8575)\right)=-\Phi^{-1}(0.27168)=0.61 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{1}}\right|_{\bar{\varepsilon}=\overline{0}}=\frac{0.74-0.68}{0.1}=0.6
\end{aligned}
$$

Therefore,

$$
M_{1}^{e}=0.68+0.6189 Z_{3}+0.3094 Z_{4}-0.722 Z_{7}
$$

$$
\begin{aligned}
& M_{4}=0.42+0.7276 Z_{4}-0.686 Z_{7} \\
& M_{3(4)}=0.49+0.4243 Z_{3}+0.4243 Z_{4}-0.8 Z_{7} \\
& \rho=0.8575, \Phi_{2}(-0.42,-0.49 ; 0.8575)=0.246666
\end{aligned}
$$

$$
\beta_{f}=0.68
$$

$$
\bar{\varepsilon}_{1}=(0.1,0,0)
$$

$$
-\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-0.42 \\
-0.49
\end{array}\right]-\left[\begin{array}{ccc}
0 & 0.7276 & -0.686 \\
0.4243 & 0.4243 & -0.8
\end{array}\right]\left[\begin{array}{c}
0.1 \\
0 \\
0
\end{array}\right]=\left[\begin{array}{c}
-0.42 \\
-0.53
\end{array}\right]
$$

$$
\begin{aligned}
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{2}}\right|_{\bar{\varepsilon}=\overline{0}}=\frac{0.71-0.68}{0.1}=0.3 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{3}}\right|_{\bar{\varepsilon}=\overline{0}} \approx \frac{0.61-0.68}{0.1}=-0.7 \\
& \bar{u}^{e}=\left(u_{1}^{e}, u_{2}^{e}, u_{3}^{e}\right) \\
& =\left(\frac{0.6}{\sqrt{0.6^{2}+0.3^{2}+(-0.7)^{2}}}, \frac{0.3}{\sqrt{0.6^{2}+0.3^{2}+(-0.7)^{2}}}, \frac{-0.7}{\sqrt{0.6^{2}+0.3^{2}+(-0.7)^{2}}}\right) \\
& =(0.6189,0.3094,-0.722)
\end{aligned}
$$

$$
\begin{aligned}
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-0.42,-0.53 ; 0.8575)\right)=-\Phi^{-1}(0.23948)=0.71 \\
& \bar{\varepsilon}_{2}=(0,0.1,0) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-0.42 \\
-0.49
\end{array}\right]-\left[\begin{array}{cc}
0 & 0.7276-0.686 \\
0.4243 & 0.4243 \\
-0.8
\end{array}\right]\left[\begin{array}{c}
0 \\
0.1 \\
0
\end{array}\right]=\left[\begin{array}{c}
-0.49 \\
-0.53
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-0.49,-0.53 ; 0.8575)\right)=-\Phi^{-1}(0.22961)=0.74 \\
& \bar{\varepsilon}_{3}=(0,0,0.1) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-0.42 \\
-0.49
\end{array}\right]-\left[\begin{array}{cc}
0 & 0.7276-0.686 \\
0.4243 & 0.4243 \\
-0.8
\end{array}\right]\left[\begin{array}{c}
0 \\
0 \\
0.1
\end{array}\right]=\left[\begin{array}{l}
-0.35 \\
-0.41
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-0.35,-0.41 ; 0.8575)\right)=-\Phi^{-1}(0.27169)=0.61 \\
& \\
& \left.\begin{aligned}
\partial \beta_{f} \\
\partial \varepsilon_{1}
\end{aligned}\right|_{\bar{\varepsilon}=\bar{\varepsilon}} \approx \frac{0.71-0.68}{0.1}=0.3 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{2}}\right|_{\bar{\varepsilon}=\overline{0}} \approx \frac{0.74-0.68}{0.1}=0.6 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{3}}\right|_{\bar{\varepsilon}=\overline{0}} \approx \frac{0.61-0.68}{0.1}=-0.7
\end{aligned}
$$

$$
\begin{aligned}
\bar{u}^{e} & =\left(u_{1}^{e}, u_{2}^{e}, u_{3}^{e}\right) \\
& =\left(\frac{0.3}{\sqrt{0.6^{2}+0.3^{2}+(-0.7)^{2}}}, \frac{0.6}{\sqrt{0.6^{2}+0.3^{2}+(-0.7)^{2}}}, \frac{-0.7}{\sqrt{0.6^{2}+0.3^{2}+(-0.7)^{2}}}\right) \\
& =(0.3094,0.6189,-0.722)
\end{aligned}
$$

Therefore,

$$
M_{2}^{e}=0.68+0.3094 Z_{3}+0.6189 Z_{4}-0.722 Z_{7}
$$

The Ditlevsen bounds for the probability of failure of the series system are as follows:


$$
M_{1}^{e}=0.68+0.6189 Z_{3}+0.3094 Z_{4}-0.722 Z_{7}
$$

$$
M_{2}^{e}=0.68+0.3094 Z_{3}+0.6189 Z_{4}-0.722 Z_{7}, \rho_{12}=0.9043
$$

upper bound:

$$
\begin{aligned}
P_{f} & \leq \Phi\left(-\beta_{1}\right)+\Phi\left(-\beta_{2}\right)-\Phi_{2}\left(-\beta_{2},-\beta_{1} ; p\right) \\
& =\Phi(-0.68)+\Phi(-0.68)-\Phi \Phi_{2}(-0.68,-0.68 ; 0.9043) \\
& =0.24667+0.24667-0.192757=0.3006
\end{aligned}
$$

The lower bound:

$$
\begin{aligned}
P_{f} & \geq \Phi\left(-\beta_{1}\right)+\max \left[\Phi\left(-\beta_{2}\right)-\Phi_{2}\left(-\beta_{2},-\beta_{1} ; \rho\right), 0\right] \\
& =\Phi(-0.68)+\Phi(-0.68)-\Phi_{2}(-0.68,-0.68 ; 0.9043) \\
& =0.24667+0.24667-0.192757=0.3006
\end{aligned}
$$

Therefore, an estimate of the structural reliability is

$$
P_{f}=0.3006, \beta=-\Phi^{-1}(0.3006)=0.52
$$

Example 3 Consider the same structure of example 2 with different external load $\mu_{L}=60000, \sigma_{L}=6000$. Calculate the structural reliability.

By the same procedure used in example 2, one can obtain the following results:
For $\mathrm{L}=60000$, the ANSYS PROGRAMS and the corresponding results are listed in the appendixes: E,E1,E2,E3,E4,E5,J,J1,J2,J3,J4,J5,J6,K,K1,K2,K3,K4,and K5.

$$
\begin{aligned}
& M_{3}=R_{3}{ }^{+}-S_{3}(\text { tesnion })=R_{3}-42426=R_{3}-0.7071 L \\
& M_{5(3)}=R_{5}^{-}+S_{5}(\text { compression })=R_{5}-42426=R_{5}-0.7071 R_{3} \\
& M_{6(3)}=R_{6}^{-}+S_{6}(\text { compression })=R_{6}-42426=R_{6}-0.7071 R_{3}
\end{aligned}
$$

$$
M_{4}=R_{4}^{-}+S_{4}(\text { compression })=R_{4}-42426=R_{4}-0.7071 L
$$

$$
M_{1(4)}=R_{1}^{+}-S_{1}(\text { tesnion })=R_{1}-42426=R_{1}-0.7071 R_{4}
$$

$$
M_{2(4)}=R_{2}^{+}-S_{2}(\text { tesnion })=R_{2}-42426=R_{2}-0.7071 R_{4}
$$

For the normalization: $Z_{i}=\frac{X_{i}-\mu_{X_{i}}}{\sigma_{X_{i}}}, X_{i}=\sigma_{X_{i}} Z_{i}+\mu_{X_{i}}$

$$
\begin{aligned}
& R_{i}=\sigma_{R_{i}} Z_{i}+\mu_{R_{i}}=6000 Z_{i}+60000,(i=1, \ldots, 6) \\
& L=\sigma_{L} Z_{7}+\mu_{L}=6000 Z_{7}+60000
\end{aligned}
$$

$$
M_{3}=R_{3}-0.7071 L=\left(6000 Z_{3}+60000\right)-0.7071\left(6000 Z_{7}+60000\right)
$$

$$
\Rightarrow 2.39+0.8165 Z_{3}-0.5773 Z_{7}
$$

$$
M_{5(3)}=R_{5}-0.7071 R_{3}=\left(6000 Z_{5}+60000\right)-0.7071\left(6000 Z_{3}+60000\right)
$$

$$
\Rightarrow 2.39-0.5773 Z_{3}+0.8165 Z_{5}
$$

$$
M_{6(3)}=R_{6}-0.7071 R_{3}=\left(6000 Z_{6}+60000\right)-0.7071\left(6000 Z_{3}+60000\right)
$$

$$
\Rightarrow 2.39-0.5773 Z_{3}+0.8165 Z_{6}
$$

$$
\begin{aligned}
& M_{4}=R_{4}-0.7071 L=\left(6000 Z_{4}+60000\right)-0.7071\left(6000 Z_{7}+60000\right) \\
& \quad \Rightarrow 2.39+0.8165 Z_{4}-0.5773 Z_{7} \\
& M_{1(4)}=R_{1}-0.7071 R_{4}=\left(6000 Z_{1}+60000\right)-0.7071\left(6000 Z_{4}+60000\right)
\end{aligned}
$$

$$
\Rightarrow 2.39+0.8165 Z_{1}-0.5773 Z_{4}
$$

$$
\begin{aligned}
& M_{2(4)}=R_{2}-0.7071 R_{4}=\left(6000 Z_{2}+60000\right)-0.7071\left(6000 Z_{4}+60000\right) \\
& \Rightarrow 2.39+0.8165 Z_{2}-0.5773 Z_{4} \\
& M_{3}=2.39+0.8165 Z_{3}-0.5773 Z_{7} \\
& M_{5(3)}=2.39-0.5773 Z_{3}+0.8165 Z_{5}, \rho=-0.4714 \\
& \Phi_{2}(-2.39,-2.39 ;-0.4714)=0.1566 \times 10^{-6}, \beta=5.12 \\
& M_{3}=2.39+0.8165 Z_{3}-0.5773 Z_{7} \\
& M_{6(3)}=2.39-0.5773 Z_{3}+0.8165 Z_{6}, \rho=-0.4714 \\
& M_{4}=2.39+0.8165 Z_{4}-0.5773 Z_{7} \\
& M_{1(4)}=2.39+0.8165 Z_{4}-0.5773 Z_{7}, \rho=-0.4714 \\
& \Phi_{2}(-2.39,-2.39 ;-0.4714)=0.1566 \times 10^{-6}, \beta=5.12 \\
& M_{4}=2.39+0.8165 Z_{4}-0.5773 Z_{7} \\
& M_{2(4)}=2.39+0.8165 Z_{2}-0.5773 Z_{4}, \rho=-0.4714
\end{aligned}
$$

The reliability is modelled as a series system:


The equivalent series system is


The equivalent safety margins are calculatedd as follows:

$$
\begin{aligned}
& M_{3}=2.39+0.8165 Z_{3}-0.5773 Z_{7} \\
& M_{5(3)}=2.39-0.5773 Z_{3}+0.8165 Z_{5}, \rho=-0.4714
\end{aligned}
$$



$$
\Phi_{2}(-2.39,-2.39 ;-0.4714)=0.1566 \times 10^{-6}, \beta=5.12
$$

$$
\bar{\varepsilon}_{1}=(0.1,0,0)
$$

$$
-\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-2.39 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0.8165 & 0 & -0.5773 \\
-0.5773 & 0.8165 & 0
\end{array}\right]\left[\begin{array}{c}
0.1 \\
0 \\
0
\end{array}\right]=\left[\begin{array}{c}
-2.47 \\
-2.33
\end{array}\right]
$$

$$
\beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-2.47,-2.33 ;-0.47)\right)=-\Phi^{-1}\left(0.1415 \times 10^{-6}\right)=5.14
$$

$$
\begin{aligned}
& \bar{\varepsilon}_{2}=(0,0.1,0) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-2.39 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0.8165 & 0 & -0.5773 \\
-0.5773 & 0.8165 & 0
\end{array}\right]\left[\begin{array}{c}
0 \\
0.1 \\
0
\end{array}\right]=\left[\begin{array}{c}
-2.39 \\
-2.47
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-2.39,-2.47 ;-0.47)\right)=-\Phi^{-1}\left(0.1055 \times 10^{-6}\right)=5.19 \\
& \bar{\varepsilon}_{3}=(0,0,0.1) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{l}
-2.39 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0.8165 & 0 & -0.5773 \\
-0.5773 & 0.8165 & 0
\end{array}\right]\left[\begin{array}{l}
0 \\
0 \\
0.1
\end{array}\right]=\left[\begin{array}{l}
-2.33 \\
-2.39
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-2.33,-2.39 ;-0.47)\right)=-\Phi^{-1}\left(0.2095 \times 10^{-6}\right)=5.06 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{1}}\right|_{\bar{\varepsilon}=\overline{0}}=\frac{5.14-5.12}{0.1}=0.2 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{2}}\right|_{\bar{\varepsilon}=\overline{0}}=\frac{5.19-5.12}{0.1}=0.7 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{3}}\right|_{\bar{\varepsilon}=\overline{0}} \approx \frac{5.06-5.12}{0.1}=-0.6
\end{aligned}
$$

$$
\begin{aligned}
\bar{u}^{e} & =\left(u_{1}^{e}, u_{2}^{e}, u_{3}^{e}\right) \\
& =\left(\frac{0.2}{\sqrt{0.2^{2}+0.7^{2}+(-0.6)^{2}}}, \frac{0.7}{\sqrt{0.2^{2}+0.7^{2}+(-0.6)^{2}}}, \frac{-0.6}{\sqrt{0.2^{2}+0.7^{2}+(-0.6)^{2}}}\right) \\
& =(0.212,0.742,-0.636)
\end{aligned}
$$

Therefore,

$$
M_{1}^{e}=5.12+0.212 Z_{3}+0.741 Z_{5}-0.636 Z_{7}
$$

$$
M_{3}=2.39+0.8165 Z_{3}-0.5773 Z_{7}
$$

$$
M_{6(3)}=2.39-0.5773 Z_{3}+0.8165 Z_{6}, \rho=-0.4714
$$



$$
\Phi_{2}(-2.39,-2.39 ;-0.4714)=0.1566 \times 10^{-6}, \beta=5.12
$$

$$
\bar{\varepsilon}_{1}=(0.1,0,0)
$$

$$
-\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-2.39 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0.8165 & 0 & -0.5773 \\
-0.5773 & 0.8165 & 0
\end{array}\right]\left[\begin{array}{c}
0.1 \\
0 \\
0
\end{array}\right]=\left[\begin{array}{l}
-2.47 \\
-2.33
\end{array}\right]
$$

$$
\beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-2.47,-2.33 ;-0.47)\right)=-\Phi^{-1}\left(0.1415 \times 10^{-6}\right)=5.14
$$

$$
\bar{\varepsilon}_{2}=(0,0.1,0)
$$

$$
\begin{aligned}
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-2.39 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0.8165 & 0 & -0.5773 \\
-0.5773 & 0.8165 & 0
\end{array}\right]\left[\begin{array}{c}
0 \\
0.1 \\
0
\end{array}\right]=\left[\begin{array}{l}
-2.39 \\
-2.47
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-2.39,-2.47 ;-0.47)\right)=-\Phi^{-1}\left(0.1055 \times 10^{-6}\right)=5.19
\end{aligned}
$$

$$
\bar{\varepsilon}_{3}=(0,0,0.1)
$$

$$
-\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-2.39 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0.8165 & 0 & -0.5773 \\
-0.5773 & 0.8165 & 0
\end{array}\right]\left[\begin{array}{l}
0 \\
0 \\
0.1
\end{array}\right]=\left[\begin{array}{l}
-2.33 \\
-2.39
\end{array}\right]
$$

$$
\beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-2.33,-2.39 ;-0.47)\right)=-\Phi^{-1}\left(0.2095 \times 10^{-6}\right)=5.06
$$

$$
\frac{\partial \beta_{f}}{\left.\partial \varepsilon_{1}\right|_{\bar{\varepsilon}=\overline{0}}}=\frac{5.14-5.12}{0.1}=0.2
$$

$$
\frac{\partial \beta_{f}}{\left.\partial \varepsilon_{2}\right|_{\bar{\varepsilon}=\bar{o}}}=\frac{5.19-5.12}{0.1}=0.7
$$

$$
\left.\frac{\partial \beta_{f}}{\partial \varepsilon_{3}}\right|_{\bar{\varepsilon}=\overline{0}}=\frac{5.06-5.12}{0.1}=-0.6
$$

$$
\begin{aligned}
\bar{u}^{e} & =\left(u_{1}^{e}, u_{2}^{e}, u_{3}^{e}\right) \\
& =\left(\frac{0.2}{\sqrt{0.2^{2}+0.7^{2}+(-0.6)^{2}}}, \frac{0.7}{\sqrt{0.2^{2}+0.7^{2}+(-0.6)^{2}}}, \frac{-0.6}{\sqrt{0.2^{2}+0.7^{2}+(-0.6)^{2}}}\right) \\
& =(0.212,0.742,-0.636)
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
& M_{2}^{e}=5.12+0.212 Z_{3}+0.741 Z_{6}-0.636 Z_{7} \\
& M_{4}=2.39+0.8165 Z_{4}-0.5773 Z_{7} \\
& M_{1(4)}=2.39+0.8165 Z_{1}-0.5773 Z_{4}, \rho=-0.4714 \\
& \Phi_{2}(-2.39,-2.39 ;-0.4714)=0.1566 \times 10^{-6}, \beta=5.12 \\
& \bar{\varepsilon}_{1}=(0.1,0,0)
\end{aligned}
$$



$$
-\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-2.39 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0 & 0.8165 & -0.5773 \\
0.8165 & -0.5773 & 0
\end{array}\right]\left[\begin{array}{c}
0.1 \\
0 \\
0
\end{array}\right]=\left[\begin{array}{l}
-2.39 \\
-2.47
\end{array}\right]
$$

$$
\beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-2.39,-2.47 ;-0.47)\right)=-\Phi^{-1}\left(0.1055 \times 10^{-6}\right)=5.19
$$

$$
\bar{\varepsilon}_{2}=(0,0.1,0)
$$

$$
\begin{aligned}
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{cc}
-2.39 \\
-2.39
\end{array}\right]\left[\begin{array}{ccc}
0 & 0.8165 & -0.5773 \\
0.8165 & -0.5773 & 0
\end{array}\right]\left[\begin{array}{c}
0 \\
0.1 \\
0
\end{array}\right]=\left[\begin{array}{l}
-2.47 \\
-2.33
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-2.47,-2.33 ;-0.47)\right)=-\Phi^{-1}\left(0.1415 \times 10^{-6}\right)=5.14 \\
& \bar{\varepsilon}_{3}=(0,0,0.1) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-2.39 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0 & 0.8165 & -0.5773 \\
0.8165 & -0.5773 & 0
\end{array}\right]\left[\begin{array}{l}
0 \\
0 \\
0.1
\end{array}\right]=\left[\begin{array}{l}
-2.33 \\
-2.39
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-2.33,-2.39 ;-0.47)\right)=-\Phi^{-1}\left(0.2095 \times 10^{-6}\right)=5.06 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{1}}\right|_{\bar{\varepsilon}=\overline{0}} \approx \frac{5.19-5.12}{0.1}=0.7 \\
& \left.\frac{\partial \beta_{f}}{}\right|_{\partial \varepsilon_{2}} \approx \frac{5.14-5.12}{0.1}=0.2 \\
& \frac{\partial \beta_{f}}{}=\overline{0} \\
& \left.\frac{2}{\partial \varepsilon_{3}}\right|_{\bar{\varepsilon}=\overline{0}} \approx \frac{5.06-5.12}{0.1}=-0.6
\end{aligned}
$$

$$
\begin{aligned}
\bar{u}^{e} & =\left(u_{1}^{e}, u_{2}^{e}, u_{3}^{e}\right) \\
& =\left(\frac{0.7}{\sqrt{0.2^{2}+0.7^{2}+(-0.6)^{2}}}, \frac{0.2}{\sqrt{0.2^{2}+0.7^{2}+(-0.6)^{2}}}, \frac{-0.6}{\sqrt{0.2^{2}+0.7^{2}+(-0.6)^{2}}}\right) \\
& =(0.742,0.212,-0.636)
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
& M_{3}^{e}=5.12+0.742 Z_{1}+0.212 Z_{4}-0.636 Z_{7} \\
& M_{4}=2.39+0.8165 Z_{4}-0.5773 Z_{7} \\
& M_{2(4)}=2.39+0.8165 Z_{2}-0.5773 Z_{4}, \rho=-0.4714
\end{aligned}
$$

$$
\Phi_{2}(-2.39,-2.39 ;-0.4714)=0.1566 \times 10^{-6}, \beta=5.12
$$

$$
\bar{\varepsilon}_{1}=(0.1,0,0)
$$

$$
-\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{l}
-2.39 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0 & 0.8165 & -0.5773 \\
0.8165 & -0.5773 & 0
\end{array}\right]\left[\begin{array}{c}
0.1 \\
0 \\
0
\end{array}\right]=\left[\begin{array}{l}
-2.39 \\
-2.47
\end{array}\right]
$$

$$
\beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-2.39,-2.47 ;-0.47)\right)=-\Phi^{-1}\left(0.1055 \times 10^{-6}\right)=5.19
$$

$$
\bar{\varepsilon}_{2}=(0,0.1,0)
$$

$$
\begin{aligned}
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-2.39 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0 & 0.8165 & -0.5773 \\
0.8165 & -0.5773 & 0
\end{array}\right]\left[\begin{array}{c}
0 \\
0.1 \\
0
\end{array}\right]=\left[\begin{array}{l}
-2.47 \\
-2.33
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-2.47,-2.33 ;-0.47)\right)=-\Phi^{-1}\left(0.1415 \times 10^{-6}\right)=5.14
\end{aligned}
$$

$$
\bar{\varepsilon}_{3}=(0,0,0.1)
$$

$$
-\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{l}
-2.39 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0 & 0.8165 & -0.5773 \\
0.8165 & -0.5773 & 0
\end{array}\right]\left[\begin{array}{c}
0 \\
0 \\
0.1
\end{array}\right]=\left[\begin{array}{l}
-2.33 \\
-2.39
\end{array}\right]
$$

$$
\beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-2.33,-2.39 ;-0.47)\right)=-\Phi^{-1}\left(0.2095 \times 10^{-6}\right)=5.06
$$

$$
\left.\frac{\partial \beta_{f}}{\partial \varepsilon_{1}}\right|_{\bar{\varepsilon}=\overline{0}} \approx \frac{5.19-5.12}{0.1}=0.7
$$

$$
\left.\frac{\partial \beta_{f}}{\partial \varepsilon_{2}}\right|_{\bar{\varepsilon}=\overline{0}} \approx \frac{5.14-5.12}{0.1}=0.2
$$

$$
\frac{\partial \beta_{f}}{\left.\partial \varepsilon_{3}\right|_{\bar{\varepsilon}=\overline{0}}}=\frac{5.06-5.12}{0.1}=-0.6
$$

$$
\begin{aligned}
\bar{u}^{e} & =\left(u_{1}^{e}, u_{2}^{e}, u_{3}^{e}\right) \\
& =\left(\frac{0.7}{\sqrt{0.2^{2}+0.7^{2}+(-0.6)^{2}}}, \frac{0.2}{\sqrt{0.2^{2}+0.7^{2}+(-0.6)^{2}}}, \frac{-0.6}{\sqrt{0.2^{2}+0.7^{2}+(-0.6)^{2}}}\right) \\
& =(0.742,0.212,-0.636)
\end{aligned}
$$

Therefore,

$$
M_{4}^{e}=5.12+0.742 Z_{2}+0.212 Z_{4}-0.636 Z_{7}
$$

The Ditlevsen bounds for the probability of failure of the series system are:


$$
\begin{aligned}
& M_{1}^{e}=5.12+0.212 Z_{3}+0.741 Z_{5}-0.636 Z_{7}, \rho_{12}=0.4494, \rho_{13}=0.4045 \\
& M_{2}^{e}=5.12+0.212 Z_{3}+0.741 Z_{6}-0.636 Z_{7}, \rho_{14}=0.4045, \rho_{23}=0.4045 \\
& M_{3}^{e}=5.12+0.742 Z_{1}+0.212 Z_{4}-0.636 Z_{7}, \rho_{24}=0.4045, \rho_{34}=0.4494 \\
& M_{4}^{e}=5.12+0.742 Z_{2}+0.212 Z_{4}-0.636 Z_{7}
\end{aligned}
$$

upper bound: $P_{f} \leq \sum_{i=1}^{n} \Phi\left(-\beta_{i}\right)-\sum_{i=2, j<i}^{n} \max \Phi_{2}\left(-\beta_{i},-\beta_{j} ; \rho\right)$

$$
\begin{aligned}
& P_{f} \leq \Phi\left(-\beta_{1}\right)+\Phi\left(-\beta_{2}\right)+\Phi\left(-\beta_{3}\right)+\Phi\left(-\beta_{4}\right)-\max \left[\Phi_{2}\left(-\beta_{2},-\beta_{1} ; \rho\right)\right] \\
& -\max \left[\Phi_{2}\left(-\beta_{3},-\beta_{2} ; \rho\right), \Phi_{2}\left(-\beta_{3},-\beta_{1} ; \rho\right)\right] \\
& -\max \left[\Phi\left(-\beta_{4},-\beta_{1} ; \rho\right), \Phi\left(-\beta_{4},-\beta_{2} ; \rho\right), \Phi\left(-\beta_{4},-\beta_{3} ; \rho\right)\right] \\
& \quad=4 \times 0.1536 \times 10^{-6}-1.7501 \times 10^{-10}-9.0809 \times 10^{-11}-1.7501 \times 10^{-10} \\
& \quad=6.1396 \times 10^{-7}
\end{aligned}
$$

lower bound: $P_{f} \geq \Phi\left(-\beta_{1}\right)+\sum_{i=2}^{n} \max \left[\Phi\left(-\beta_{i}\right)-\sum_{j=1}^{i-1} \Phi_{2}\left(-\beta_{i},-\beta_{j} ; p\right), 0\right]$

$$
\begin{aligned}
& P_{f} \geq \Phi\left(-\beta_{1}\right)+\max \left[\Phi\left(-\beta_{2}\right)-\Phi_{2}\left(-\beta_{2},-\beta_{1} ; \rho\right), 0\right] \\
& \quad+\max \left[\Phi\left(-\beta_{3}\right)-\Phi_{2}\left(-\beta_{3},-\beta_{1} ; \rho\right)-\Phi_{2}\left(-\beta_{3},-\beta_{2} ; \rho\right), 0\right]+
\end{aligned}
$$

$$
\max \left[\Phi\left(-\beta_{4}\right)-\Phi_{2}\left(-\beta_{4},-\beta_{1} ; \rho\right)-\Phi_{2}\left(-\beta_{4},-\beta_{2} ; \rho\right)-\Phi_{2}\left(-\beta_{4},-\beta_{3} ; \rho\right), 0\right]
$$

$$
=0.1536 \times 10^{-6}+0.1536 \times 10^{-6}-1.7501 \times 10^{-10}+0.1536 \times 10^{-\epsilon}
$$

$$
-9.0809 \times 10^{-11}-9.0809 \times 10^{-11}+0.1536 \times 10^{-6}-9.0809 \times 10^{-11}
$$

$$
-9.0809 \times 10^{-11}-1.7501 \times 10^{-10}=6.1369 \times 10^{-7}
$$

$6.1369 \times 10^{-7} \leq P_{f} \leq 6.1396 \times 10^{-7}$

$$
P_{f} \approx 6.1383 \times 10^{-7}, \beta=4.85
$$

Example 4. Consider the same structure of example 2 with different external load $\mu_{L}=40000, \sigma_{L}=4000$. Calculate the structural reliability.

By the same procedure used in example 2, one can obtain the following results:
For $\mathrm{L}=4000$, the ANSYS PROGRAMS and the corresponding results are listed in the appendixes: E,E1,E2,E3,E4,E5,H,H1,H2,H3,H4,H5,H6,I,I1,I2,I3,I4, and I5.
$M_{3}=R_{3}{ }^{+}-S_{3}($ tesnion $)=R_{3}-28284=R_{3}-0.7071 L$
$M_{5(3)}=R_{5}^{-}+S_{5}($ compression $)=R_{5}-42426=R_{5}-0.7071 R_{3}$
$M_{6(3)}=R_{6}^{-}+S_{6}($ compression $)=R_{6}-42426=R_{6}-0.7071 R_{3}$
$M_{4}=R_{4}^{-}+S_{4}($ compression $)=R_{4}-28284=R_{4}-0.7071 L$
$M_{1(4)}=R_{1}{ }^{+}-S_{1}($ tesnion $)=R_{1}-42426=R_{1}-0.7071 R_{4}$
$M_{2(4)}=R_{2}{ }^{+}-S_{2}($ tesnion $)=R_{2}-42426=R_{2}-0.7071 R_{4}$

For the normalization: $Z_{i}=\frac{X_{i}-\mu_{X_{i}}}{\sigma_{X_{i}}}, X_{i}=\sigma_{X_{i}} Z_{i}+\mu_{X_{i}}$
$R_{i}=\sigma_{R_{i}} Z_{i}+\mu_{R_{i}}=6000 Z_{i}+60000,(i=1, \ldots, 6)$.

$$
\begin{aligned}
& L=\sigma_{L} Z_{7}+\mu_{L}=4000 Z_{7}+40000 \\
& M_{3}=R_{3}-0.7071 L=\left(6000 Z_{3}+60000\right)-0.7071\left(4000 Z_{7}+40000\right) \\
& \quad \Rightarrow 4.78+0.9045 Z_{3}-0.4264 Z_{7} \\
& M_{5(3)}=R_{5}-0.7071 R_{3}=\left(6000 Z_{5}+60000\right)-0.7071\left(6000 Z_{3}+60000\right) \\
& \quad \Rightarrow 2.39-0.5773 Z_{3}+0.8165 Z_{5} \\
& M_{6(3)}=R_{6}-0.7071 R_{3}=\left(6000 Z_{6}+60000\right)-0.7071\left(6000 Z_{3}+60000\right) \\
& \quad \Rightarrow 2.39-0.5773 Z_{3}+0.8165 Z_{6}
\end{aligned}
$$

$$
M_{4}=R_{4}-0.7071 L=\left(6000 Z_{4}+60000\right)-0.7071\left(4000 Z_{7}+40000\right)
$$

$$
\Rightarrow 4.78+0.9045 Z_{4}-0.4264 Z_{7}
$$

$$
M_{1(4)}=R_{1}-0.7071 R_{4}=\left(6000 Z_{1}+60000\right)-0.7071\left(6000 Z_{4}+60000\right)
$$

$$
\Rightarrow 2.39+0.8165 Z_{1}-0.5773 Z_{4}
$$

$$
M_{2(4)}=R_{2}-0.7071 R_{4}=\left(6000 Z_{2}+60000\right)-0.7071\left(6000 Z_{4}+60000\right)
$$

$$
\Rightarrow 2.39+0.8165 Z_{2}-0.5773 Z_{4}
$$

$$
M_{3}=4.78+0.9045 Z_{3}-0.4264 Z_{7}
$$

$$
M_{5(3)}=2.39-0.5773 Z_{3}+0.8165 Z_{5}, \rho=-0.5222
$$

$$
\Phi_{2}(-4.78,-2.39 ;-0.5222)=0.2571 \times 10^{-14}, \beta=7.83
$$



$$
\begin{aligned}
& M_{3}=4.78+0.9045 Z_{3}-0.4264 Z_{7} \\
& M_{6(3)}=2.39-0.5773 Z_{3}+0.8165 Z_{6}, \rho=-0.5222 \\
& \Phi_{2}(-4.78,-2.39 ;-0.5222)=0.2571 \times 10^{-14}, \beta=7.83 \\
& M_{4}=4.78+0.9045 Z_{4}-0.4264 Z_{7}, \\
& M_{1(4)}=2.39+0.8165 Z_{4}-0.5773 Z_{7}, \rho=-0.5222 \\
& \Phi_{2}(-4.78,-2.39 ;-0.5222)=0.2571 \times 10^{-14}, \beta=7.83 \\
& M_{4}=4.78+0.9045 Z_{4}-0.4264 Z_{7} \\
& M_{2(4)}=2.39+0.8165 Z_{2}-0.5773 Z_{4}, \rho=-0.5222
\end{aligned}
$$

The reliability is modelled as a series system:


The equivalent series system is


The equivalent safety margins are calculated as follows:

$$
\begin{aligned}
& M_{3}=4.78+0.9045 Z_{3}-0.4264 Z_{7} \\
& M_{5(3)}=2.39-0.5773 Z_{3}+0.8165 Z_{5}, \rho=-0.5222 \\
& \Phi_{2}(-4.78,-2.39 ;-0.5222)=0.2571 \times 10^{-14}, \beta=7.83 \\
& \bar{\varepsilon}_{1}=(0.1,0,0) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
M_{3} \\
-4.78 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0.9045 & 0 & -0.4264 \\
-0.5773 & 0.8165 & 0
\end{array}\right]\left[\begin{array}{c}
0.1 \\
0 \\
0
\end{array}\right]=\left[\begin{array}{l}
-4.87 \\
-2.33
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-4.87,-2.33 ;-0.52)\right)=-\Phi^{-1}\left(0.1805 \times 10^{-14}\right)=7.87
\end{aligned}
$$

$$
\bar{\varepsilon}_{2}=(0,0.1,0)
$$

$$
-\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{l}
-4.78 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0.9045 & 0 & -0.4264 \\
-0.5773 & 0.8165 & 0
\end{array}\right]\left[\begin{array}{c}
0 \\
0.1 \\
0
\end{array}\right]=\left[\begin{array}{c}
-4.78 \\
-2.47
\end{array}\right]
$$

$$
\beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-4.78,-2.47 ;-0.52)\right)=-\Phi^{-1}\left(0.1464 \times 10^{-14}\right)=7.89
$$

$$
\begin{aligned}
& \bar{\varepsilon}_{3}=(0,0,0.1) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-4.78 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0.9045 & 0 & -0.4264 \\
-0.5773 & 0.8165 & 0
\end{array}\right]\left[\begin{array}{c}
0 \\
0 \\
0.1
\end{array}\right]=\left[\begin{array}{l}
-4.74 \\
-2.39
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-4.74,-2.39 ;-0.52)\right)=-\Phi^{-1}\left(0.3616 \times 10^{-14}\right)=7.78 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{1}}\right|_{\bar{\varepsilon}=\overline{0}}=\frac{7.87-7.83}{0.1}=0.4 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{2}}\right|_{\bar{\varepsilon}=\overline{0}}=\frac{7.89-7.83}{0.1}=0.6 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{3}}\right|_{\bar{\varepsilon}=\overline{0}} \approx \frac{7.78-7.83}{0.1}=-0.5 \\
& \bar{u}^{e}=\left(u_{1}^{e}, u_{2}^{e}, u_{3}^{e}\right) \\
& =\left(\frac{0.4}{\sqrt{0.4^{2}+0.6^{2}+(-0.5)^{2}}}, \frac{0.6}{\sqrt{0.4^{2}+0.6^{2}+(-0.5)^{2}}}, \frac{-0.5}{\sqrt{0.4^{2}+0.6^{2}+(-0.5)^{2}}}\right) \\
& =(0.4558,0.6838,-0.5698)
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
& M_{1}^{e}=7.83+0.4558 Z_{3}+0.6838 Z_{5}-0.5698 Z_{7} \\
& M_{3}=4.78+0.9045 Z_{3}-0.4264 Z_{7}
\end{aligned}
$$



$$
\begin{aligned}
& M_{6(3)}=2.39-0.5773 Z_{3}+0.8165 Z_{6}, \rho=-0.5222 \\
& \Phi_{2}(-4.78,-2.39 ;-0.5222)=0.2571 \times 10^{-14}, \beta=7.83 \\
& \bar{\varepsilon}_{1}=(0.1,0,0) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{l}
-4.78 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0.9045 & 0 & -0.4264 \\
-0.5773 & 0.8165 & 0
\end{array}\right]\left[\begin{array}{c}
0.1 \\
0 \\
0
\end{array}\right]=\left[\begin{array}{l}
-4.87 \\
-2.33
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-4.87,-2.33 ;-0.52)\right)=-\Phi^{-1}\left(0.1805 \times 10^{-14}\right)=7.87 \\
& \bar{\varepsilon}_{2}=(0,0.1,0) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{cc}
-4.78 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0.9045 \\
-0.5773 & 0.8165 & -0.4264
\end{array}\right]\left[\begin{array}{c}
0 \\
0.1 \\
0
\end{array}\right]=\left[\begin{array}{l}
-4.78 \\
-2.47
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi \Phi_{2}(-4.78,-2.47 ;-0.52)\right)=-\Phi^{-1}\left(0.1464 \times 10^{-14}\right)=7.89 \\
& \bar{\varepsilon}_{3}=(0,0,0.1)
\end{aligned}
$$

$$
\begin{aligned}
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-4.78 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0.9045 & 0 & -0.4264 \\
-0.5773 & 0.8165 & 0
\end{array}\right]\left[\begin{array}{c}
0 \\
0 \\
0: 1
\end{array}\right]=\left[\begin{array}{c}
-4.74 \\
-2.39
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-4.74,-2.39 ;-0.52)\right)=-\Phi^{-1}\left(0.3616 \times 10^{-14}\right)=7.78 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{1}}\right|_{\bar{\varepsilon}=\overline{0}}=\frac{7.87-7.83}{0.1}=0.4 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{2}}\right|_{\bar{\varepsilon}=\overline{0}} \approx \frac{7.89-7.83}{0.1}=0.6 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{3}}\right|_{\bar{\varepsilon}=\overline{0}} \approx \frac{7.78-7.83}{0.1}=-0.5 \\
& \bar{u}^{e}=\left(u_{1}^{e}, u_{2}^{e}, u_{3}^{e}\right) \\
& =\left(\frac{0.4}{\sqrt{0.4^{2}+0.6^{2}+(-0.5)^{2}}}, \frac{0.6}{\sqrt{0.4^{2}+0.6^{2}+(-0.5)^{2}}}, \frac{-0.5}{\sqrt{0.4^{2}+0.6^{2}+(-0.5)^{2}}}\right) \\
& =(0.4558,0.6838,-0.5698)
\end{aligned}
$$

Therefore, $M_{2}^{e}=7.83+0.4558 Z_{3}+0.6838 Z_{5}-0.5698 Z_{7}$

$$
\begin{aligned}
& M_{4}=4.78+0.9045 Z_{4}-0.4264 Z_{7} \\
& M_{1(4)}=2.39+0.8165 Z_{1}-0.5773 Z_{4}, \rho=-0.5222
\end{aligned}
$$



$$
\Phi_{2}(-4.78,-2.39 ;-0.5222)=0.2571 \times 10^{-14}, \beta=7.83
$$

$$
\begin{aligned}
& \bar{\varepsilon}_{1}=(0.1,0,0) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{l}
-4.78 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0 & 0.9045 & -0.4264 \\
0.8165 & -0.5773 & 0
\end{array}\right]\left[\begin{array}{c}
0.1 \\
0 \\
0
\end{array}\right]=\left[\begin{array}{l}
-4.78 \\
-2.47
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-4.78,-2.47 ;-0.52)\right)=-\Phi^{-1}\left(0.1464 \times 10^{-14}\right)=7.89
\end{aligned}
$$

$$
\begin{aligned}
& \bar{\varepsilon}_{2}=(0,0.1,0) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{l}
-4.78 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0 & 0.9045 & -0.4264 \\
0.8165 & -0.5773 & 0
\end{array}\right]\left[\begin{array}{c}
0 \\
0.1 \\
0
\end{array}\right]=\left[\begin{array}{l}
-4.87 \\
-2.33
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-4.87,-2.33 ;-0.52)\right)=-\Phi^{-1}\left(0.1805 \times 10^{-14}\right)=7.87
\end{aligned}
$$

$$
\bar{\varepsilon}_{3}=(0,0,0.1)
$$

$$
-\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{l}
-4.78 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0 & 0.9045 & -0.4264 \\
0.8165 & -0.5773 & 0
\end{array}\right]\left[\begin{array}{c}
0 \\
0 \\
0.1
\end{array}\right]=\left[\begin{array}{l}
-4.74 \\
-2.39
\end{array}\right]
$$

$$
\begin{aligned}
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-4.74,-2.39 ;-0.52)\right)=-\Phi^{-1}\left(0.3616 \times 10^{-14}\right)=7.78 \\
& \begin{aligned}
\partial \beta_{f} \\
\left.{ }^{1}\right|_{\bar{\varepsilon}}=\overline{0}
\end{aligned} \\
& \approx \frac{7.89-7.83}{0.1}=0.6 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{2}}\right|_{\bar{\varepsilon}=\overline{0}} \quad \approx \frac{7.87-7.83}{0.1}=0.4 \\
& \begin{aligned}
&\left.\frac{\partial \beta_{f}}{\partial \varepsilon_{3}}\right|_{\bar{\varepsilon}}=\overline{0} \\
& \approx \frac{7.78-7.83}{0.1}=-0.5 \\
& \bar{u}^{e}=\left(u_{1}^{e}, u_{2}^{e}, u_{3}^{e}\right) \\
&=\left(\frac{0.6}{\sqrt{0.4^{2}+0.6^{2}+(-0.5)^{2}}}, \frac{0.4}{\sqrt{0.4^{2}+0.6^{2}+(-0.5)^{2}}}, \frac{-0.5}{\sqrt{0.4^{2}+0.6^{2}+(-0.5)^{2}}}\right) \\
& \quad=(0.6838,0.4558,-0.5698)
\end{aligned}
\end{aligned}
$$

Therefore, $M_{3}^{e}=7.83+0.6838 Z_{1}+0.4558 Z_{4}-0.5698 Z_{7}$

$$
M_{4}=4.78+0.9045 Z_{4}-0.4264 Z_{7}
$$

$$
M_{2(4)}=2.39+0.8165 Z_{2}-0.5773 Z_{4}, \rho=-0.5222
$$


$\Phi_{2}(-4.78,-2.39 ;-0.5222)=0.2571 \times 10^{-14}, \beta=7.83$

$$
\begin{aligned}
& \bar{\varepsilon}_{1}=(0.1,0,0) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-4.78 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0 & 0.9045 & -0.4264 \\
0.8165 & -0.5773 & 0
\end{array}\right]\left[\begin{array}{c}
0.1 \\
0 \\
0
\end{array}\right]=\left[\begin{array}{c}
-4.78 \\
-2.47
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-4.78,-2.47 ;-0.52)\right)=-\Phi^{-1}\left(0.1464 \times 10^{-14}\right)=7.89 \\
& \bar{\varepsilon}_{2}=(0,0.1,0) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-4.78 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0 & 0.9045 & -0.4264 \\
0.8165 & -0.5773 & 0
\end{array}\right]\left[\begin{array}{c}
0 \\
0.1 \\
0
\end{array}\right]=\left[\begin{array}{l}
-4.87 \\
-2.33
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-4.87,-2.33 ;-0.52)\right)=-\Phi^{-1}\left(0.1805 \times 10^{-14}\right)=7.87 \\
& \bar{\varepsilon}_{3}=(0,0,0.1) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-4.78 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0 & 0.9045 & -0.4264 \\
0.8165 & -0.5773 & 0
\end{array}\right]\left[\begin{array}{c}
0 \\
0 \\
0.1
\end{array}\right]=\left[\begin{array}{l}
-4.74 \\
-2.39
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-4.74,-2.39 ;-0.52)\right)=-\Phi^{-1}\left(0.3616 \times 10^{-14}\right)=7.78 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{1}}\right|_{\bar{\varepsilon}=\overline{0}}=\frac{7.89-7.83}{0.1}=0.6
\end{aligned}
$$

$$
\begin{aligned}
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{2}}\right|_{\bar{\varepsilon}=\overline{0}} \approx \frac{7.87-7.83}{0.1}=0.4 \\
& \begin{aligned}
&\left.\frac{\partial \beta_{f}}{\partial \varepsilon_{3}}\right|_{\bar{\varepsilon}}=\overline{0} \\
& \approx \frac{7.78-7.83}{0.1}=-0.5 \\
& \bar{u}^{e}=\left(u_{1}^{e}, u_{2}^{e}, u_{3}^{e}\right) \\
&=\left(\frac{0.6}{\sqrt{0.4^{2}+0.6^{2}+(-0.5)^{2}}}, \frac{0.4}{\sqrt{0.4^{2}+0.6^{2}+(-0.5)^{2}}}, \frac{-0.5}{\sqrt{0.4^{2}+0.6^{2}+(-0.5)^{2}}}\right) \\
&=(0.6838,0.4558,-0.5698)
\end{aligned}
\end{aligned}
$$

Therefore, $M_{4}^{e}=7.83+0.6838 Z_{1}+0.4558 Z_{4}-0.5698 Z_{7}$

The Ditlevsen bounds for the probability of failure of the series system are:


$$
\begin{array}{ll}
M_{1}^{e}=7.83+0.4558 Z_{3}+0.6838 Z_{5}-0.5698 Z_{7}, & \rho_{12}=0.5324 \\
\rho_{13}=0.3247 & \\
M_{2}^{e}=7.83+0.4558 Z_{3}+0.6838 Z_{5}-0.5698 Z_{7}, & \rho_{14}=0.3247 \\
\rho_{23}=0.3247 &
\end{array}
$$

$$
\begin{aligned}
& M_{3}^{e}=7.83+0.6838 Z_{1}+0.4558 Z_{4}-0.5698 Z_{7}, \quad \rho_{24}=0.3247, \\
& \rho_{34}=0.5324 \\
& M_{4}^{e}=7.83+0.6838 Z_{2}+0.4558 Z_{4}-0.5698 Z_{7} \\
& \text { upper bound: } P_{f} \leq \sum_{i=1}^{n} \Phi\left(-\beta_{i}\right)-\sum_{i=2, j<i}^{n} \max ^{n} \Phi_{2}\left(-\beta_{i},-\beta_{j} ; \rho\right) \\
& P_{f} \leq \Phi\left(-\beta_{1}\right)+\Phi\left(-\beta_{2}\right)+\Phi\left(-\beta_{3}\right)+\Phi\left(-\beta_{4}\right)-\max \left[\Phi_{2}\left(-\beta_{2},-\beta_{1} ; \rho\right)\right] \\
& -\max \left[\Phi \Phi_{2}\left(-\beta_{3},-\beta_{2} ; \rho\right), \Phi \Phi_{2}\left(-\beta_{3},-\beta_{1} ; \rho\right)\right] \\
& -\max \left[\Phi\left(-\beta_{4},-\beta_{1} ; \rho\right), \Phi\left(-\beta_{4},-\beta_{2} ; \rho\right), \Phi\left(-\beta_{4},-\beta_{3} ; \rho\right)\right] \\
& =4 \times 0.2439 \times 10^{-14}-0.2826 \times 10^{-19}-3.641 \times 10^{-23}-0.2826 \times 10^{-19} \\
& =9.7559 \times 10^{-15}
\end{aligned}
$$

lower bound: $P_{f} \geq \Phi\left(-\beta_{1}\right)+\sum_{i=2}^{n} \max \left[\Phi\left(-\beta_{i}\right)-\sum_{j=1}^{i-1} \Phi_{2}\left(-\beta_{i},-\beta_{j} ; \rho\right), 0\right]$

$$
\begin{aligned}
& P_{f} \geq \Phi\left(-\beta_{1}\right)+\max \left[\Phi\left(-\beta_{2}\right)-\Phi_{2}\left(-\beta_{2},-\beta_{1} ; \rho\right), 0\right] \\
& \quad+\max \left[\Phi\left(-\beta_{3}\right)-\Phi_{2}\left(-\beta_{3},-\beta_{1} ; \rho\right)-\Phi_{2}\left(-\beta_{3},-\beta_{2} ; \rho\right), 0\right]+ \\
& \max \left[\Phi\left(-\beta_{4}\right)-\Phi_{2}\left(-\beta_{4},-\beta_{1} ; \rho\right)-\Phi_{2}\left(-\beta_{4},-\beta_{2} ; \rho\right)-\Phi_{2}\left(-\beta_{4},-\beta_{3} ; \rho\right), 0\right]
\end{aligned}
$$

$$
=0.2439 \times 10^{-14}+0.2439 \times 10^{-14}-0.2826 \times 10^{-19}+0.2439 \times 10^{-14}
$$

$$
\begin{aligned}
& -3.641 \times 10^{-23}-3.641 \times 10^{-23}+0.2439 \times 10^{-14}-3.641 \times 10^{-23} \\
& -3.641 \times 10^{-23}-0.2826 \times 10^{-19}=9.7559 \times 10^{-15}
\end{aligned}
$$

$$
P_{f} \approx 9.7559 \times 10^{-15}, \beta=7.66
$$

Example 5. Consider the same structure of example 2 with different extemal load $\mu_{L}=20000, \sigma_{L}=2000$. Calculate the structural reliability.

By the same procedure used in example 2, one can obtain the following results:
For $\mathrm{L}=20000$, the ANSYS PROGRAMS and the corresponding results are listed in the appendixes: $\mathrm{E}, \mathrm{E} 1, \mathrm{E} 2, \mathrm{E} 3, \mathrm{E} 4, \mathrm{E} 5, \mathrm{~F}, \mathrm{~F} 1, \mathrm{~F} 2, \mathrm{~F} 3, \mathrm{~F} 4, \mathrm{~F} 5, \mathrm{~F} 6, \mathrm{G}, \mathrm{G} 1, \mathrm{G} 2, \mathrm{G} 3, \mathrm{G} 4$, and G 5 .
$M_{3}=R_{3}{ }^{+}-S_{3}($ tesnion $)=R_{3}-14142=R_{3}-0.7071 L$
$M_{5(3)}=R_{5}^{-}+S_{5}($ compression $)=R_{5}-42426=R_{5}-0.7071 R_{3}$
$M_{6(3)}=R_{6}^{-}+S_{6}($ compression $)=R_{6}-42426=R_{6}-0.7071 R_{3}$

$$
M_{4}=R_{4}^{-}+S_{4}(\text { compression })=R_{4}-14142=R_{4}-0.7071 L
$$

$$
M_{1(4)}=R_{1}^{+}-S_{1}(\text { tesnion })=R_{1}-42426=R_{1}-0.7071 R_{4}
$$

$$
M_{2(4)}=R_{2}^{+}-S_{2}(\text { tesnion })=R_{2}-42426=R_{2}-0.7071 R_{4}
$$

For the normalization: $Z_{i}=\frac{X_{i}-\mu_{X_{i}}}{\sigma_{X_{i}}}, X_{i}=\sigma_{X_{i}} Z_{i}+\mu_{X_{i}}$

$$
\begin{aligned}
& R_{i}=\sigma_{R_{i}} Z_{i}+\mu_{R_{i}}=6000 Z_{i}+60000,(i=1, \ldots, 6) \\
& L=\sigma_{L} Z_{7}+\mu_{L}=2000 Z_{7}+20000 \\
& M_{3}=R_{3}-0.7071 L=\left(6000 Z_{3}+60000\right)-0.7071\left(2000 Z_{7}+20000\right) \\
& \quad \Rightarrow 7.44+0.9733 Z_{3}-0.2294 Z_{7}
\end{aligned}
$$

$$
M_{5(3)}=R_{5}-0.7071 R_{3}=\left(6000 Z_{5}+60000\right)-0.7071\left(6000 Z_{3}+60000\right)
$$

$$
\Rightarrow 2.39-0.5773 Z_{3}+0.8165 Z_{5}
$$

$$
M_{6(3)}=R_{6}-0.7071 R_{3}=\left(6000 Z_{6}+60000\right)-0.7071\left(6000 Z_{3}+60000\right)
$$

$$
\Rightarrow 2.39-0.5773 Z_{3}+0.8165 Z_{6}
$$

$$
\begin{aligned}
& M_{4}=R_{4}-0.7071 L=\left(6000 Z_{4}+60000\right)-0.7071\left(2000 Z_{7}+20000\right) \\
& \quad \Rightarrow 7.44+0.9733 Z_{4}-0.2294 Z_{7} \\
& M_{1(4)}=R_{1}-0.7071 R_{4}=\left(6000 Z_{1}+60000\right)-0.7071\left(6000 Z_{4}+60000\right) \\
& \quad \Rightarrow 2.39+0.8165 Z_{1}-0.5773 Z_{4}
\end{aligned}
$$

$$
\begin{aligned}
& M_{2(4)}=R_{2}-0.7071 R_{4}=\left(6000 Z_{2}+60000\right)-0.7071\left(6000 Z_{4}+60000\right) \\
& \Rightarrow 2.39+0.8165 Z_{2}-0.5773 Z_{4} \\
& M_{3}=7.44+0.9733 Z_{3}-0.2294 Z_{7} \\
& M_{5(3)}=2.39-0.5773 Z_{3}+0.8165 Z_{5}, \rho=-0.5619 \\
& \Phi_{2}(-7.44,-2.39 ;-0.5619)=0.288352 \times 10^{-28}, \beta=11.18 \\
& M_{3}=7.44+0.9733 Z_{3}-0.2294 Z_{7} \\
& M_{6(3)}=2.39-0.5773 Z_{3}+0.8165 Z_{6}, \rho=-0.5619 \\
& \Phi_{2}(-7.44,-2.39 ;-0.5619)=0.288352 \times 10^{-28}, \beta=11.18
\end{aligned}
$$

$$
\begin{aligned}
& M_{4}=7.44+0.9733 Z_{4}-0.2294 Z_{7} \\
& M_{1(4)}=2.39+0.8165 Z_{4}-0.5773 Z_{7}, \rho=-0.5619 \\
& \Phi_{2}(-7.44,-2.39 ;-0.5619)=0.288352 \times 10^{-28}, \beta=11.18
\end{aligned}
$$

$$
M_{4}=7.44+0.9733 Z_{4}-0.2294 Z_{7}
$$



$$
\begin{aligned}
& M_{2(4)}=2.39+0.8165 Z_{2}-0.5773 Z_{4}, \rho=-0.5619 \\
& \Phi_{2}(-7.44,-2.39 ;-0.5619)=0.288352 \times 10^{-28}, \beta=11.18
\end{aligned}
$$

The reliability is modelled as a series system:


The equivalent series system is


The equivalent safety margins are calculated as follows:
$M_{3}=7.44+0.9733 Z_{3}-0.2294 Z_{7}$
$M_{5(3)}=2.39-0.5773 Z_{3}+0.8165 Z_{5}, \rho=-0.5619$
$\Phi_{2}(-7.44,-2.39 ;-0.5619)=0.288352 \times 10^{-28}, \beta=11.18$


$$
\begin{aligned}
& \bar{\varepsilon}_{1}=(0.1,0,0) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-7.44 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0.9733 & 0 & -0.2294 \\
-0.5773 & 0.8165 & 0
\end{array}\right]\left[\begin{array}{c}
0.1 \\
0 \\
0
\end{array}\right]=\left[\begin{array}{l}
-7.54 \\
-2.33
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-7.54,-2.33 ;-0.56)\right)=-\Phi^{-1}\left(1.4046 \times 10^{-29}\right)=11.25 \\
& \bar{\varepsilon}_{2}=(0,0.1,0) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-7.44 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0.9733 & 0 & -0.2294 \\
-0.5773 & 0.8165 & 0
\end{array}\right]\left[\begin{array}{c}
0 \\
0.1 \\
0
\end{array}\right]=\left[\begin{array}{l}
-7.44 \\
-2.47
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-7.44,-2.47 ;-0.56)\right)=-\Phi^{-1}\left(1.3093 \times 10^{-29}\right)=11.25 \\
& \bar{\varepsilon}_{3}=(0,0,0.1) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{l}
-7.44 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0.9733 & 0 & -0.2294 \\
-0.5773 & 0.8165 & 0
\end{array}\right]\left[\begin{array}{l}
0 \\
0 \\
0.1
\end{array}\right]=\left[\begin{array}{l}
-7.42 \\
-2.39
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-7.42,-2.39 ;-0.56)\right)=-\Phi^{-1}\left(3.7409 \times 10^{-29}\right)=11.16
\end{aligned}
$$

Therefore,

$$
M_{1}^{e}=11.18+0.6931 Z_{3}+0.6931 Z_{5}-0.198 Z_{7}
$$

$$
M_{3}=7.44+0.9733 Z_{3}-0.2294 Z_{7}
$$

$$
M_{6(3)}=2.39-0.5773 Z_{3}+0.8165 Z_{6}, \rho=-0.5619
$$



$$
\Phi_{2}(-7.44,-2.39 ;-0.5619)=0.288352 \times 10^{-28}, \beta=11.18
$$

$$
\begin{aligned}
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{1}}\right|_{\bar{\varepsilon}=\overline{0}}=\frac{11.25-11.18}{0.1}=0.7 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{2}}\right|_{\bar{\varepsilon}=\overline{0}} \approx \frac{11.25-11.18}{0.1}=0.7 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{3}}\right|_{\bar{\varepsilon}=\overline{0}} \approx \frac{11.16-11.18}{0.1}=-0.2 \\
& \bar{u}^{e}=\left(u_{1}^{e}, u_{2}^{e}, u_{3}^{e}\right) \\
& =\left(\frac{0.7}{\sqrt{0.7^{2}+0.7^{2}+(-0.2)^{2}}}, \frac{0.7}{\sqrt{0.7^{2}+0.7^{2}+(-0.2)^{2}}}, \frac{-0.2}{\sqrt{0.7^{2}+0.7^{2}+(-0.2)^{2}}}\right) \\
& =(0.6931,0.6931,-0.198)
\end{aligned}
$$

$$
\begin{aligned}
& \bar{\varepsilon}_{1}=(0.1,0,0) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-7.44 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0.9733 & 0 & -0.2294 \\
-0.5773 & 0.8165 & 0
\end{array}\right]\left[\begin{array}{c}
0.1 \\
0 \\
0
\end{array}\right]=\left[\begin{array}{l}
-7.54 \\
-2.33
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-7.54,-2.33 ;-0.56)\right)=-\Phi^{-1}\left(1.4046 \times 10^{-29}\right)=11.25 \\
& \bar{\varepsilon}_{2}=(0,0.1,0) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{l}
-7.44 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0.9733 & 0 & -0.2294 \\
-0.5773 & 0.8165 & 0
\end{array}\right]\left[\begin{array}{c}
0 \\
0.1 \\
0
\end{array}\right]=\left[\begin{array}{l}
-7.44 \\
-2.47
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-7.44,-2.47 ;-0.56)\right)=-\Phi^{-1}\left(1.3093 \times 10^{-29}\right)=11.25 \\
& \bar{\varepsilon}_{3}=(0,0,0.1) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{l}
-7.44 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0.9733 \\
-0.5773 & 0.8165 & 0
\end{array}\right]\left[\begin{array}{c}
0.2294 \\
0 \\
0.1
\end{array}\right]=\left[\begin{array}{l}
0 \\
-7.42 \\
-2.39
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-7.42,-2.39 ;-0.56)\right)=-\Phi^{-1}\left(3.7409 \times 10^{-29}\right)=11.16 \\
& \partial \beta_{f} \\
& \left.\overline{\sigma \varepsilon}_{1}\right|_{\bar{\varepsilon}=\overline{0}} \approx \frac{11.25-11.18}{0.1}=0.7
\end{aligned}
$$

$$
\begin{aligned}
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{2}}\right|_{\bar{\varepsilon}=\overline{0}}=\frac{11.25-11.18}{0.1}=0.7 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{3}}\right|_{\bar{\varepsilon}=\overline{0}}=\frac{11.16-11.18}{0.1}=-0.2 \\
& \bar{u}^{e}=\left(u_{1}^{e}, u_{2}^{e}, u_{3}^{e}\right) \\
& \\
& =\left(\frac{0.7}{\sqrt{0.7^{2}+0.7^{2}+(-0.2)^{2}}}, \frac{0.7}{\sqrt{0.7^{2}+0.7^{2}+(-0.2)^{2}}}, \frac{-0.2}{\sqrt{0.7^{2}+0.7^{2}+(-0.2)^{2}}}\right) \\
& \quad=(0.6931,0.6931,-0.198)
\end{aligned}
$$

Therefore,

$$
M_{2}^{e}=11.18+0.6931 Z_{3}+0.6931 Z_{6}-0.198 Z_{7}
$$

$$
\begin{aligned}
& M_{4}=744+0.9733 Z_{4}-0.2294 Z_{7} \\
& M_{1(4)}=2.39+0.8165 Z_{1}-0.5773 Z_{4}, \rho=-0.5619
\end{aligned}
$$



$$
\Phi_{2}(-7.44,-2.39 ;-0.5619)=2.88352 \times 10^{-29}, \beta=11.18
$$

$$
\bar{\varepsilon}_{1}=(0.1,0,0)
$$

$$
\begin{aligned}
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-7.44 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0 & 0.9733 & -0.2294 \\
0.8165 & -0.5773 & 0
\end{array}\right]\left[\begin{array}{c}
0.1 \\
0 \\
0
\end{array}\right]=\left[\begin{array}{l}
-7.44 \\
-2.47
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-7.44,-2.47 ;-0.56)\right)=-\Phi^{-1}\left(1.30927 \times 10^{-29}\right)=11.25 \\
& \bar{\varepsilon}_{2}=(0,0.1,0) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{l}
-7.44 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0 & 0.9733 & -0.2294 \\
0.8165 & -0.5773 & 0
\end{array}\right]\left[\begin{array}{c}
0 \\
0.1 \\
0
\end{array}\right]=\left[\begin{array}{l}
-7.54 \\
-2.33
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-7.54,-2.33 ;-0.52)\right)=-\Phi^{-1}\left(1.4046 \times 10^{-29}\right)=11.25 \\
& \bar{\varepsilon}_{3}=(0,0,0.1) \\
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{l}
-7.44 \\
-2.39
\end{array}\right]-\left[\begin{array}{cc}
0 & 0.9733 \\
0.8165 & -0.5773 \\
\hline
\end{array}\right]\left[\begin{array}{l}
0.2294
\end{array}\right]\left[\begin{array}{c}
0 \\
0 \\
0.1
\end{array}\right]=\left[\begin{array}{l}
-7.42 \\
-2.39
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-7.42,-2.39 ;-0.56)\right)=-\Phi^{-1}\left(3.7409 \times 10^{-29}\right)=11.16 \\
& \partial \beta_{f} \\
& \left.\frac{\partial \varepsilon_{1}}{} \right\rvert\, \bar{\varepsilon}=\overline{0} \\
& \approx \frac{11.25-11.18}{0.1}=0.7
\end{aligned}
$$

$$
\begin{aligned}
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{2}}\right|_{\bar{\varepsilon}=\overline{0}}=\frac{11.25-11.18}{0.1}=0.7 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{3}}\right|_{\bar{\varepsilon}=\overline{0}} \approx \frac{11.16-11.18}{0.1}=-0.2 \\
& \bar{u}^{e}
\end{aligned} \begin{aligned}
& =\left(u_{1}^{e}, u_{2}^{e}, u_{3}^{e}\right) \\
& \quad=\left(\frac{0.7}{\sqrt{0.7^{2}+0.7^{2}+(-0 .)^{2}}}, \frac{0.7}{\sqrt{0.7^{2}+0.7^{2}+(-0.2)^{2}}}, \frac{-0.2}{\sqrt{0.7^{2}+0.7^{2}+(-0.2)^{2}}}\right) \\
& \quad=(0.6931,0.6931,-0.198)
\end{aligned}
$$

Therefore, $M_{3}^{e}=11.18+0.6931 Z_{3}+0.6931 Z_{6}-0.198 Z_{7}$

$$
\left.\begin{array}{l}
M_{4}=7.44+0.9733 Z_{4}-0.2294 Z_{7} \\
M_{2(4)}=2.39+0.8165 Z_{2}-0.5773 Z_{4}, \rho=-0.5619 \\
\Phi_{2}(-.44,-2.39 ;-0.5619)=2.88352 \times 10^{-29}, \beta=11.18 \\
M_{2(4)}
\end{array}\right]
$$

$$
\beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-7.44,-2.47 ;-0.56)\right)=-\Phi^{-1}\left(1.3093 \times 10^{-29}\right)=11.25
$$

$$
\bar{\varepsilon}_{2}=(0,0.1,0)
$$

$$
\begin{aligned}
& -\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-7.44 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0 & 0.9733 & -0.2294 \\
0.8165 & -0.5773 & 0
\end{array}\right]\left[\begin{array}{c}
0 \\
0.1 \\
0
\end{array}\right]=\left[\begin{array}{l}
-7.54 \\
-2.33
\end{array}\right] \\
& \beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-7.54,-2.33 ;-0.56)\right)=-\Phi^{-1}\left(1.4046 \times 10^{-29}\right)=11.25
\end{aligned}
$$

$$
\bar{\varepsilon}_{3}=(0,0,0.1)
$$

$$
-\beta(\bar{\varepsilon})=-\bar{\beta}-\bar{u} \bar{\varepsilon}=\left[\begin{array}{c}
-7.44 \\
-2.39
\end{array}\right]-\left[\begin{array}{ccc}
0 & 0.9733 & -0.2294 \\
0.8165 & -0.5773 & 0
\end{array}\right]\left[\begin{array}{c}
0 \\
0 \\
0.1
\end{array}\right]=\left[\begin{array}{l}
-7.42 \\
-2.39
\end{array}\right]
$$

$$
\beta_{f}(\bar{\varepsilon})=-\Phi^{-1}\left(\Phi_{2}(-7.42,-2.39 ;-0.56)\right)=-\Phi^{-1}\left(3.7409 \times 10^{-29}\right)=11.16
$$

$$
\begin{aligned}
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{1}}\right|_{\bar{\varepsilon}=\overline{0}}=\frac{11.25-11.18}{0.1}=0.7 \\
& \left.\frac{\partial \beta_{f}}{\partial \varepsilon_{2}}\right|_{\bar{\varepsilon}=\overline{0}} \approx \frac{11.25-11.18}{0.1}=0.7
\end{aligned}
$$

$$
\begin{aligned}
&\left.\frac{\partial \beta_{f}}{\partial \varepsilon_{3}}\right|_{\bar{\varepsilon}}=\overline{0} \\
& \approx \frac{11.16-11.18}{0.1}=-0.2 \\
& \bar{u}^{e}=\left(u_{1}^{e}, u_{2}^{e}, u_{3}^{e}\right) \\
&=\left(\frac{0.7}{\sqrt{0.7^{2}+0.7^{2}+(-0.2)^{2}}}, \frac{0.7}{\sqrt{0.7^{2}+0.7^{2}+(-0.2)^{2}}}, \frac{-0.2}{\sqrt{0.7^{2}+0.7^{2}+(-0.2)^{2}}}\right) \\
&=(0.6931,0.6931,-0.198)
\end{aligned}
$$

Therefore, $M_{4}^{e}=11.18+0.6931 Z_{2}+0.6931 Z_{4}-0.198 Z_{7}$

The Ditlevsen bounds for the probability of failure of the series system are:


$$
\begin{array}{ll}
M_{1}^{e}=11.18+0.6931 Z_{3}+0.6931 Z_{5}-0.198 Z_{7}, & \rho_{12}=0.5196 \\
\rho_{13}=0.0392 & \\
M_{2}^{e}=11.18+0.6931 Z_{3}+0.6931 Z_{6}-0.198 Z_{7}, & \rho_{14}=0.0392, \\
\rho_{23}=0.0392 &
\end{array}
$$

$$
M_{3}^{e}=11.18+0.6931 Z_{1}+0.6931 Z_{4}-0.198 Z_{7}, \quad \quad \rho_{24}=0.0392
$$

$$
\rho_{35}=0.5196
$$

$$
M_{4}^{e}=11.18+0.6931 Z_{2}+0.6931 Z_{4}-0.198 Z_{7}
$$

$$
\begin{aligned}
& \text { upper bound: } P_{f} \leq \sum_{i=1}^{n} \Phi\left(-\beta_{i}\right)-\sum_{i=2, j<i}^{n} \max \Phi_{2}\left(-\beta_{i},-\beta_{j} ; \rho\right) \\
& P_{f} \leq \Phi\left(-\beta_{1}\right)+\Phi\left(-\beta_{2}\right)+\Phi\left(-\beta_{3}\right)+\Phi\left(-\beta_{4}\right)-\max \left[\Phi_{2}\left(-\beta_{2},-\beta_{1} ; \rho\right)\right] \\
& -\max \left[\Phi_{2}\left(-\beta_{3},-\beta_{2} ; \rho\right), \Phi_{2}\left(-\beta_{3},-\beta_{1} ; \rho\right)\right] \\
& -\max \left[\Phi\left(-\beta_{4},-\beta_{1} ; \rho\right), \Phi\left(-\beta_{4},-\beta_{2} ; \rho\right), \Phi\left(-\beta_{4},-\beta_{3} ; \rho\right)\right] \\
& \quad=4 \times 2.5545 \times 10^{-29}-6.29596 \times 10^{-39}-7.86105 \times 10^{-56}-6.29596 \times 10^{-39} \\
& \quad=1.0218 \times 10^{-28}
\end{aligned}
$$

$$
\text { lower bound: } P_{f} \geq \Phi\left(-\beta_{1}\right)+\sum_{i=2}^{n} \max \left[\Phi\left(-\beta_{i}\right)-\sum_{j=1}^{i-1} \Phi_{2}\left(-\beta_{i},-\beta_{j} ; \rho\right), 0\right]
$$

$$
P_{f} \geq \Phi\left(-\beta_{1}\right)+\max \left[\Phi\left(-\beta_{2}\right)-\Phi_{2}\left(-\beta_{2},-\beta_{1} ; \rho\right), 0\right]
$$

$$
+\max \left[\Phi\left(-\beta_{3}\right)-\Phi_{2}\left(-\beta_{3},-\beta_{1} ; \rho\right)-\Phi_{2}\left(-\beta_{3},-\beta_{2} ; \rho\right), 0\right]+
$$

$$
\max \left[\Phi\left(-\beta_{4}\right)-\Phi_{2}\left(-\beta_{4},-\beta_{1} ; \rho\right)-\Phi_{2}\left(-\beta_{4},-\beta_{2} ; \rho\right)-\Phi_{2}\left(-\beta_{4},-\beta_{3} ; \rho\right), 0\right]
$$

$$
=2.5545 \times 10^{-29}+2.5545 \times 10^{-29}-6.29596 \times 10^{-39}+2.5545 \times 10^{-29}
$$

$$
-7.86105 \times 10^{-56}-7.86105 \times 10^{-56}+2.5545 \times 10^{-29}-7.86105 \times 10^{-56}
$$

$$
-7.86105 \times 10^{-56}-6.29596 \times 10^{-39}=1.0218 \times 10^{-28}
$$

$P_{f} \approx 1.0218 \times 10^{-28}, \beta=11.07$

Example 6. Consider the effects of loads on structures: (1) probabilities vs. loads (2) dafeindices vs. loads (3) probabilities vs. safety-factors.
S.F. $=$ safety factor $=\frac{\text { ultimate load }}{\text { allowable load }}$
(a).


For $p=p_{1}=p_{2}=10000 ; P_{f}=\Phi(-\beta)=\Phi(-7.95)=9.823 \times 10^{-16}$;
S.F. $=\frac{60000}{11830}=5.07$

For $p=p_{1}=p_{2}=20000 ; P_{f}=\Phi(-\beta)=\Phi(-5.82)=2.951 \times 10^{-9}$;
S.F. $=\frac{60000}{23660}=2.54$

For $p=p_{1}=p_{2}=30000 ; p_{f}=\Phi(-\beta)=\Phi(-3.75)=8.837 \times 10^{-5}$;
S.F. $=\frac{60000}{35490}=1.69$

For $p=p_{1}=p_{2}=50000 ; P_{f}=\Phi(-\boldsymbol{\beta})=\Phi(-0.11)=0.4562$
S.F. $=\frac{60000}{59150}=1.01$
(1) $\ln$ prob. vs. $\ln$ load.

(2) (-) safety index vs. load.

(3) $\ln$ prob. vs. (-) $\ln$ S.F.

(-) $\ln$ S.F.
(b).


For $\mathrm{L}=20000 ; P_{f}=\Phi(-\beta)=\Phi(-11.07)=1.02 \times 10^{-28} ;$ S.F. $=4.24$

For $\mathrm{L}=40000 ; P_{f}=\Phi(-\beta)=\Phi(-7.66)=9.756 \times 10^{-15} ;$ S.F. $=2.12$

For $\mathrm{L}=60000 ; P_{f}=\Phi(-\beta)=\Phi(-4.85)=0.6138 \times 10^{-6} ;$ S.F. $=1.41$

For $\mathrm{L}=80000 ; P_{f}=\Phi(-\beta)=\Phi(-0.52)=0.3006$; S.F. $=1.06$
(1) $\ln$ prob. vs. In load.
$\ln$ prob.

(2) (-) safety index vs. load.

(3) $\ln$ prob. vs. (-) $\ln S . F$.


## APPENDIX A ANSYS PROGRAM AND FORCE DISTRIBUTIONS



KAN,0 \$ET, 1, 1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,57.735,100 \$N,3,173.205,100
N,4,115.47 \$N,5,230.94 \$E,1,2 \$E,2,3 \$E,3,4 \$E,2,4 \$E,3,5 \$E,1,4 \$E,4,5 \$D,1,ALL,0
D,5,UY,0 \$F,2,FX,10000 \$F,2,FY,-10000 \$ITER,1,1,1 \$AFWRITE \$FINISH
\$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE \$FINISH

## FOREC DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | -3660.3 | compression |
| 2 | -7886.8 | compression |
| 3 | 7886.8 | tension |
| 4 | -7886.8 | compression |
| 5 | -7886.8 | compression |

## APPENDIX A1ANSYS PROGRAM AND FORCE DISTRIBUTIONS



FORCE DISTRIBUTIONS:
ELEMENT FORCE

1
tension

| 2 | -5000 | compression |
| :--- | :--- | :--- |
| 3 | 5000 | tension |
| 4 | -5000 | compression |
| 5 | -5000 | compression |
| 6 | 7500 | tension |
| 7 | 2500 | tension |

## APPENDIX A2 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7
KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,57.735,100
\$N,3,173.205,100 N,4,115.47 \$ N,5,230.94 \$E,1,2 \$E,2,3 \$E,3,4 \$E,2,4 \$E,3,5 \$E, 1, 4 \$E,4,5 \$D,1,ALL,0 D,5,UY,0 \$F,2,FY,-10000 \$ITER,1,1,1 \$AFWRITE \$FINISH \$/ INPUT,27 \$FINISH
/POST1 \$SET \$PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | -8660.3 | compression |
| 2 | -2886.8 | compression |
| 3 | 2886.8 | tension |
| 4 | -2886.8 | compression |
| 5 | -2886.8 | compression |
| 6 | 4330.1 | tension |
| 7 | 1443.4 | tension |

# APPENDIX B ANSYS PROGRAM AND FORCE DISTRIBUTIONS 


(Figure b)
/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,20 \$N,3,40 \$N,4,60 N,5,80 \$N,6,20,28.2843 \$N,7,40,34.641 \$N,8,60,28.2843 \$E,1,6 \$E,6,7 \$E,1,2 E,2,6 \$E,3,6 \$E,3,7 \$E,5,8 \$E,7,8 \$E,4,5 \$E,4,8 \$E,3,8 \$E,2,3 \$E,3,4 \$D,1,ALL,0

D,5,UY,0 \$F,2,FY,-10000 \$F,3,FY,-10000 \$F,4,FY,-10000 \$ITER,1,1,1 \$AFWRITE FINISH \$/INPUT,27 \$FINISH \$/POST1 \$PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTIONS

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | -18371 | compression |
| 2 | -12116 | compression |
| 3 | 10607 | tension |


| 4 | 10000 | tension |
| :--- | :--- | :--- |
| 5 | 1628.9 | tension |
| 6 | 7340.1 | tension |
| 7 | -18371 | compression |
| 8 | -12116 | compression |
| 9 | 10607 | tension |
| 10 | 10000 | tension |
| 11 | 1628.9 | tension |
| 12 | 10607 | tension |
| 13 | 10607 | tension |

## APPENDIX B1 ANSYS PROGRAM AND FOREC DISTRIBUTION


(Figure b1)
/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N, 1 N , 2,20 \$N,3,40 \$N,4,60 \$N,5,80 N,6,20,28.2843 \$N,7,40,34.641 \$N,8,60,28.2843 \$E,1,6 \$E,6,7 \$E,1,2 \$E,2,6 \$E,3,6 E,3,7 \$E,5,8 \$E,7,8 \$E,4,5 \$E,4,8\$E,3,8 \$E,2,3 \$E,3,4 \$D,1,ALL,0 \$D,5,UY,0 F,2,FY,-10000 \$ITER,1,1,1 \$AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 SET \$PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | -9185.6 | compression |
| 2 | -3029.1 | compression |
| 3 | 5303.3 | tension |
| 4 | 10000 | tension |
| 5 | -4185.6 | compression |
| 6 | 1835 | tension |
| 7 | -3061.9 | compression |


| 8 | -3029.1 | compression |
| :--- | :--- | :--- |
| 9 | 1767.8 | tension |
| 10 | 0 |  |
| 11 | 1938.1 | tension |
| 12 | 5303.3 | tension |
| 13 | 1767.8 | tension |

## APPENDIX B2 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


(Figure b2)
/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,20 \$N,3,40 \$N,4,60 N,5,80 \$N,6,20,28.2843 \$N,7,40,34.641 \$N,8,60,28.2843 \$E,1,6 \$E,6,7 \$E,1,2 \$E,2,6

E,3,6 \$E,3,7 \$E,5,8 \$E,7,8 \$E,4,5 \$E,4,8 \$E,3,8 \$E,2,3 \$E,3,4 \$D,1,ALL,0 \$D,5,UY,0

## F,3,FY,-10000 \$ITER,1,1,1 \$AFWRITE \$FINISH \%/INPUT,27 \$FINISH \$/POST1 SET \$PRDISP \$NFORCE \$FINIS

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :---: | :---: | :---: |
| 1 | -6123.7 | compression |
| 2 | -6058.1 | compression |
| 3 | 3535.5 | tension |
| 4 | 0 |  |
| 5 | 3876.3 | tension |
| 6 | 3670 | tension |
| 7 | -6123.7 | compression |
| 8 | -6058.1 | compression |
| 9 | 3535.5 | tension |
| 10 | 0 |  |
| 11 | 3876.3 | tension |
| 12 | 3535.3 | tesnion |
| 13 | 3535.3 | tension |

## APPENDIX B3 ANSYS PROGRAM AND FORCEDISTRIBUTIONS


(Figure b3)
/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,20 \$N,3,40 \$N,4,60
N,5,80 \$N,6,20,28.2843 \$N,7,40,34.641 \$N,8,60,28.2843 \$E,1,6 \$E,6,7 \$E,1,2 \$E,2,6
E,3,6 \$E,3,7 \$E,5,8 \$E,7,8 \$E,4,5 \$E,4,8 \$E,3,8 \$E,2,3 \$E,3,4 \$D,1,ALL,0 \$D,5,UY,0
F,4,FY,-10000 4ITER,1,1,1 \$AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET
PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | -3061.9 | compression |
| 2 | -3029.1 | compression |
| 3 | 1767.8 | tension |


| 4 | 0 |  |
| :--- | :--- | :--- |
| 5 | 1938.1 | tension |
| 6 | 1835 | tension |
| 7 | -9185.6 | compression |
| 8 | -3029.1 | compression |
| 9 | 5303.3 | tension |
| 10 | 10000 | tension |
| 11 | -4185.6 | compression |
| 12 | 1767.8 | tension |
| 13 | 5303.3 | tension |

## APPENDIX C ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET, 1,1 \$R, 1,2 \$MP,EX,1,30E6 \$N, 1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E,1,4 \$E,1,2 \$E,1,3 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,80000 ITER, $1,1,1$ \$AFWRITE \$FINISH \$/INPUT, 27 \$FINISH \$/POST1 \$SET \$NFORCE FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 40000 | tension |
| 2 | 40000 | tension |
| 3 | 56569 | tension |
| 4 | -56569 | compression |
| 5 | -40000 | compression |
| 6 | -40000 | compression |

## APPENDIX C1 ANSYS PROGRAMS AND FORCE DISTRIBUTIONS


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,2 \$E,1,3 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,80000 \$F,1,FX,60000 F,4,FX,-60000 \$ITER, 1,1,1 \$AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 2 | 60000 | tension |
| 3 | 28284 | tension |
| 4 | -84853 | compression |
| 5 | -20000 | compression |
| 6 | -20000 | compression |

## APPENDIX C2 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E, 1,3 \$E, 2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,80000 \$F,2,FY,-60000 F,1,FY,60000 \$ITER,1,1,1 \$AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 60000 | tension |
| 3 | 28284 | tension |
| 4 | -84853 | compression |
| 5 | -20000 | compression |
| 6 | -20000 | compression |

## APPENDIX C3 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET, 1, 1 RR,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E,1,2 \$E,2,4 \$E,3,4 \$E,2,3\$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,80000 F,1,FX,42426.4 F,1,FY,42426.4 \$F,3,FX,-42426.4 \$F,3,FY,-42426.4 \$ITER,1,1,1 \$AFWRITE \$FINISH /INPUT, 27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 37574 | tension |
| 2 | 37574 | tension |
| 4 | -53137 | compression |
| 5 | -42426 | compression |
| 6 | -42426 | compression |

## APPENDIX C4 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E, 1,2 \$E,1,3 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,37573.6 F,2,FY,42426.4 \$F,4,FX,42426.4 \$F,4,FY,-42426.4 \$ITER,1,1,1 \$AFWRITE \$FINISH /INPUT, 27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 42426 | tension |
| 2 | 42426 | tension |
| 3 | 53137 | tension |
| 5 | -37574 | compression |
| 6 | -37574 | compression |

## APPENDIX C5 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,3E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0
E,1,4 \$E,1,2 \$E,1,3 \$E,2,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,80000 \$F,3,FY,60000
F,4,FY,-60000 \$ITER,1,1,1 \$AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET

PRDISP \$NFORCE \$FINISH

FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 20000 | tension |
| 2 | 20000 | tension |
| 3 | 84853 | tension |
| 4 | -28284 | compression |
| 6 | -60000 | compression |

## APPENDIX C6 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,3E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 \$E,1,4 \$E,1,2 \$E,1,3 \$E,2,4 \$E,3,4 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,20000 F,3,FX,60000

ITER,1,1,1 \$AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 20000 | tension |
| 2 | 20000 | tension |
| 3 | 84853 | tension |
| 4 | -28284 | compression |
| 5 | -60000 | compression |

## APPENDIX D ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET, 1, 1 RR,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E,1,2 \$E,1,3 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,80000 ITER, $1,1,1$ \$AFWRITE \$FINISH \$/INPUT, 27 \$FINISH \$/POST1 \$SET \$PRDISP NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 2 | 0 |  |
| 3 | 113140 | tension |
| 4 | 0 |  |
| 5 | -80000 | compression |
| 6 | -80000 | compression |

## APPENDIX D1 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX, 1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E,1,2 \$E, 1,3 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,80000 \$ITER,1,1,1 AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

## FORCE DISTRIBUTIONS:

## EL

3

4

5

6

113140

0
$-80000$
$-80000$

FORCE
tension
compression
compression

## APPENDIX D2 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1, 4 \$E,1,3 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,80000 \$ITER,1,1,1 AFWRITE \$FINISH \$/INPUT, 27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 80000 | tension |
| 2 | 80000 | tension |
| 4 | -113140 | compression |
| 5 | 0 |  |
| 6 | 0 |  |

## APPENDIX D3 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N, 1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0
E, 1,4 \$E,1,2 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,80000 \$ITER,1,1,1 AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 0 |  |
| 2 | 0 |  |
| 3 | 113140 | tension |
| 5 | -80000 | compression |
| 6 | -80000 | compression |

## APPENDIX D4 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E,1,2 \$E,1,3 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,80000 \$ITER,1,1,1 AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

FORCE DISTRIBUTIONS:

| ELEMENT | FORCE |
| :--- | :--- |
| 80000 | tension |
| 80000 | tension |
| 0 |  |
| -113140 | compression |
| 0 |  |

## APPENDIX D5 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E,1,2 \$E,1,3 \$E,2,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,80000 \$TTER,1,1,1 AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 80000 | tension |
| 2 | 80000 | tension |
| 3 | 0 |  |
| 4 | -113140 | compression |
| 5 | 0 |  |

## APPENDIX E ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0
E, 1,2 \$E, 1,3 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,1,FX,60000 \$F,4,FX,-60000 ITER,1,1,1 \$AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 2 | 60000 | tension |
| 3 | -84853 | compression |
| 4 | -84853 | compression |
| 5 | 60000 | tension |
| 6 | 60000 | tension |

## APPENDIX E1 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0
E,1,4 \$E,1,3 \$E,2,4 \$E,3,4 \$E,2,3\$D,1,ALL,0 \$D,4,UY,0 \$F,2,FY,-60000 \$F,1,FY,60000 ITER,1,1,1 \$AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

ELEMENT

1

3

4

5

6

60000
$-84853$
$-84853$

60000

60000

FORCE
tension
compression
compression
tension
tension

## APPENDIX E2 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E,1,4 \$E,1,2 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,1,FX,42426.4

F,1,FY,42426.4 \$F,3,FX,-42426.4 \$F,3,FY,-42426.4 \$ITER,1,1,1 \$AFWRITE \$FINISH /INPUT, 27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

| ELEMENT | FORCE |
| :--- | :--- |
| -42426 | compression |
| -42426 | compression |
| 60000 | tension |
| -42426 | compression |
| -42426 | compression |

# APPENDIX E3 ANSYS PROGRAM AND FORCE DISTRIBUTIONS 


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E,1,2 \$E,1,3 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,-42426.4 F,2,FY,42426.4 \$F,4,FX,42426.4 \$F,4,FY,-42426.4 \$ITER,1,1,1 \$AFWRITE \$FINISH /INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 42426 | tension |
| 2 | 42426 | tension |
| 3 | -60000 | compression |
| 5 | 42426 | tension |
| 6 | 42426 | tension |

## APPENDIX E4 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E, 1, 2 \$E, 1,3 \$E,2,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,3,FY,60000 \$F,4,FY,-60000 ITER,1,1,1 \$AFWRITE \$FINISH \$/INPUT,27 \$\%FINISH \$/POST1 \$SET \$PRDISP NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | -60000 | compression |
| 2 | -60000 | compression |
| 3 | 84853 | tension |
| 4 | 84853 | tension |
| 6 | -60000 | compression |

## APPENDIX E5 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N, 1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E, 1,2 \$E, 1,3 \$E,2,4 \$E,3,4 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,-60000 \$F,3,FX,60000 ITER,1,1,1 \$AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | -60000 | compression |
| 2 | -60000 | compression |
| 3 | 84853 | tension |
| 4 | 84853 | tension |
| 5 | -60000 | compression |

## APPENDIX F ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0
E,1,4 \$E,1,2 \$E,1,3 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,20000 ITER,1,1,1 \$AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 10000 | tension |
| 2 | 10000 | tension |
| 3 | 14142 | tension |
| 4 | -14142 | compression |
| 5 | -10000 | compression |
| 6 | -10000 | compression |

## APPENDIX F1 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E,1,2 \$E,1,3 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,20000 \$F,1,FX,60000 F,4,FX,-60000 \$ITER,1,1,1 \$AFWRITE\$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 2 | 60000 | tension |
| 3 | -56569 | compression |
| 4 | -84853 | compression |
| 5 | 40000 | tension |
| 6 | 40000 | tension |

## APPENDIX F2 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET, 1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E, 1,3 \$E, 2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,20000 \$F,2,FY,-60000 F,1,FY,60000 \$ITER,1,1,1 \$AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 60000 | tension |
| 3 | -56569 | compression |
| 4 | -84853 | compression |
| 5 | 40000 | tension |
| 6 | 40000 | tension |

## APPENDIX F3 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET, 1, 1 RR,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E,1,2 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,20000 F,1,FX,42426.4 F,1,FY,42426.4 \$F,3,FX,-42426.4 \$F,3,FY,-42426.4 \$ITER,1,1,1 \$AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

| ELEMENT | FORCE |
| :--- | :--- |
| -22426 | compression |
| -22426 | compression |
| 31716 | tension |
| -42426 | compression |
| -42426 | compression |

## APPENDIX F4 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E,1,2 \$E,1,3 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,-22426.4 F,2,FY,42426.4 \$F,4,FX,42426.4 \$F,4,FY,-42426.4 \$ITER,1,1,1 \$AFWRITE \$FINISH /INPUT, 27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTION:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 42426 | tension |
| 2 | 42426 | tension |
| 3 | -31716 | compression |
| 5 | 22426 | tension |
| 6 | 22426 | tension |

## APPENDIX F5 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E, 1,2 \$E, 1,3 \$E,2,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,20000 \$F,3,FY,60000 F,4,FY,-60000 \$ITER,1,1,1 \$AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET PRDISP \$NFORCE \$FINISH

FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | -40000 | compression |
| 2 | -40000 | compression |
| 3 | 84853 | tension |
| 4 | 56569 | tension |
| 6 | -60000 | compression |

## APPENDIX F6 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET, 1,1 \$R,1,2 \$MP,EX,1,30E6 \$N, 1 N , 2,0,50 \$N,3,50,50 \$N,4,50,0 E,1,4 \$E,1,2 \$E,1,3 \$E,2,4 \$E,3,4 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,-40000 \$F,3,FX,60000 ITER,1,1,1 \$AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | -40000 | compression |
| 2 | -40000 | compression |
| 3 | 84853 | tension |
| 4 | 56569 | tension |
| 5 | -60000 | compression |

## APPENDIX G ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET, 1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E,1,2 \$E,1,3 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,20000 \$TTER,1,1,1 AFWRITE \$FINISH \$/INPUT, 27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 2 | 0 |  |
| 3 | 28284 | tension |
| 4 | 0 |  |
| 5 | -20000 | compression |
| 6 | -20000 | compression |

## APPENDIX G1 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E,1,4 \$E,1,3 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,20000 \$ITER,1,1,1 AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

## FORCE DISTRIBUTION:

ELEMENT FORCE

| 1 | 0 |  |
| :--- | :--- | :--- |
| 3 | 28284 | tension |
| 4 | 0 |  |
| 5 | -20000 | compression |
| 6 | -20000 | compression |

## APPENDIX G2 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET, 1, $\$$ R, 1,2 \$MP,EX, $1,30 \mathrm{E} 6$ \$N, 1 \$N, 2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E,1,2 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,20000 \$ ITER,1,1,1 AFWRITE \$FINISH \$/INPUT, 27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 20000 | tension |
| 2 | 20000 | tension |
| 4 | -28284 | compression |
| 5 | 0 |  |
| 6 | 0 |  |

## APPENDIX G3 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET, 1, 1 R, 1,2 \$MP,EX, 1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E,1,4 \$E,1,2 \$E,1,3 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,20000 \$ITER,1,1,1 AFWRITE \$FINISH \$/INPUT, 27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

## FORCE DISTRIBUTIONS:

## ELEMENT <br> FORCE

10

20

3

5
$-20000$
$6 \quad-20000$
tension
compression
compression

## APPENDIX G4 ANSYS PROGRAM AND FORCE DISTRIBUTRIONS


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E,1,2 \$E,1,3 \$E,2,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,20000 \$TTER,1,1,1 AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 20000 | tension |
| 2 | 20000 | tension |
| 3 | 0 |  |
| 4 | -28284 | compression |
| 6 | 0 |  |

## APPENDIX G5 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E, 1,2 \$E,1,3 \$E,2,4 \$E,3,4 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,20000 \$ITER,1,1,1 AFWRITE \$FINISH \$/INPUT, 27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 20000 | tension |
| 2 | 20000 | tension |
| 3 | 0 |  |
| 4 | -28284 | compression |
| 5 | 0 |  |

## APPENDIX H ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E,1,4 \$E,1,2 \$E,1,3 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,40000 ITER,1,1,1 \$AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 20000 | tension |
| 2 | 20000 | tension |
| 3 | 28284 | tension |
| 4 | -28284 | compression |
| 5 | -20000 | compression |
| 6 | -20000 | compression |

## APPENDIX H1 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET, 1,1 \$R,1,2 \$MP,EX, 1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,2 \$E, 1,3 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,40000 \$F,1,FX,60000 F,4,FX,-60000 \$ITER, 1,1,1 \$AFWRTTE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET PRDISP \$NFORCE \$FINISH

FORCE DISTRIBUTIONS:

ELEMENT FORCE

2

3

4

5
20000
tension

6
20000
tension

## APPENDIX H2 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E,1,3 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,40000 \$F,2,FY,-60000 F,1,FY,60000 \$ITER,1,1,1 \$AFWRITE \$FINISH \$/INPUT, 27 \$FINISH \$/POST1 \$SET PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 60000 | tension |
| 3 | -28284 | compression |
| 4 | -84853 | compression |
| 5 | 20000 | tension |
| 6 | 20000 | tension |

## APPENDIX H3 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E,1,2 \$E,2,4 \$E,3,4 \$E,2,3 \$EPLOT \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,40000 F,1,FX,42426.4 \$F,1,FY,42426.4 \$F,3,FX,-42426.4 \$F,3,FY,-42426.4 \$ITER,1,1,1 AFWRITE \$FINISH \$/INPUT, 27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

FORCE DISTRIBUTIONS:

ELEMENT FORCE

1

2

4
3431.4
tension

5
$-42426$
compression
compression

## APPENDIX H4 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


 E,1,4 \$E,1,2 \$E,1,3 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,-2426.4

F,2,FY,42426.4 \$F,4,FX,42426.4 \$F,4,FY,-42426.4 \$ITER,1,1,1 \$AFWRITE \$FINISH /INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTION:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 42426 | tension |
| 2 | 42426 | tension |
| 3 | -3431.4 | compression |
| 5 | 2426.4 | tension |
| 6 | 2426.4 | tension |

## APPENDIX H5 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E,1,4 \$E,1,2 \$E,1,3 \$E,2,4 \$E,2,3 \$D,1,ALL, 0 \$D,4,UY,0 \$F,2,FX,40000 \$F,3,FY,60000 F,4,FY,-60000 \$ITER, 1,1,1 \$AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | -20000 | compression |
| 2 | -20000 | compression |
| 3 | 84853 | tension |
| 4 | 28284 | tension |
| 6 | -60000 | compression |

## APPENDIX H6 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E,1,4 \$E,1,2 \$E,1,3 \$E,2,4 \$E,3,4 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,-20000 \$F,3,FX,60000 ITER,1,1,1 \$AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | -20000 | compression |
| 2 | -20000 | compression |
| 3 | 84853 | tension |
| 4 | 28284 | tension |
| 5 | -60000 | compression |

## APPENDIX I ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0
E, 1,2 \$E,1,3 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,40000 \$TTER,1,1,1 AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 2 | 0 |  |
| 3 | 56569 | tension |
| 4 | 0 |  |
| 5 | -40000 | compression |
| 6 | -40000 | compression |

## APPENDIX I1 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$EMP,EX,1,3E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E,1,3 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,40000 \$ITER,1,1,1 AFWRITE \$FINISH \$/INPUT, 27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

## FORCE DISTRIBUTION:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 0 |  |
| 3 | 56569 | tension |
| 4 | 0 |  |
| 5 | -40000 | compression |
| 6 | -40000 | compression |

## APPENDIX I2 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0
E, 1,4 \$E,1,2 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,40000 \$ITER,1,1,1 AFWRITE \$FINISH \$/INPUT, 27 \$FINISH \$/POST1 \$SET \$\%PRDISP \$NFORCE FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 40000 | tension |
| 2 | 40000 | tension |
| 4 | -56569 | compression |
| 5 | 0 |  |
| 6 | 0 |  |

## APPENDIX I3 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E,1,4 \$E,1,2 \$E,1,3 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,40000 \$TTER,1,1,1 AFWRITE \$FINISH \$/INPUT, 27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 0 |  |
| 2 | 0 |  |
| 3 | 56569 | tension |
| 5 | -40000 | compression |
| 6 | -40000 | compression |

## APPENDIX I4 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E,1,2 \$E,1,3 \$E,2,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,40000 \$ITER,1,1,1 AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 40000 | tension |
| 2 | 40000 | tension |
| 3 | 0 |  |
| 4 | -56569 | compression |
| 6 | 0 |  |

## APPENDIX I5 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E,1,4 \$E,1,2 \$E,1,3 \$E,2,4 \$E,3,4 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,40000 \$ITER,1,1,1 AFWRITE \$FINISH \$/INPUT, 27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 40000 | tension |
| 2 | 40000 | tension |
| 3 | 0 |  |
| 4 | -56569 | compression |
| 5 | 0 |  |

## APPENDIX J1 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0
E, 1,2 \$E,1,3 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,60000 \$F,1,FX,60000
F,4,FX,-60000 \$ITER,1,1,1 \$AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET
PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 2 | 60000 | tension |
| 3 | 0 |  |
| 4 | -84853 | compression |
| 5 | 0 |  |
| 6 | 0 |  |

## APPENDIX J2 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E,1,4 \$E,1,3 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,60000 \$F,2,FY,-60000 F,1,FY,60000 \$ITER,1,1,1 \$AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 60000 | tension |
| 3 | 0 |  |
| 4 | -84853 | compression |
| 5 | 0 |  |
| 6 | 0 |  |

## APPENDIX J3 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET, 1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E,1,2 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,60000 F,1,FX,42426.4 F,1,FY,42426.4 \$F,3,FX,-42426.4 \$F,3,FY,-42426.4 \$ITER,1,1,1 \$AFWRITE \$FINISH /INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 17574 | tension |
| 2 | 17574 | tension |
| 4 | -24853 | compression |
| 5 | -42426 | compression |
| 6 | -42426 | compression |

## APPENDIX J4 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0
E, 1,4 \$E,1,2 \$E,1,3 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,17573.6
F,2,FY,42426.4 \$F,4,FX,42426.4 \$F,4,FY,-42426.4 \$ITER,1,1,1 \$AFWRITE \$FINISH /INPUT, 27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE \$FINISH

FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 42426 | tension |
| 2 | 42426 | tension |
| 3 | 24853 | tension |
| 5 | -17574 | compression |
| 6 | -17574 | compression |

## APPENDIX J5 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0
E,1,4 \$E,1,2 \$E,1,3 \$E,2,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,60000 \$F,3,FY,60000 F,4,FY,-60000 \$ITER, 1,1,1 \$AFWRITE \$FINISH \$/INPUT, 27 \$FINISH \$/POST1 \$SET PRDISP \$NFORCE \$FINISH

## FORCE DISTRIBUTION:

ELEMENT FORCE

1

2

3

4
0

6 $-60000$
tension
compression

## APPENDIX J6 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET, 1, 1 R, 1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1, 4 \$E,1,2 \$E,1,3 \$E,2,4 \$E,3,4 \$D,1,ALL,0 \$D,4,UY,0 \$F,3,FX,60000 \$ITER,1,1,1 AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

## FORCE DISTRIBUTIONS:

| ELEMENT | FORCE |
| :--- | :--- |
| 0 |  |
| 0 |  |
| 84853 | tension |
| 0 |  |
| -60000 | compression |

## APPENDIX K ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E,1,2.\$E,1,3 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,60000 \$ITER,1,1,1 AFWRITE \$FINISH \$/INPUT, 27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

FORCE DISTRIBUTIONS:

ELEMENT

0

3

4

5

$$
-60000
$$

$-60000$

FORCE
tension
compression
compression

## APPENDIX K1 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET, 1, $\$$ R, $1,2 \$$ MP,EX, $1,30 \mathrm{E} 6 \$ \mathrm{~N}, 1 \$ \mathrm{~N}, 2,0,50 \$ \mathrm{~N}, 3,50,50 \$ \mathrm{~N}, 4,50,0$ E,1,4 \$E,1,3 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,60000 \$ITER,1,1,1 AFWRITE \$\$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 0 |  |
| 3 | 84853 | tension |
| 4 | 0 |  |
| 5 | -60000 | compression |
| 6 | -60000 | compression |

## APPENDIX K2 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E,1,4 \$E,1,2 \$E,2,4 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,60000 \$ITER,1,1,1 AFWRITE \$FINISH \$/INPUT, 27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 60000 | tension |
| 2 | 60000 | tension |
| 4 | -84853 | compression |
| 5 | 0 |  |
| 6 | 0 |  |

## APPENDIX K3 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E,1,4 \$E,1,2 \$E,1,3 \$E,3,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,60000 \$ITER,1,1,1 AFWRITE \$FINISH \$/INPUT, 27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

## FORCE DISTRIBUTIONS:

| ELEMENT | FORCE |
| :--- | :--- |
| 0 |  |
| 0 |  |
| 84853 | tension |
| -60000 | compression |
| -60000 | compression |

## APPENDIX K4 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN,0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E,1,4 \$E,1,2 \$E,1,3 \$E,2,4 \$E,2,3 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,60000 \$ITER,1,1,1 AFWRITE \$FINISH \$/INPUT,27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 60000 | tension |
| 2 | 60000 | tension |
| 3 | 0 |  |
| 4 | -84853 | compression |
| 6 | 0 |  |

## APPENDIX K5 ANSYS PROGRAM AND FORCE DISTRIBUTIONS


/PREP7 \$KAN, 0 \$ET,1,1 \$R,1,2 \$MP,EX,1,30E6 \$N,1 \$N,2,0,50 \$N,3,50,50 \$N,4,50,0 E, 1,4 \$E, 1, 2 \$E,1,3 \$E,2,4 \$E,3,4 \$D,1,ALL,0 \$D,4,UY,0 \$F,2,FX,60000 \$TTER,1,1,1 AFWRITE \$FINISH \$/INPUT, 27 \$FINISH \$/POST1 \$SET \$PRDISP \$NFORCE FINISH

## FORCE DISTRIBUTIONS:

|  | ELEMENT | FORCE |
| :--- | :--- | :--- |
| 1 | 60000 | tension |
| 2 | 60000 | tension |
| 3 | 0 |  |
| 4 | -84853 | compression |
| 5 | 0 |  |

## BIBLIOGRAPHY

Alain Pages, and Michel Gondran. "System reliability, Evaluation and Prediction in Engineering." Springer-Verlag, New York (1986).

Ang, A. H-S., and Tang, W. H. "Probability Concepts in Engineering Planning and Design." John Wiley and Sons, New York (1984).

Ahmed, S., and Koo, B. "Improved Reliability Bounds of Structural Systems." Journal of Structural Engineering. V116, Nov. (1990): 3138-3147.

Augusti, G., Baratta, A., and Gasciati, F. "Probabilistic Methods in Structural Engineering." Chapman and Hall, New York (1984).

Ayyub, B. M., Ibrahin, A., and Schelling, D. "Posttensioned Trusses." Journal of Structural Engineering, V116, June (1990): 1491-1521.

Ayyub, B. M., and Haldar, A. "Practical Structural Reliability Techniques." J. Struct. Eng., ASCE, 110, No. 8, (1984): 1707-1724.

Bennett, R. M. and Ang, A. H. "Formulations of Structural System Reliability." Journal of Engineering Mechanics, V112, Nov. (1986): 1135-1151.

Besterfield, G. L., Liu, W. K., and Lawrence, M. A. "Brittle Fracture Reliability by Probabilistic Finite Elements." Journal of Engineering Mechanics, V116, March (1990): 642-659.

Bjerager, P., and Krenk, S. "Parametric Sensitivity in First Order Reliability Theory." Journal of Engineering Mechanics, V115, July (1989): 1577-1582.

Cornell, C. A. "Bounds on the Reliability of Structural Systems." J. Struct. Div., ASCE, 93, No. ST1 (1967): 171-200.
de Finetti, B. "Theory of Probability." John Wiley and Sons, New York (1974).
Ditlevsen, O. "Taylor Expansion of Series System Reliability." J. Eng. Mech., ASCE, V110, No. 2 (1984): 293-307.

Ditlevsen, O., and Bjerager, P. "Reliability of Highly Redundant Plastic Structures." J. Eng, Mech., ASCE, V10 (1984): 671-693.

Ditlevsen, O., "Fundamental Postulate in Structural Safety." J. Eng. Mech. Div., ASCE, 109, No. 4 (1983): 1096-1102.

Ditlevsen, O., "Systems Reliability Bounding by Conditioning." J. Eng. Mech. Div., ASCE, 108, No. EM5 (1982) 708-718.

Ditlevsen, O., "Principle of Normal Tail Approximation." J. Eng. Mech. Div., ASCE, 107, No. EM6 (1981): 1191-1208.

Ditlevsen, O., "Narrow Reliability Bounds for Structural Systems." J. Struct. Mech., V7 (1979): 453-472.

Elishakoff, I. "Probabilistic Methods in the Theory of Structures." John Wiley and sons, New York (1985).

Frangopol, D. M. "Sensitivity Studies in Reliability Bound Analysis of Redundant Structures." Struct. Safety, 3, No. 1 (1985): 13-22.

Gallwitzer, S., and Rackwitz, R. "Equivalent Components in First-Order System Reliability." Reliability Engineering, V5 (1983): 99-115.

Garson, R. C. "Failure Mode Correlation in Weakest-link Systems." J. Struc. Div., ASCE, 106, No. ST8 (1980): 1797-1810.

Grigoriu, M. "Crossings of Non-Gaussian Translation Processes." J. Eng. Mech. Div., ASCE, 110, No. 6 (1984): 610-620.

Grigoriu, M. "Approximate Analysis of Complex Reliability Problems." Stru. Safety, I, No. 4 (1983): 277-288.

Grigoriu, M. "Methods for Approximate Reliability Analysis." Struct, Safety, 1, No. 2 (1982): 155-165.

Grigoriu, M., and Turkstra, C. "Safety of Structural Systems with Correlated Resistances." Applied Mathematical Modelling, V3 (1979): 130-136.

Grigoriu, M., Veneziano, D. and Cornell, C. A. "Probabilistic Modelling as Decision Making." ASCE, j. Eng. Mech. Div., V105, No. Em4, Aug. (1979): 585-597.

Horne, M. R. "Plastic Theory of Structures." Pergamon, New York (1979).
Hoel, P. G. "Introduction to Mathematical Statistics." John Wiley and Sons, New York (1984).

Hohenbicher, M., and Rackwitz, R. "Improvement of Second-Order Reliability Estimates by Important Sampling." Journal of Engineering Mechanics, V114, Dec. (1988): 2195-2199.

Hohenbichler, M., and Rackwitz, R. "First-Order Concepts in Reliability." Structural Safety, V1 (1983): 177-188.

Hohenbichler, M., and Rackwitz, R. "Reliability of Parallel Systems under Imposed Uniform Strain." J. Eng. Mech., ASCE, V109, No. 3, June (1983): 896-907.

Hohenbichler, M., and Rackwitz, R. "Non-Normal Dependent Vectors in Structural Safety." ASCE, J. Eng. Mech. Div., V107 (1981): 1227-1258.

Kaufmann, A., Grouchko, D., and Fruon, R. "Mathematical Models for the Study of the Reliability of Systems." Academic Press, New York (1977).

Kjerengtren, L., and Wirsching, P. H. "Structural Reliability Analysis of Series System." Jounal of Structural Engineering, V110, July (1984): 1495-1511.

Kuesel, T. R. "Whatever Happened to Long-Term Bridge Design?." ASCE, V60, Feb. (1990): 57-60.

Madsen, H. O., and Tvedt, L. "Methods for Time-Dependent Reliability and Sensitivity Anslysis." Journal of Engineering Mechanics, V116, Oct. (1990) 2118-2135.

Massonnet, CH., Olszak W., and Phillips A. "Plasticity in Structural Engineering Fundamentals and Applications." Springer-Verlag, New York (1979).

Matheson, J. A. L. "Hyperstatic Structures." Butterworths, London (1971).
Melchers, R. E. "Radical Importance Sampling For Structure Reliability" Journal of Engineering, Mechanics, V116, Jan. (1990): 189-203.

Melchers, R. E. "Structural Reliability Analysis and Prediction." John Wiley and Sons, New York (1987).

Melchers, R. E., and Tang, T. K. "Dominant Failure Modes in Stochastic Structural Systems." Structural Safety, 2 (1984): 127-143.

Melchers, R.E.: Reliability of Parallel Structural Systems. J. Struc. Div., ASCE, 109, No. 11, 1983, p2651-65.

Moses, F. "System Reliability Development in Structural Engineering." Struc. Safety, 1, No. 1 (1982): 3-13.

Murotsu, Y., Kishi, M., Okada, H., Ikeda, Y., and Matsuzaki, S. "Probabilistic Collapse Analysis of Offshore Structure." ASME, VI (1985): 250-258.

Murotsu, Y., Okada, H., Yonezawa, M., and Taguchi, K. "Reliability Assessment of Redudant Structural Safety and Reliability." Elsevier (1981): 315-329.

Murotsu, Y., Okada, H., Niwa, K., and Miwa, S. "Reliability Analysis of Redundant Truss Structures." ASME Publication No. H00165 (1980): 81-93.

Murotsu, Y., Okada, H., Niwa, K., and Miwa, S. "Reliability Analysis of Truss Structures by Using Matrix Methods." Transactions of the ASME. J. Mech. Design, V102, No. 4, Oct. (1980): 749-756.

Murotsu, Y., Yonezawa, M., Oba, F., and Niwa, K. "Method for Reliability Anslysis of Structures. Advances in Reliability and Stress Analysis." ASME Publication No. H00119 (1979): 3-21.

Nowak, A. S., and Tharmabala, T. "Bridge Reliability Evaluation Using Load Tests." Journal of Sructural engineering, V114, Oct. (1988): 2268-2279.

Quek, S. T., and Ang, A. H. "Reliability Analysis of Structural Systems by Stable Configurations." Journal of Structure Engineering, V116, Oct. (1990): 2656-2670.

Paliou, C., Shinozuka, M., and Chen, Y. N. "Reliability and Redundancy of Offshore Structures." Journal of Engineering Mechanics, V116, Feb. (1990): 359-378.

Palmer, A. C. "Structural Mechanics." Clarendon Oxford (1976).
Przemierniecki, J. S. "Theory of Matrix Structural Analysis." Mcgraw-Hill, New York (1968).

Rashedi, R., and Moses, F. "Idendification of Failure Modes in System Reliability." Journal of Structural Engineering, V114, Feb. (1988): 292-313.

Reddy, J. N. "An Introduction to the Finite Element Method." Mcgraw-Hill, New York (1984).

Ronold, K. O. "Reliability Analysis of Tension Pile." Journal of Geotechnical Engineering, V116, May (1990) 760-773.

Rosenblueth, E. "On Computing Normal Reliabilities." Struct. Safety, 2, No. 3 (1985): 165-167.

Shinozuka, M. "Basic Analysis of Structural Safety." J. Struct. Div., ASCE, 109, No. 3 (1983): 721-740.

Terada, S., and Takahashi, T. "Failure-Conditioned Reliability Index." Journal of Structural Engineering, V114, April (1988): 942-952.

Thoft-Christensen, P., and Baker, M. J. "Structural Reliability Theory and Its Applications." Spring-Verlag, New york (1982).

Thoft-Christensen, P., and Murotsu, Y. "Application of Structural Systems Reliability Theory." Springer-Verlag, New York (1986).

Thoft-Christensen, P., and Sorensen, J. D. "Reliability of Structural Systems with Correlated Elements." Applied Mathematical modelling, V6 (1982): 171-178.

Tvedt, L. "Distribution of Quadratic Forms in Normal Space--Application to Structural Reliability. Journal of Engineering Mechanics, V116, June (1990): 1679-1695.

Wirsching, P. H., and Wu, Y. T. "Advanced Reliability Methods for Structural Evaluation." Journal of Engineering for Industry, V109, Feb. (1987): 19-23.

Wu, Y. T., and Wirsching, P. H. "New Algorithm for Structural Reliability Estimation." Journal of Engineering Mechanics, V113, Sept. (1987): 1319-1336.

Zahn, J. J. "Empirical Failure Criteria with Correlated Resistance Variables." Journal of Structural Engineering, V116, Nov. (1990): 3122-3137.

Zienkiewicz, O, C. "The Finite Element Method in Engineering Science." McGraw-Hill, New York (1971).

