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INVESTIGATION OF DIFFERENT CMOS DRAM
SENSE AMPLIFIER CONFIGURATIONS IN VLSI

by
Bihju Chiu

Thesis submitted to the Faculty of the Graduate School of
the New Jersey Institute of Technology in partial fulfillment
of the requirements for the degree of
Master of Science in Electrical Engineering
1988

APPROVAL SHEET

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Amplifier Configurations by Simulation

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ABSTRACT

Title of Thesis : Investigation of Different CMOS Sense
Amplifier Configurations by Simulation

Bihju Chiu, Master of Electrical Engineering, 1988

Thesis directed by : Dr. Michael P. Singh.

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Sense amplifiers are particularly difficult circuits to design. In this work, only CMOS sense amplifiers are considered. There are typically two configurations of CMOS sense amplifiers : the cross-connected flip flop configuration and the current-mirror configuration. They are widely used nowadays with various modifications. These improved configurations are simulated and optimized with SPICE package, and their relative performances are also compared in this thesis.

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This thesis itself is an acknowledgement to the individuals who have contributed to it.

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I also want to thank my parents for their support and love, and wish this thesis will be the most valuable Mother's Day gift.

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CHAPTER ONE INTRODUCTION

Sense amplifiers play a major role in deciding the performance of semiconductor memories. This is specially so in the case of modern high density dynamic memories, whose cells have small storage capacitors and use only a single transistor. The differential voltage available is only of the order of 0.1v or less. The sense amplifiers have to receive the small input voltage and develop a large output voltage within the shortest possible time so that the access time for the memory can be made small. Basically, sense amplifiers are either flip-flops or current mirrors whose output nodes latch into high and low states by regenerative action. There may be a second stage of amplification but invariably the output reaches the data output pad after passing through a buffer.(Fig.1.1)

As shown in Fig.1.2, B/S lines are directly connected to the sense amplifier input node1 and node2. Two transistors M1 and M2 are connected to the dummy cells. B/S lines run symmetrically on both the sides of sense amplifier, connecting the drains of the storage transistors. Just two storage cells are shown in the diagram (represented by C_S). M3 and M4 are their access transistors.

Read cycle starts by precharging B/S lines to a fixed value (V_{PRE}). When the address is placed on the memory chip,

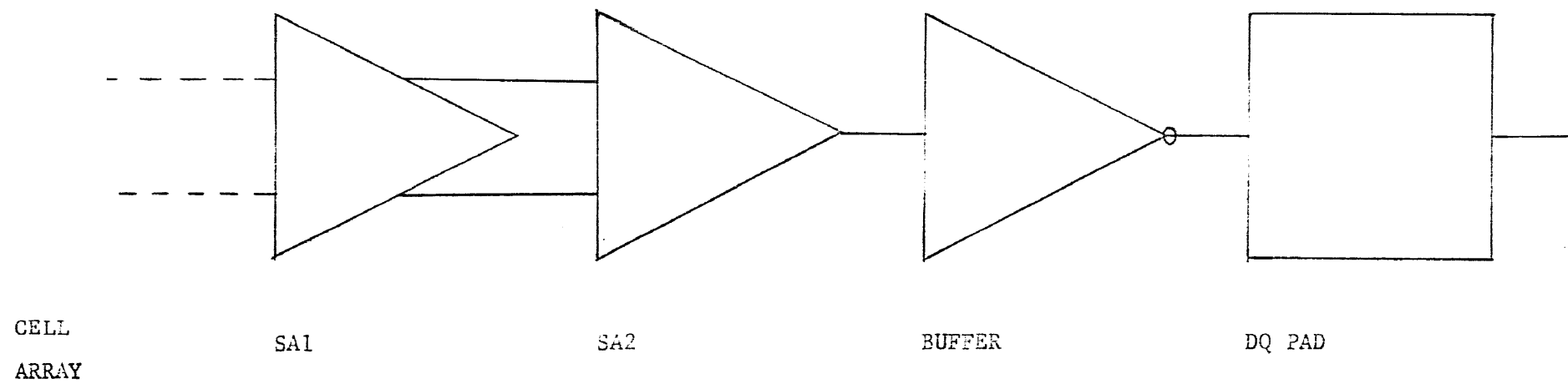


Fig. i.1

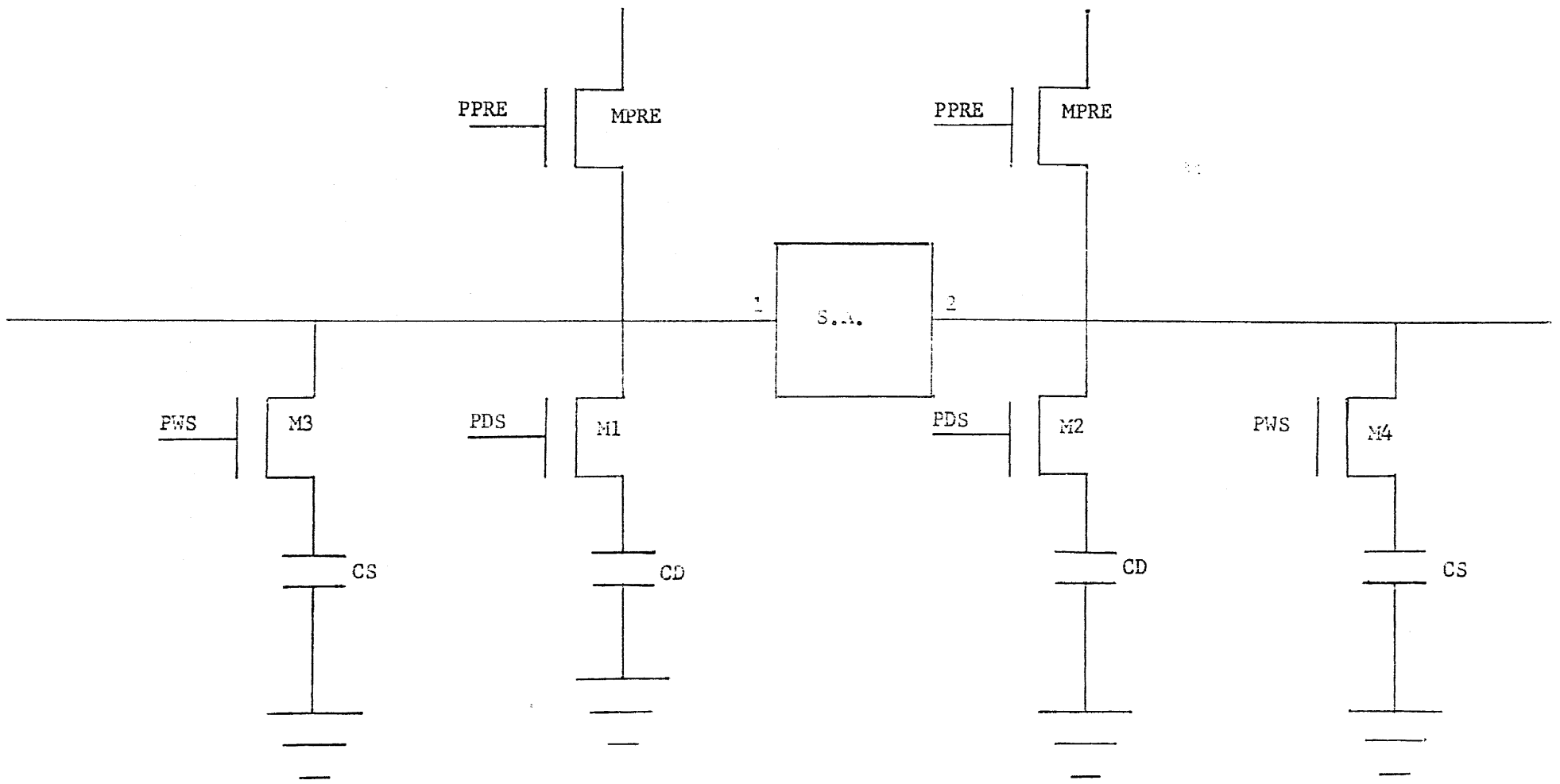


Fig. 1.2

one of the memory cells is selected, say for example, M3 is selected by the word line (P_{WS}). When a memory cell is selected on one side, the dummy cell is selected on the other side of the sense amplifier. Before selecting, dummy cell is charged to a reference potential (V_{REF}). If the selected memory cell C_S has a stored 'ONE' in it, it is transferred to node1 whereas V_{REF} is transferred to node2. Thus differential voltages are introduced on the opposite sides of the sense amplifier and the sense amplifier starts to work.

Once the latching is completed, dummy cells and B/S lines are precharged to V_{REF} and V_{PRE} for the next cycle.

Nowadays, CMOS technology is used more and more widely in integrated circuits processing, especially when the circuits are of large scale or very large scale integration. Although CMOS does require more complex processing, there are several advantages of using it that are worth the trouble:

1. Very Low Static Power Dissipation :

This is because in a CMOS inverter, the signal inversion is achieved by turning one of the transistors heavily on and simultaneously turning the other off. Since these two devices are in series, only junction leaking currents will be drawn from the power supply in either of the two stable states.

2. High Speed :

This is achieved by the push-pull operation of the inverter. During switching from logic one to logic zero or vice versa, the node capacitance is always charged or discharged through a heavily conducting MOS transistor.

3. High Noise Immunity :

The following characteristics produce a very nearly ideal transfer characteristic :

- (1) Symmetry.
- (2) A very high gain in the transition region.
- (3) The very high off/on resistance ratio of the device.

With CMOS technology permeating all IC fabrication, cells and peripheral circuits in memories have also switched over to CMOS. One type of CMOS sense amplifier is a simple cross-connected CMOS flip-flop circuit.(Fig.1.3) Another type is the current mirror circuit.(Fig.1.4) In practice, however, these simple circuits are modified and the aim of this work is to investigate these new configurations in detail and compare their relative performances. Though these circuits appear in the literature, they are seldom described in detail. Normally they are mentioned in a cursory manner.

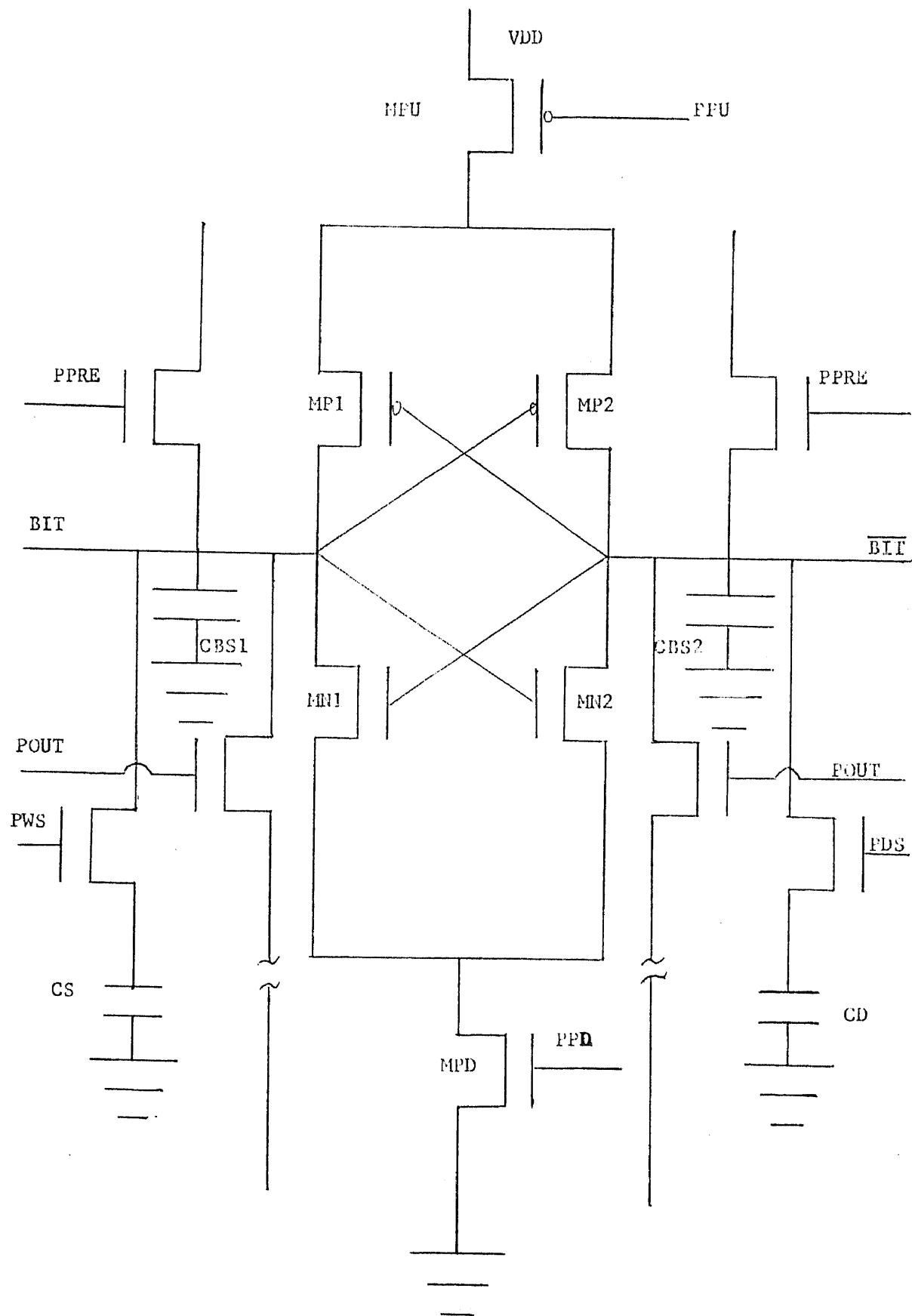


Fig. 1.3

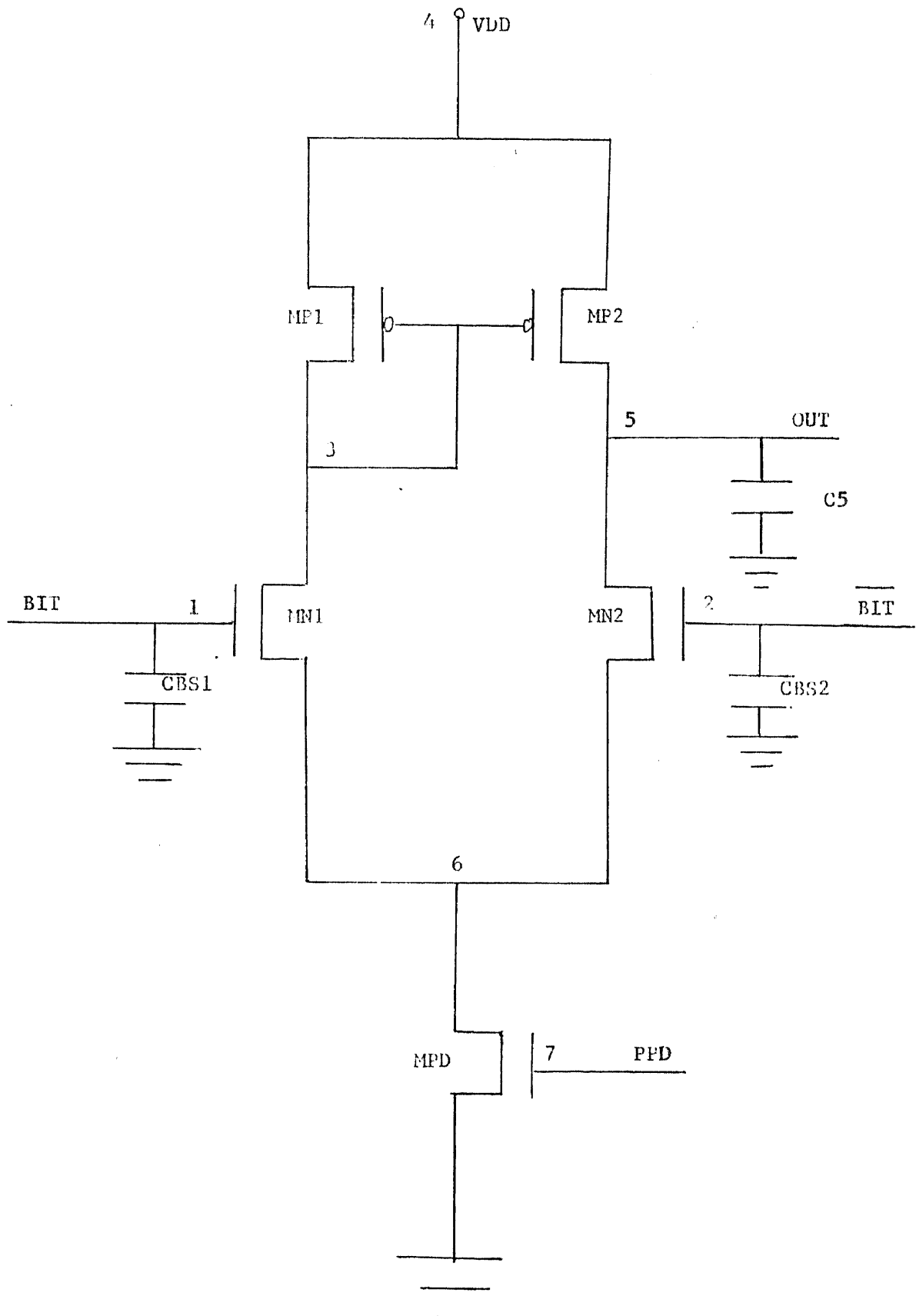


Fig. 1.4

The operating conditions such as relative timing between the top and bottom pull up and pull down pulses and the aspect ratios used for the transistors are rarely given. In this work, initially optimal operating conditions and aspect ratios for various transistors are arrived at. Then the speed of the these circuits are compared for the same input and output conditions. Conclusions such as these and others regarding optimum aspect ratios will be of immense practical value for memory designers.

CHAPTER TWO THE CMOS FLIP FLOP SENSE AMPLIFIERS

2.1 The Standard Form

2.1.1 Principle of Operation

Fig.1.3 shows the standard CMOS flip flop sense amplifier, which consists of 3 NMOS and 3 PMOS transistors. MP1 and MP2 are PMOS load transistors whose W/L ratios will be called B_{LO} , MN1 and MN2 are NMOS driver transistors whose W/L ratios will be called B_{DR} . MP1, MP2 and MN1, MN2 are two perfectly matched pairs. MPU and MPD are PMOS pull-up transistor and NMOS pull-down transistor with B_{PU} and B_{PD} as W/L ratio respectively.

C_{BS} is a 1PF load capacitor, $V(1)$ and $V(2)$ are the voltages at nodes 1 and 2 respectively. P_{PU} and P_{PD} are the gate clock pulses of MPU and MPD. Both of them have the same delay time and then change to 0V and V_{DD} abruptly. V_{DD} is 5V from the power supply.

The initial values of $V(1)$ and $V(2)$ are V_{I1} and V_{I2} , and $V_{I1} < V_{I2}$. (Let's assume they are 2.4 and 2.5) When P_{PD} rises to V_{DD} , MPD conducts and node 6 is pulled down to the ground. At this time, MP1, MP2, MN1 and MN2 are all on. Since V_{I2} is higher than V_{I1} , MN1 conducts more than MN2, $V(1)$ decreases faster than $V(2)$. And because $V(1)$ decreases faster than $V(2)$, the V_{GS} of MP2 becomes higher than that of

MP1 and MP2 conducts more than MP1. It makes $V(2)$ to rise faster than $V(1)$. When $V(1)$ finally reaches V_t , MN2 stops conducting, $V(2)$ rises much faster until finally it reaches V_{DD} and $V(1)$ continues to decrease since MN1 is still on, until it finally reaches a value close to zero.

2.2 The Modified Forms

The bit line capacitance, i.e. the capacitance of the line which runs all along the memory cell array, loads the latching nodes. The amplifier must be able to drive these large capacitances on the two nodes. This severely degrades the sensing time. Modified versions of the CMOS flip-flop sense amplifiers avoid this capacitive load. One way is to insert isolation nodes as shown in Fig.2.1.(McAdams 1986; Miyamoto 1986; Kimura 1987) When the sense amplifier is enabled, the isolation transistors are turned off to isolate the nodes which latch.

Another approach is to separate the p channel cross-connected transistors from the n channel cross-connected transistors with the help of separation transistors as shown in Fig.2.2 (Furuyama 1986; Fujii 1986; Miyamoto 1987). The bit line capacitance is connected to the p channel transistors but the latching nodes at the n channel cross connections do not face this large capacitance directly.

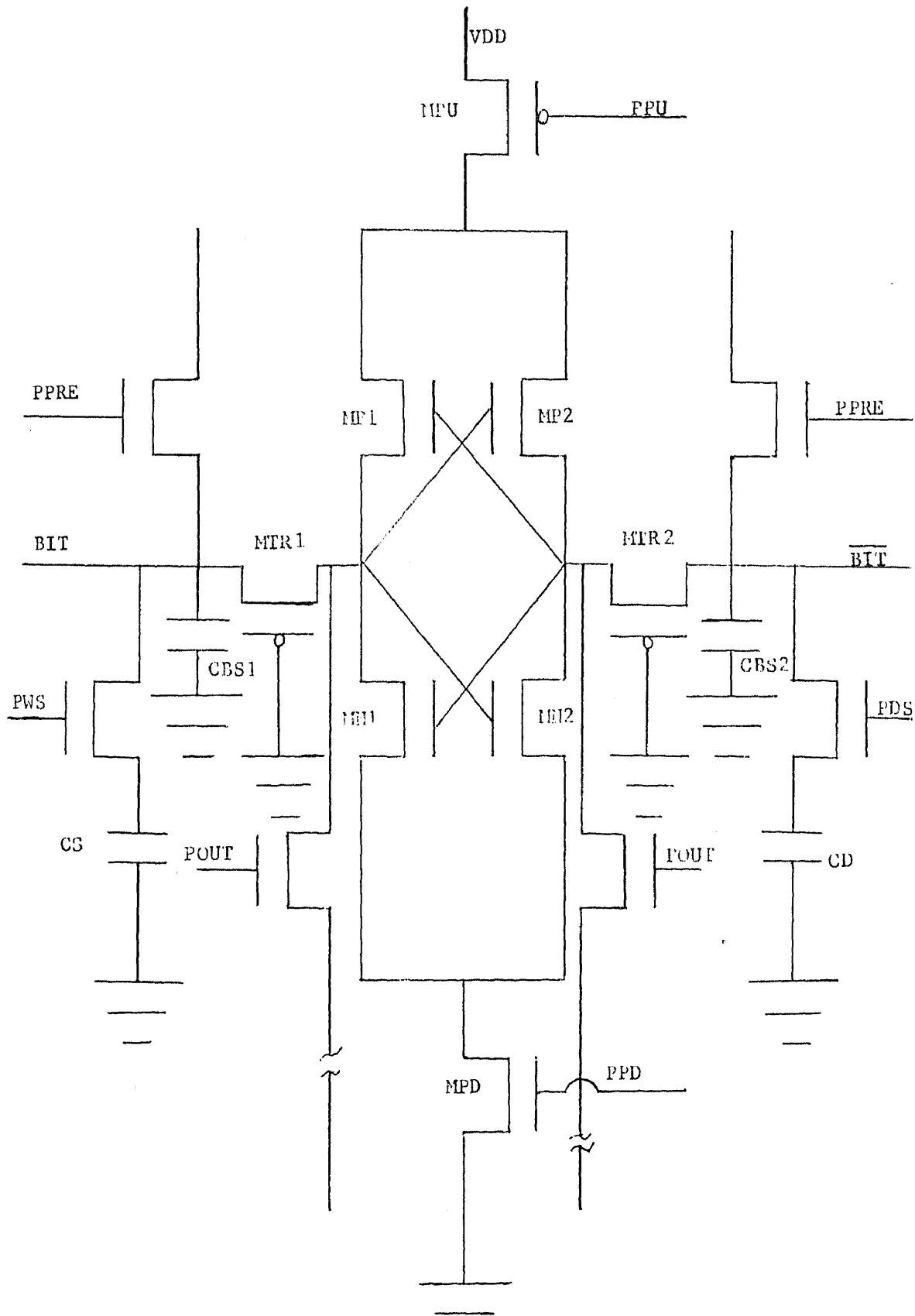


Fig. 2.1

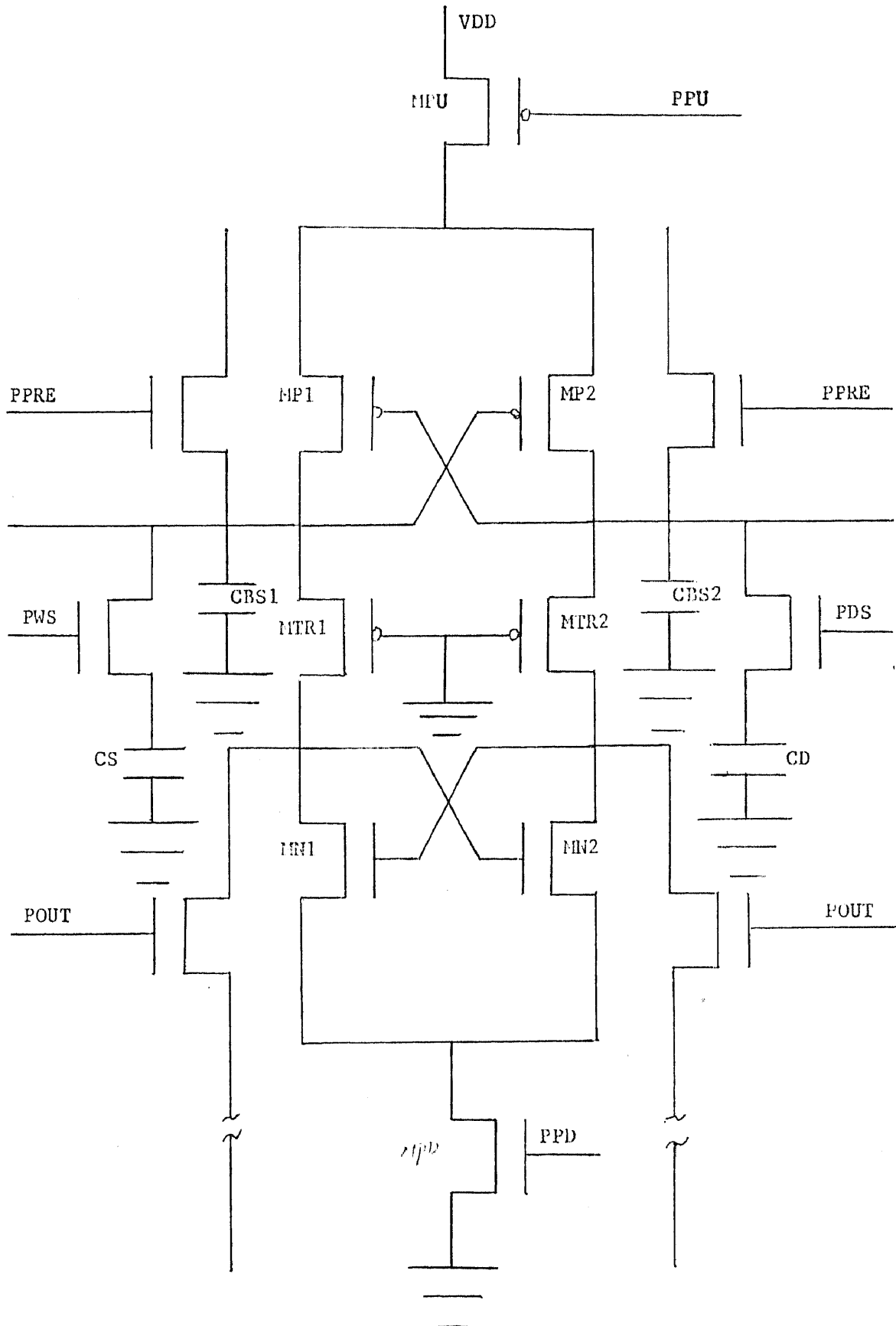


Fig. 2.2

2.3 Simulation Results

2.3.1 Clock Timings

Simulations show that for both the modified configurations, there is not much advantage in relatively delaying the pull-up and the pull-down clocks. They can be simultaneous. Though the pull up may be delayed in case of the first configuration which uses isolation transistors, delay of pull down clock adds a dead time and makes the sensing process inefficient. For the relative timing between turning off the isolation transistor and turning on the flip flop sense amplifier (pull up and pull down transistors), again simultaneous operation is seen to be optimum. Turning off the isolation transistor may be delayed, say, by 1NS with respect to the pull up and pull down and the performance slightly improves. Turning the isolation transistor much later or much earlier worsens the performance since the large capacitance of the bit sense lines impede rapid changes in the voltages of the latching nodes. For the isolation and separation transistors, PMOS was seen to give better results than NMOS. PMOS can take a node to V_{DD} easily.

2.3.2 Voltage Levels

Optimum common mode input signal is seen to be 5V. This is expected since higher voltages make the driver transistors

to conduct faster and the low going node reaches the threshold voltage earlier. Also greater the differential input signal, better is the performance and this is obvious.

2.3.3 Aspect Ratios

The NMOS driver transistors, if they have higher aspect ratios, the latching process will be faster. Simulations show that increasing W/L greater than 4 does not result in much superior performance. Therefore the optimum value is chosen as 4. For the pull up and pull down transistors, again, higher W/L values will be better since they will take the nodes closer to the rails quickly. The final V_{OL} and V_{OH} will also be better due to potential division of transistor resistances. Increasing above 4 did not result in much enhanced performance and so 4 is chosen as the optimum. The load transistors do not play that much role and a minimum size with W/L=1 seem to work fine. Increasing the size does not yield much better performance. The isolation and separation transistors have an optimum W/L of 1. Increasing the size further does not appreciably alter the performance.

2.3.4 Comparative Performance

For the optimized clock timings, voltage levels and aspect ratios, the two circuits are simulated for the same output load capacitance of 0.1PF. Differential input voltage

is fixed at 200mV. The SPICE parameters are taken from (Glasser 1985) and L is 2 um. Fig.2.3 gives the results. The first configuration with isolation transistor is clearly the winner. Latching process is completed much earlier. The second configuration with separation transistors has added resistances in the main paths and that will be causing additional delays.

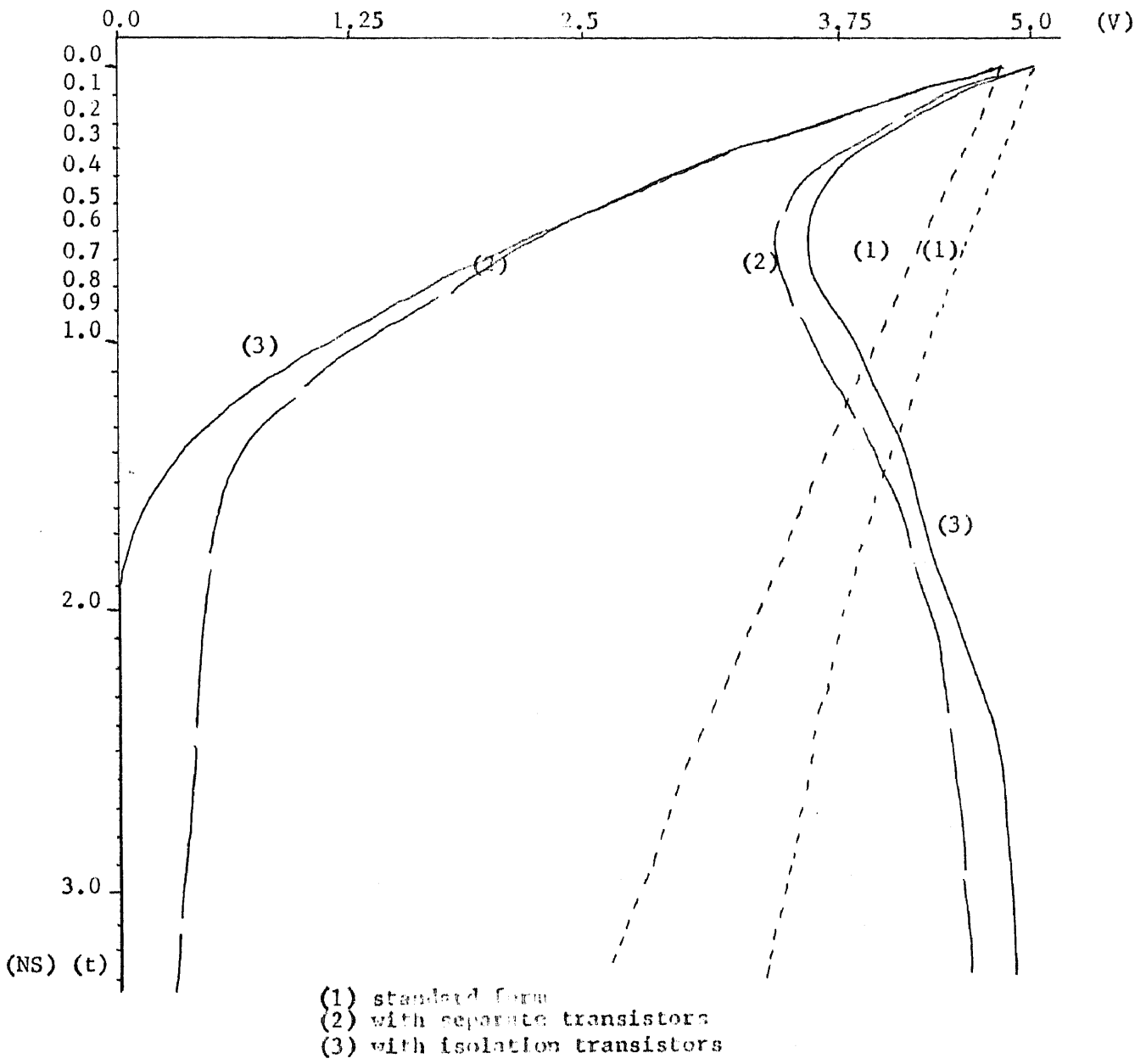


Fig. 2.3

CHAPTER THREE THE CURRENT MIRROR CMOS SENSE AMPLIFIERS

3.1 The Standard Form

3.1.1 Principle of Operation

Fig.1.4 is a standard current mirror sense amplifier.(Donoghue 1985; Yamamoto 1985; Kobayashi 1985; Kayano 1986) It is also used as front-end in operational amplifiers. It detects voltage difference, rather than absolute values.

The current mirror sense amplifier consists of two PMOS and three NMOS transistors. MP1 and MP2 are PMOS load transistors with B_{LO} as W/L ratios, MN1 and MN2 are NMOS driver transistors whose W/L ratios will be called B_{DR} later. M_{PD} is NMOS pull-down transistor with B_{PD} as W/L ratio.

MP1, MP2 and MN1, MN2 are two perfectly matched pairs.(Annaratone, 1986) C_{BS1} and C_{BS2} are 1PF load capacitors. V(1) and V(2) are the voltages at node 1 and 2 respectively. P_{PD} is the gate clock pulse of MPD. V_{DD} is 5V from the power supply. The initial values of V(1), V(2) and V(5) are V_{I1} , V_{I2} and V_{I5} .

The bit line is connected to node 1, and its reference value is connected to node 2. Initially, node 7 is 0V, M_{PD}

is off. Before it begins to work, node 1, 2 and 5 are precharged to fixed values. After $V(7)$ is pulled up, the circuits starts to work. If V_{I2} is lower than V_{I1} , MN2 conducts poorer, and V_5 begins to charge up and approaches to V_{OH} . If V_{I2} is higher than V_{I1} , MN2 conducts better than MN1, V_5 starts to discharge, and finally reaches a value near zero.

This kind of circuit is called current mirror amplifier because when both load transistors are in saturation mode, the ratio of the current flowing through the drains of both loads is equal to the ratio of their beta values. If the beta value of both transistors are the same, the current flowing through both transistors will also be equal.

If V_{I1} is higher than V_{I2} , the current flowing through MN1 will be duplicated to MP2. The current flowing through MN2 is smaller than that of MN1 and so the extra current will flow through node 5 to charge up C_5 .

When V_{I1} is smaller than V_{I2} , the current flowing through MN1 is smaller and is duplicated to MP2. The current flowing through MN2 is larger than that of MN1 and so C_5 will be discharged. Thus this circuit can work better with the help of current mirror load than a normal differential amplifier which does not have the current mirror action.

3.1.2 Simulation Results For The Standard

Current Mirror Circuit :

Voltage Levels :

The optimum precharged voltages for V_1 , V_2 and V_5 are decided by the following procedure : at first, common mode voltage of V_{I1} and V_{I2} is changed, V_5 is not precharged so the optimum DC output value can be decided by DC analysis. The best output is decided from the difference of V_5 (high) and V_5 (low) when $V_{I1} > V_{I2}$ and $V_{I1} < V_{I2}$. After deciding the optimum V_{I1} and V_{I2} , different V_5 initial values are assigned and optimum value for V_{PRE} for V_5 is decided. Then, the procedure continues to find the optimum value of other parameters such as aspect ratios. After aspect ratios are decided, V_{I1} , V_{I2} and V_{I5} are optimized again. For this problem, the best value of V_{I5} turns out to be 2.7V and the common mode of V_{I1} and V_{I2} is 0.7V.

The optimum common mode level of V_{I1} and V_{I2} can be explained as follows :

The optimum value is about the V_t (threshold voltage) of NMOS transistor. This makes the driver transistor with higher initial value to be nearly 'ON' and the other to be 'OFF'. With only one of the drivers 'ON', C_5 is either charged up by

MP2 or discharged by MN2. The speed is quicker this way than being charged up by MP2 and discharged by MN2 at the same time. That will happen if V_{I1} and V_{I2} are both above V_t . Thus the discrimination of the input voltages begins early if the input voltages are on either side of V_t .

Aspect Ratios :

The NMOS driver transistors, if they have higher W/L ratios, the performance will be better. Simulations show that increasing W/L greater than 22 does not result in much superior performance. Therefore the optimum value is chosen as 22.

For the pull down transistor, higher W/L ratio will be better, since it makes the common node closer to the ground rail quickly. After W/L ratio becomes greater than 4, there is no much change of output, so the optimum value of B_{PD} is 4.

For PMOS load transistors, however, if W/L is greater than one, the higher values give worse results; If W/L is smaller than one, the smaller values give better results, although there is no much change. So the optimum value of B_{LO} is one.

3.2. The Modified Configurations :

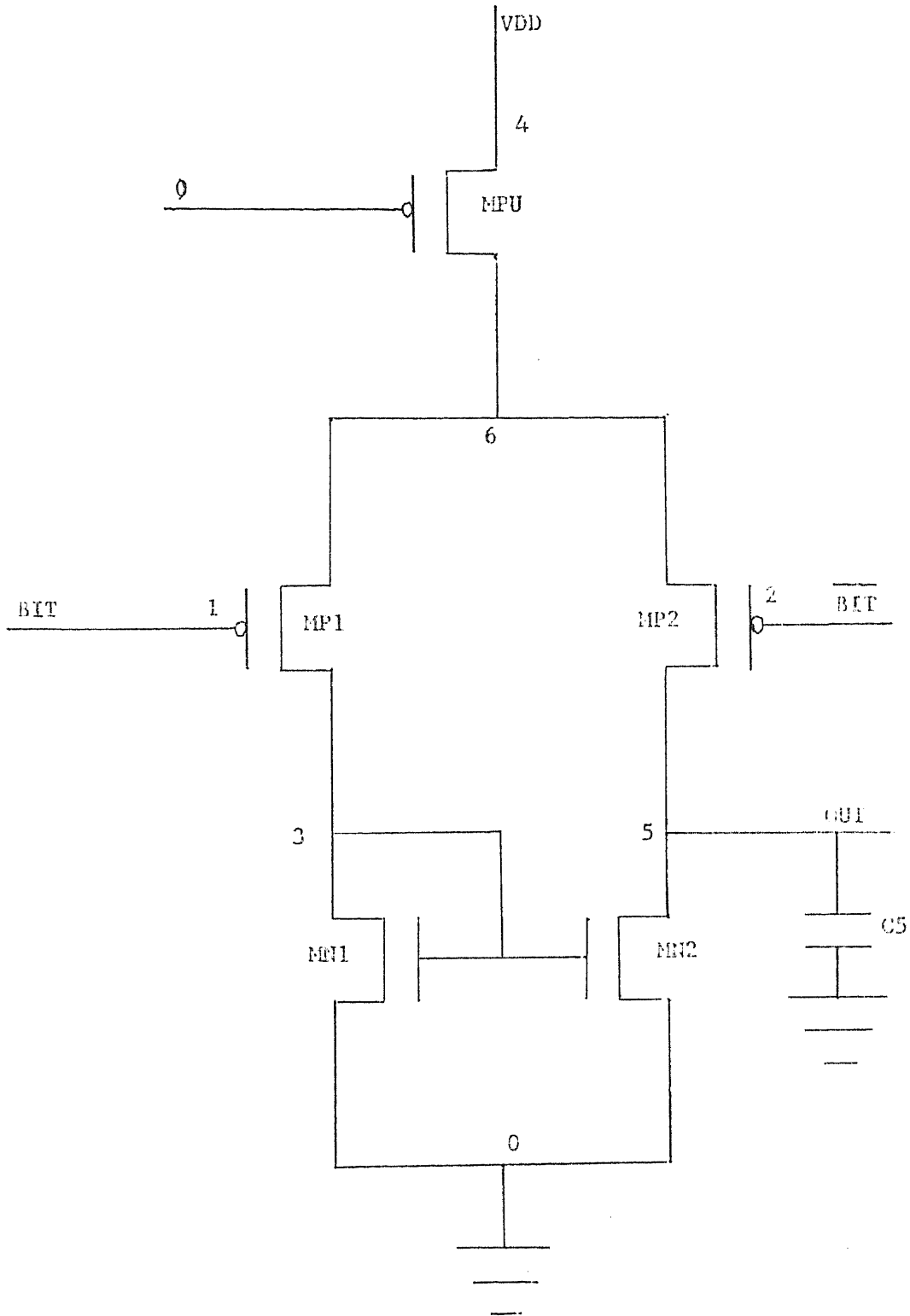


Fig. 3.1

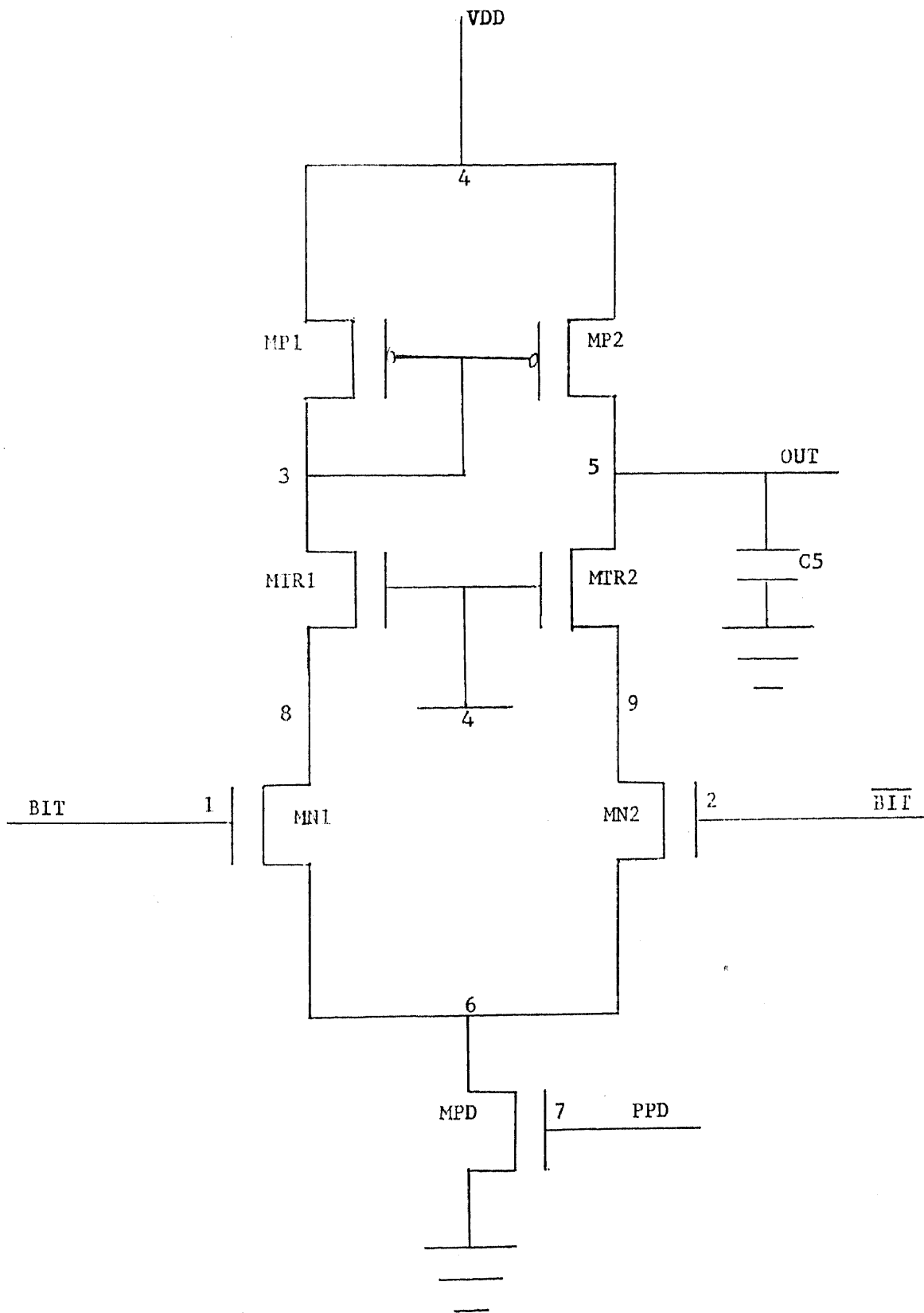


Fig. 3.2

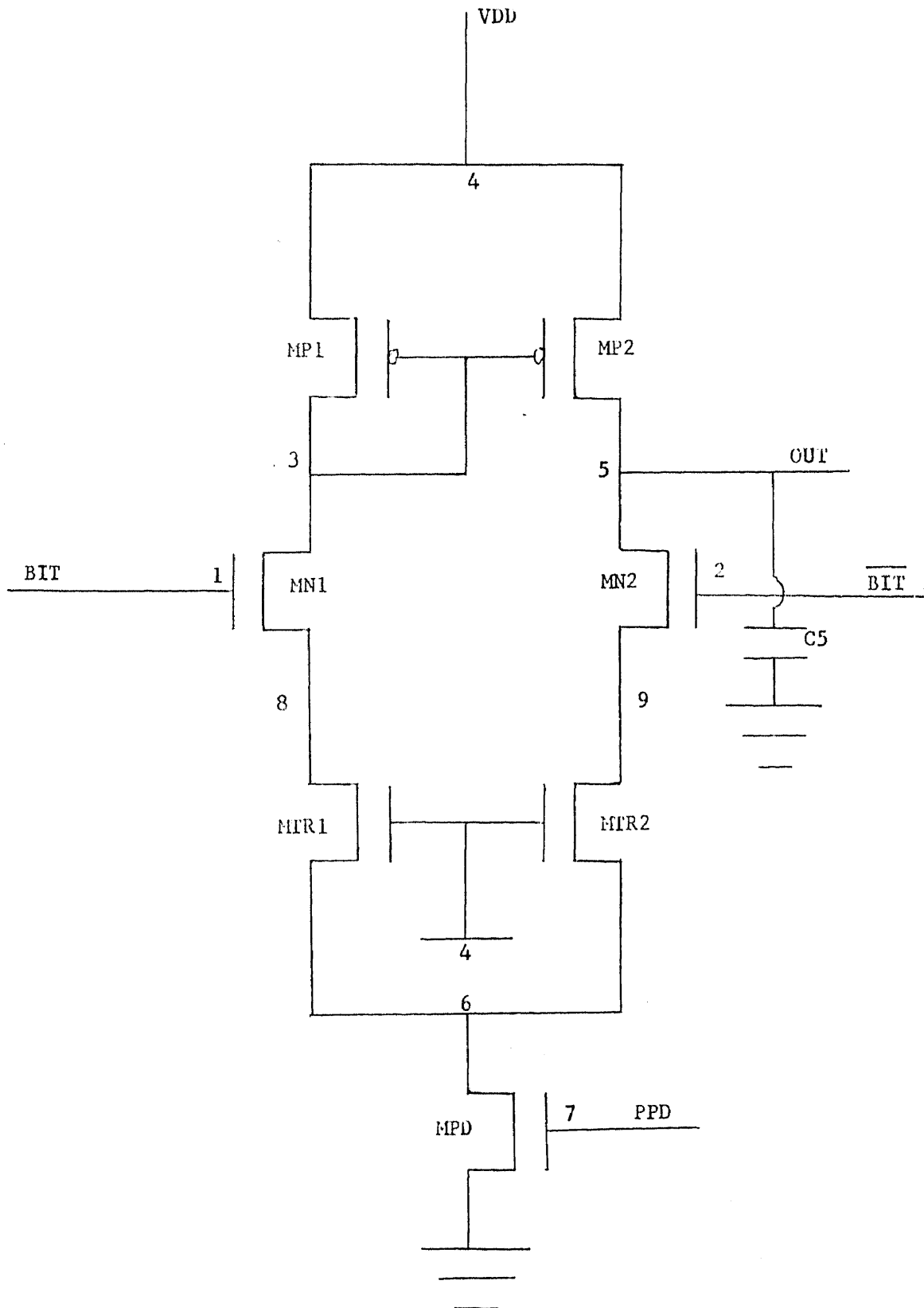


Fig. 3.3

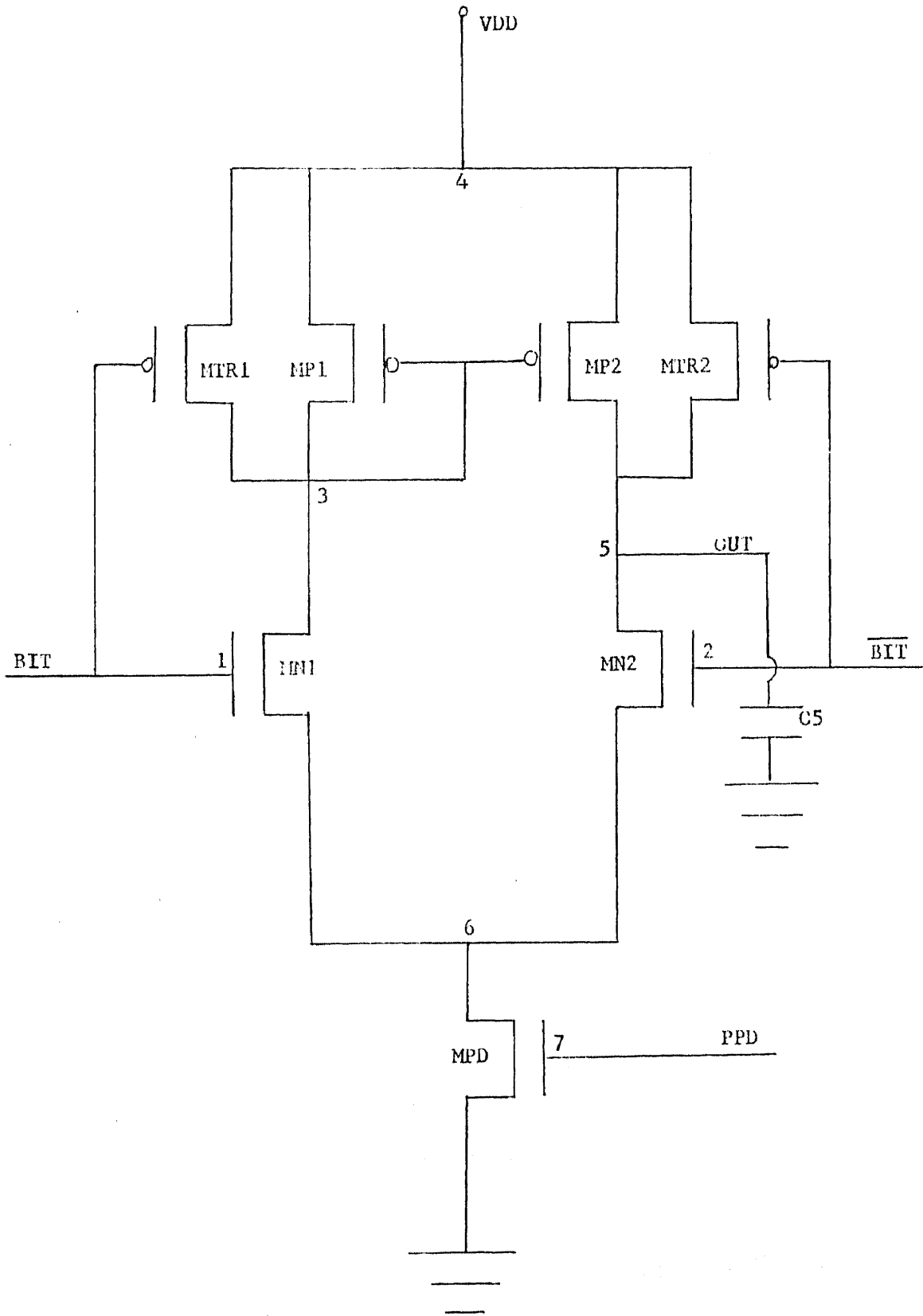


Fig. 3.4

Fig.3-1,3-2,3-3 and 3-4 show four different types of modified forms derived from the standard circuit.

3.2.1 Complementary Form

3.2.1.1 Schematic

Fig.3-1 shows the structure of one modified form from the standard circuit.(Furuyama 1987; Ohtsuka 1987) It is almost the inverse of the standard one with PMOS pull-up transistor and the bit lines connected to the gate of the PMOS 'load' transistors (which act as drivers).

3.2.1.2 Simulation Results :

3.2.1.2.1 Voltage Level :

With the same procedure as for the standard form, simulations reveal that the common mode of V_{I1} and V_{I2} is about 4.2V, and V_{I5} is 4.9V. The voltage level is much higher than that of the standard form.

The optimum common mode value of V_{I1} and V_{I2} can be explained as follows :

The optimum value can make the V_{GS} value of both PMOS

transistors about V_t . This makes one of the 'loads'(drivers) to be nearly 'ON' and the other to be 'OFF' and let C_5 to be either charged up by MP2 or discharged by MN2. This will initiate discrimination earlier and speed up the process.

Aspect Ratios :

The NMOS 'driver' transistors,(which act as loads) if they have lower W/L ratios, the performance will be better. But the NMOS transistors have to support the heavy currents flowing from the top PMOS transistors. Simulations show that increasing W/L greater than 12 does not result in much superior performance. Therefore the optimum value of B_{DR} is chosen as 12.

For the pull-up transistor, higher W/L ratio will be better, the reason being the same as the standard form. The optimum value of B_{PD} is 4.

For the PMOS 'load' transistor which act as drivers higher W/L value can give better performance. The optimum value of B_{LO} is 24.

3.2.2 Circuits With Level Shifting Transistors

3.2.2.1 Schematic

Fig.3-2 and 3-3 show two other modified current mirror sense amplifiers.(Matsui 1987) They are almost the same as the standard form but with a pair of level shifting transistors interposed either above or below the driver transistors.

In Fig.3-2, the level shifting transistors are added between PMOS load and NMOS driver transistors, while in Fig.3-3, the level shifting transistors are added below the NMOS driver transistors.

3.2.2.2 Simulation Results :

3.2.2.2.1 Voltage Level :

With the same procedure before, the common mode of V_{I1} and V_{I2} of both configurations are around 0.7V, i.e. the same as that of the standard form. This result is rather unexpected since the presence of extra transistors is said to shift the common mode voltage.(Matsui 1987) The V_{I5} of Fig.3-2 is 3.1V, and that of Fig.3-3 is 2.0V. The precharge level of the output node seems to get shifted. However, the performance did not change significantly with V_{I5} .

3.2.2.2.2 Aspect Ratios :

For the NMOS driver transistors of both circuits, if

they have higher W/L ratio, the performance will be better. And the optimum value of B_{DR} is 22, which is the same as the standard form.

For the pull-down transistors of both circuits, again, higher W/L is better and optimum value is about 4.

For the PMOS load transistors of both circuits, neither higher nor lower W/L gives better performance and so the optimum value of both are one.

For the level shifting transistors of Fig.3-2, neither higher nor lower W/L ratio gives better performance. So the optimum value is one. For the circuit of Fig.3-3, if W/L ratio of the level shifting transistor is higher, the performance is better. Optimum value is around 4. This may be due to the fact that the bottom transistors need to pass the large currents that are possible with the drivers. Simulations also showed that NMOS is better than PMOS for the level shifting transistors. This is so because NMOS is good for pulling down. PMOS is good for pulling up a node. PMOS when present in the discharge path (to the ground) will offer higher resistance and slow down the process.

3.2.3 Circuit With Additional Transistors Across The Loads

3.2.3.1 Circuit Diagram

Fig.3-4 shows another type of modified circuit.(Wada 1987) It is the same as the standard form but there is another pair of PMOS load transistors with their gates connected to the bit line or the inverted bit line. The additional two PMOS transistors can help the circuit to get additional gain. For example, when V_{I1} is greater than V_{I2} , the current flowing through MN1 increases and that of MTR1 decreases (its gate voltage being higher). This causes the current flowing through MP1 to increase. This increased current is duplicated by MP2. V_{I2} being lower, makes the current flowing through MN2 to decrease. The current charging up C_5 is much bigger than that of the standard form and thus there is additional gain.

3.2.3.2 Simulation Results :

3.2.3.2.1 Voltage Level :

With the same procedure as before, the common mode value of V_{I1} and V_{I2} is 2.6V, and precharge value for V_{I5} is 2.3V.

3.2.3.2.2 Aspect Ratios :

For the NMOS driver transistors, neither higher nor lower W/L ratios would worsen the result. So the optimized value of B_{DR} is one. This result is in complete contrast

with the other modified forms.

For the pull down transistor, again, there is no advantage in increasing or decreasing the W/L ratio. The optimum value of B_{PD} is one. This again is in contrast to previous results.

For the regular PMOS load transistor, if W/L ratio is higher, the performance is a little bit better, but it makes not much difference. So the optimum value of B_{LO} is one.

For the additional PMOS load transistor pair, neither higher nor lower W/L ratio will make the performance better. So the optimum value is one. The above results are surprising. This means that this configuration will occupy the least area. The performance with smaller area may be attributed to the extra gain as explained in 3.2.3.1.

3.2.4 Comparative Performance :

Fig.3-5 shows the performance of the standard and modified sense amplifiers with their optimized parameters.

3.2.4.1 Output Level :

It appears that the differential output voltage of the following sense amplifiers : (1) The standard form, (2) The

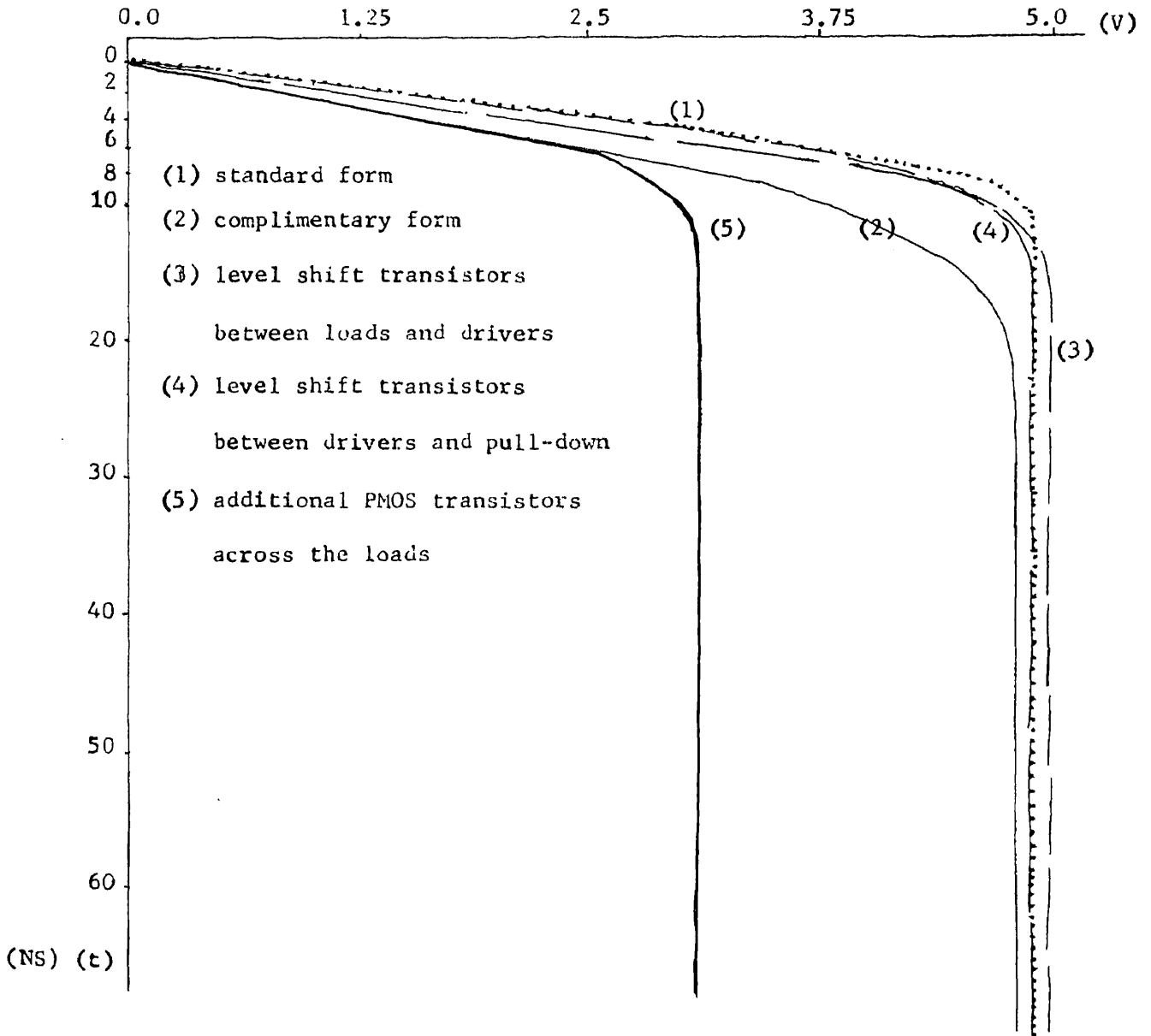


Fig. 3.5

level shifting forms and (3) The complementary form are around 5V, and that means the $V_5(\text{high})$ can approach 5V, and $V_5(\text{low})$ can approach 0V. So they are good enough. But the performance of the circuit with additional transistors across the loads is not so good. It is about 3.0V, which means the $V_5(\text{high})$ can only approach about 4V, and $V_5(\text{low})$ can only approach about 1V.

3.2.4.2 Switching Speed :

It appears that all these circuits have almost the same speed, while the speed of the circuit with level shifting transistors between driver and pull-down transistor is a little slower than others. The reason may be the additional resistance in the discharge path.

Size :

Table 3-1 shows that the size of the circuit with additional transistors across the loads is the smallest. It can still have the same speed as others in approaching the final values.

Initial Levels :

Table 3-1 shows another important comparison of V_{I1} , V_{I2} and V_{I5} . Circuits in the following : (1) The standard form

and (2) The level shifting form, have the same low V_{I1} and V_{I2} . While V_{I5} in the standard form is 2.7V, in the circuit with level shifting transistors between the loads and drivers, it is 3.1V and in the circuit with level shifting transistors between the drivers and pull-down transistor, it is 2.0V.

The V_{I1} , V_{I2} and V_{I5} of the circuit in the complementary form is the highest, and those of the circuit with additional transistors across the loads is around the middle value(2.5V).

CHAPTER FOUR CONCLUSION

Two modified CMOS flip flop sense amplifier configurations are investigated in this work. Optimum operating conditions and aspect ratios are obtained and the performances of the two circuits are compared for the same input and output conditions. The sense amplifier that uses the isolation transistors outperforms the other configuration that uses the separation transistors. The separation transistors, though they are ON, add some delay and resistance and the latching process gets slightly delayed. Also the large capacitances of the bit sense lines are not fully isolated from this circuit during the latching process. Therefore the performance is expected to be inferior to the other configuration.

In case of current mirror sense amplifiers, five different configurations are investigated in detail and their optimized parameters are obtained. The optimum common mode input values of the standard form and the complimentary form make the V_{GS} of the drivers about V_t . This makes only one driver 'ON' at one time and can speed up the charging or discharging action of the load capacitance. The circuit with additional PMOS transistors across the load transistors has the smallest area. Therefore any one wanting the minimum area should go for this one. Though V_{OH} and V_{OL} are not as good as those of others, this circuit can be used as the





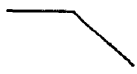










	STANDARD FORM	COMPLEMENTARY FORM	LEVEL SHIFTING BETWEEN LOADS AND DRIVERS	LEVEL SHIFTING BETWEEN DRIVERS AND PULL-DOWN	ADDITIONAL TRANSISTORS ACROSS LOADS
VREF	0.8 0.6 2.7	4.3 4.1 4.9	0.8 0.6 3.1	0.8 0.6 2.0	2.7 2.5 2.3
BDR	 44/2	 24/2	 44/2	 44/2	1
BLO	 1	 48/2	 1	 1	 1
BPD	 8/2	 8/2	 8/2	 8/2	1
BTR	x	x	 1	 8/2	1
SPEED	1	4	2	3	5
FINAL	2	3	1	2	4

Table 3.1

first stage. The second stage can take care of the final high and low values.

Not all simulations have been thoroughly explained and this is a fertile field of investigation for future researchers.

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APPENDIX

CMOS2/ALL SENSE AMPLIFIER

VDD 4 0 5V

V7 7 0 5V

C501 501 0 0.1PF

C502 502 0 0.1PF

C503 503 0 0.1PF

C504 504 0 0.1PF

C505 505 0 0.1PF

C506 506 0 0.1PF

C507 507 0 0.1PF

C508 508 0 0.1PF

C509 509 0 0.1PF

C510 510 0 0.1PF

CLA101 101 0 1PF

CLA201 201 0 1PF

CLA102 102 0 1PF

CLA202 202 0 1PF

CLA103 103 0 1PF

CLA203 203 0 1PF

CLA104 104 0 1PF

CLA204 204 0 1PF

CLA105 105 0 1PF

CLA205 205 0 1PF

CLA106 106 0 1PF

CLA206 206 0 1PF

CLA107 107 0 1PF

CLA207 207 0 1PF

CLA108 108 0 1PF

CLA208 208 0 1PF

CLA109 109 0 1PF

CLA209 209 0 1PF

CLA110 110 0 1PF

CLA210 210 0 1PF

MN101 301 101 601 601 N L=2U W=44U

MN201 501 201 601 601 N L=2U W=44U

MN102 302 102 602 602 N L=2U W=2U

MN202 502 202 602 602 N L=2U W=2U

MN103 803 103 603 603 N L=2U W=44U

MN203 903 203 603 603 N L=2U W=44U

MN104 304 104 804 604 N L=2U W=44U

MN204 504 204 904 604 N L=2U W=44U

MN105 305 305 0 0 N L=2U W=24U

MN205 505 305 0 0 N L=2U W=24U

MN106 306 106 606 606 N L=2U W=44U

MN206 506 206 606 606 N L=2U W=44U

MN107 307 107 607 607 N L=2U W=2U

MN207 507 207 607 607 N L=2U W=2U

MN108 808 108 608 608 N L=2U W=44U
 MN208 908 208 608 608 N L=2U W=44U
 MN109 309 109 809 609 N L=2U W=44U
 MN209 509 209 909 609 N L=2U W=44U
 MN110 310 310 0 0 N L=2U W=24U
 MN210 510 310 0 0 N L=2U W=24U
 MNA03 303 4 803 603 N L=2U W=2U
 MNB03 503 4 903 603 N L=2U W=2U
 MNA04 804 4 604 604 N L=2U W=8U
 MNB04 904 4 604 604 N L=2U W=8U
 MNA08 308 4 808 608 N L=2U W=2U
 MNB08 508 4 908 608 N L=2U W=2U
 MNA09 809 4 609 609 N L=2U W=8U
 MNB09 909 4 609 609 N L=2U W=8U
 MP101 301 301 4 4 P L=2U W=2U
 MP201 501 301 4 4 P L=2U W=2U
 MP102 302 302 4 4 P L=2U W=2U
 MP202 502 302 4 4 P L=2U W=2U
 MPA02 302 102 4 4 P L=2U W=2U
 MPB02 502 202 4 4 P L=2U W=2U
 MP103 303 303 4 4 P L=2U W=2U
 MP203 503 303 4 4 P L=2U W=2U
 MP104 304 304 4 4 P L=2U W=2U
 MP204 504 304 4 4 P L=2U W=2U
 MP105 305 105 605 605 P L=2U W=48U
 MP205 505 205 605 605 P L=2U W=48U
 MP106 306 306 4 4 P L=2U W=2U
 MP206 506 306 4 4 P L=2U W=2U
 MP107 307 307 4 4 P L=2U W=2U
 MP207 507 307 4 4 P L=2U W=2U
 MPA07 307 107 4 4 P L=2U W=2U
 MPB07 507 207 4 4 P L=2U W=2U
 MP108 308 308 4 4 P L=2U W=2U
 MP208 508 308 4 4 P L=2U W=2U
 MP109 309 309 4 4 P L=2U W=2U
 MP209 509 309 4 4 P L=2U W=2U
 MP110 310 110 610 610 P L=2U W=48U
 MP210 510 210 610 610 P L=2U W=48U
 MPD1 601 7 0 0 N L=2U W=8U
 MPD2 602 7 0 0 N L=2U W=2U
 MPD3 603 7 0 0 N L=2U W=8U
 MPD4 604 7 0 0 N L=2U W=8U
 MPD5 605 0 4 4 P L=2U W=8U
 MPD6 606 7 0 0 N L=2U W=8U
 MPD7 607 7 0 0 N L=2U W=2U
 MPD8 608 7 0 0 N L=2U W=8U
 MPD9 609 7 0 0 N L=2U W=8U
 MPD10 610 0 4 4 P L=2U W=8U
 .MODEL N NMOS LEVEL=3 RSH=0 TOX=225E-10 LD=0.15E-6
 + XJ=0.21E-6 CJ=1.0E-4 CJSW=1.25E-10 UO=650 VTO=0.628
 + CGSO=2.3E-10 CGDO=2.3E-10 NSUB=3E15
 + THETA=0.06 KAPPA=0.4 ETA=0.14 VMAX=17E4
 + PB=0.7 MJ=0.5 MJSW=0.3 NFS=1E10
 .MODEL P PMOS LEVEL=3 RSH=0 TOX=225E-10 LD=0.4E-6

```
+ XJ=0.6E-6 CJ=6E-4 CJSW=3.75E-10 UO=220 VTO=-0.668
+ CGSO=6.2E-10 CGDO=6.2E-10 TPG=-1 NSUB=5E15
+ THETA=0.03 KAPPA=0.4 ETA=0.06 VMAX=17E4
+ PB=0.7 MJ=0.5 MJSW=0.3 NFS=1E10
.IC V(101)=0.8V V(201)=0.6V V(501)=2.7V
.IC V(102)=2.7V V(202)=2.5V V(502)=2.3V
.IC V(103)=0.8V V(203)=0.6V V(503)=3.1V
.IC V(104)=0.8V V(204)=0.6V V(504)=2.0V
.IC V(105)=4.3V V(205)=4.1V V(505)=4.9V
.IC V(106)=0.6V V(206)=0.8V V(506)=2.7V
.IC V(107)=2.5V V(207)=2.7V V(507)=2.5V
.IC V(108)=0.6 V(208))=0.8V V(508)=3.1V
.IC V(109)=0.6 V(209)=0.8 V(509)=2.0V
.IC V(110)=4.1 V(210)=4.3 V(510)=4.9V
.WIDTH OUT=80
.TRAN 2NS 100NS
.PRINT TRAN V(501) V(502) V(503) V(504) V(505)
.PRINT TRAN V(506) V(507) V(508) V(509) V(510)
.PRINT TRAN V(501,506) V(502,507) V(503,508) V(504,509)
+ V(505,510)
.PLOT TRAN V(501) V(502) V(503) V(504) V(505) (0 5)
.PLOT TRAN V(506) V(507) V(508) V(509) V(510) (0 5)
.PLOT TRAN V(501,506) V(502,507) V(503,508) V(504,509)
+ V(505,510) (0,5)
.END
```